



*Climate
Analytics
Lab*



SCRIPPS INSTITUTION OF
OCEANOGRAPHY

UC San Diego™

HALICIOĞLU DATA SCIENCE INSTITUTE

Machine Learning for Climate

Duncan Watson-Parris, SIO/HDSI

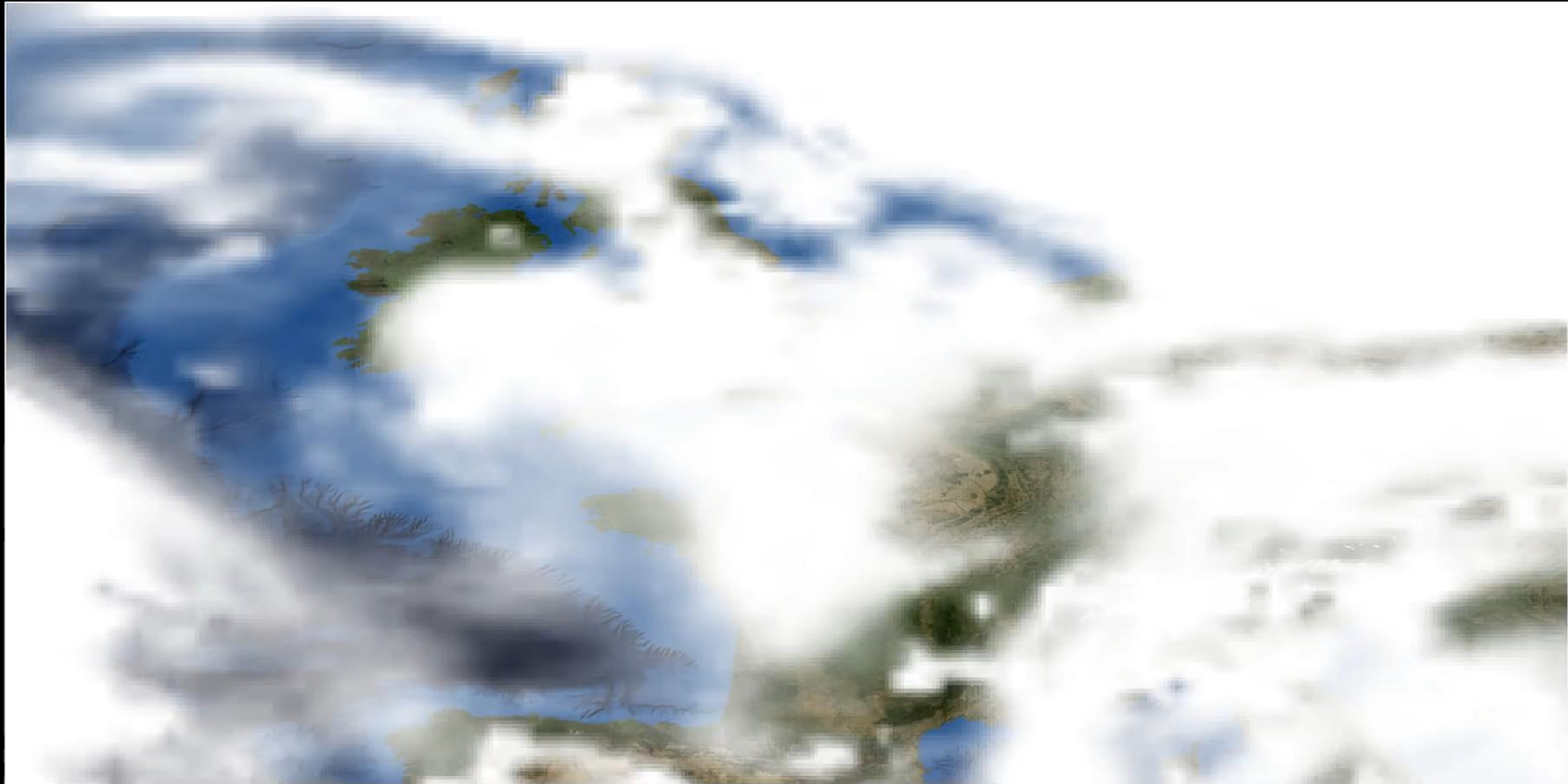
DSC 106: 6th May 2026

Overview

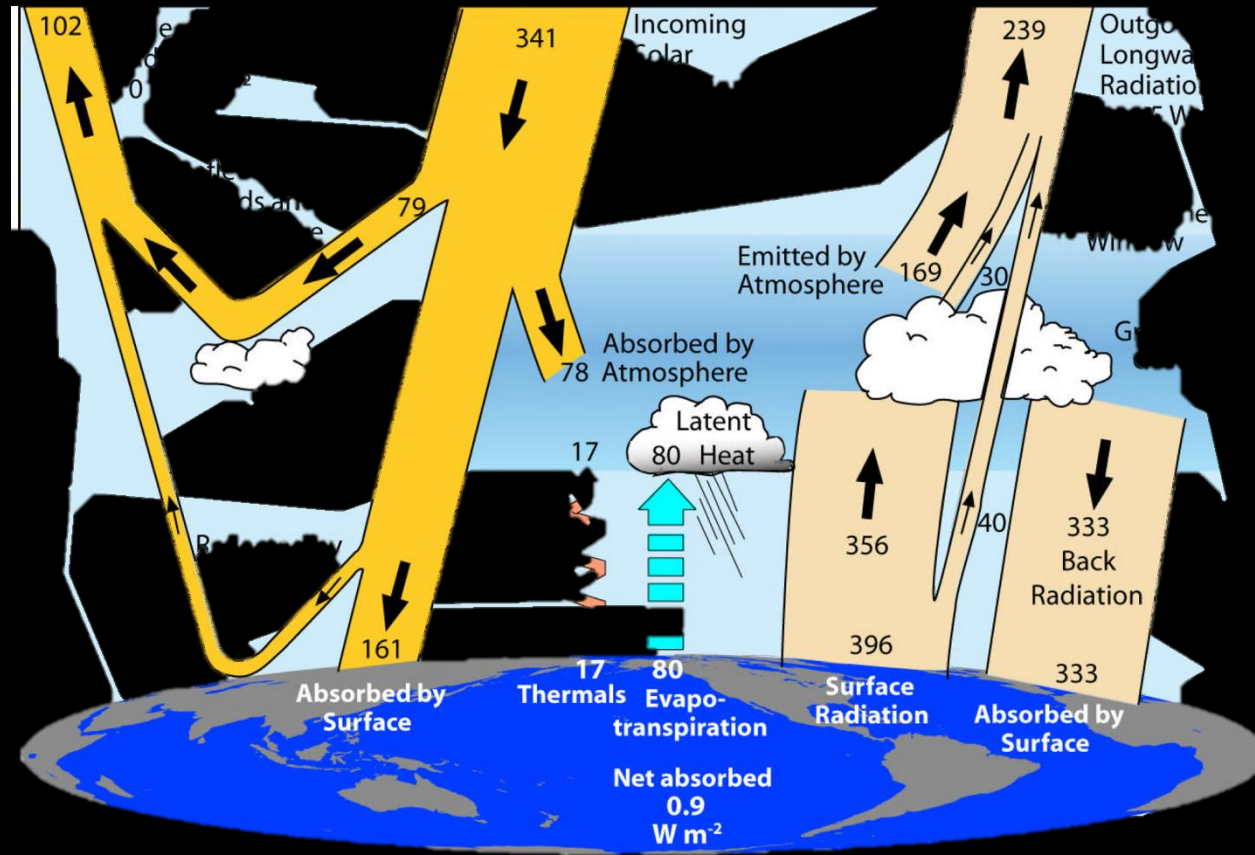
- Introduction to machine learning and aerosol forcing
- Three example approaches:
 1. **Emulating** climate models for improved calibration
 2. Deep-learning for **measuring** aerosol-cloud perturbations
 3. **Exploring** future climates with physical climate emulators
- Summary and my journey here

ML for Weather and Climate are worlds apart

Date: 01-01-1982, averaged over 3 hours



The Global Energy Balance



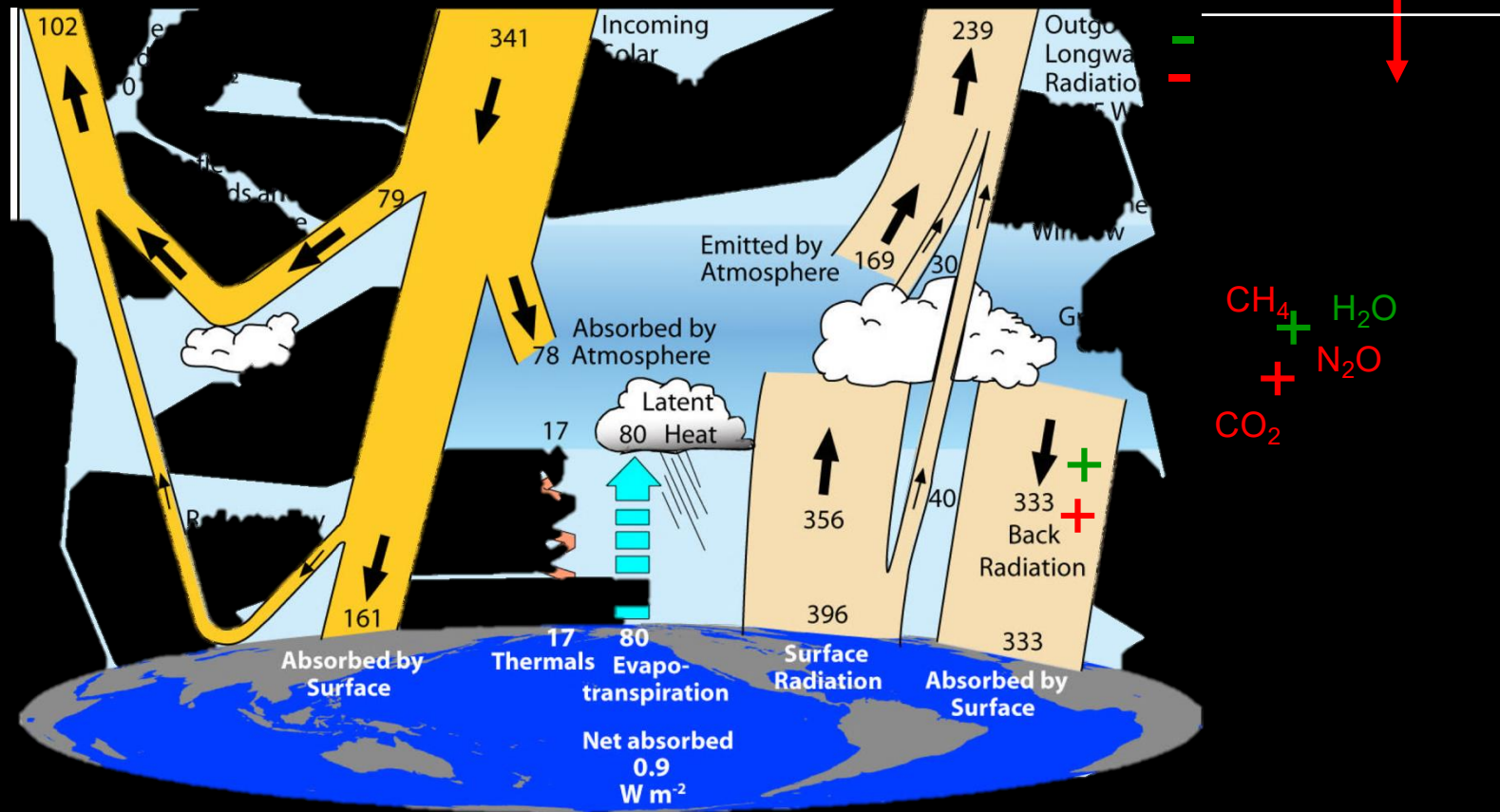
(Trenberth, 2009)

The Global Energy Balance

Natural Greenhouse Effect

Anthropogenic Greenhouse Effect

positive "radiative forcing"
⇒ warming

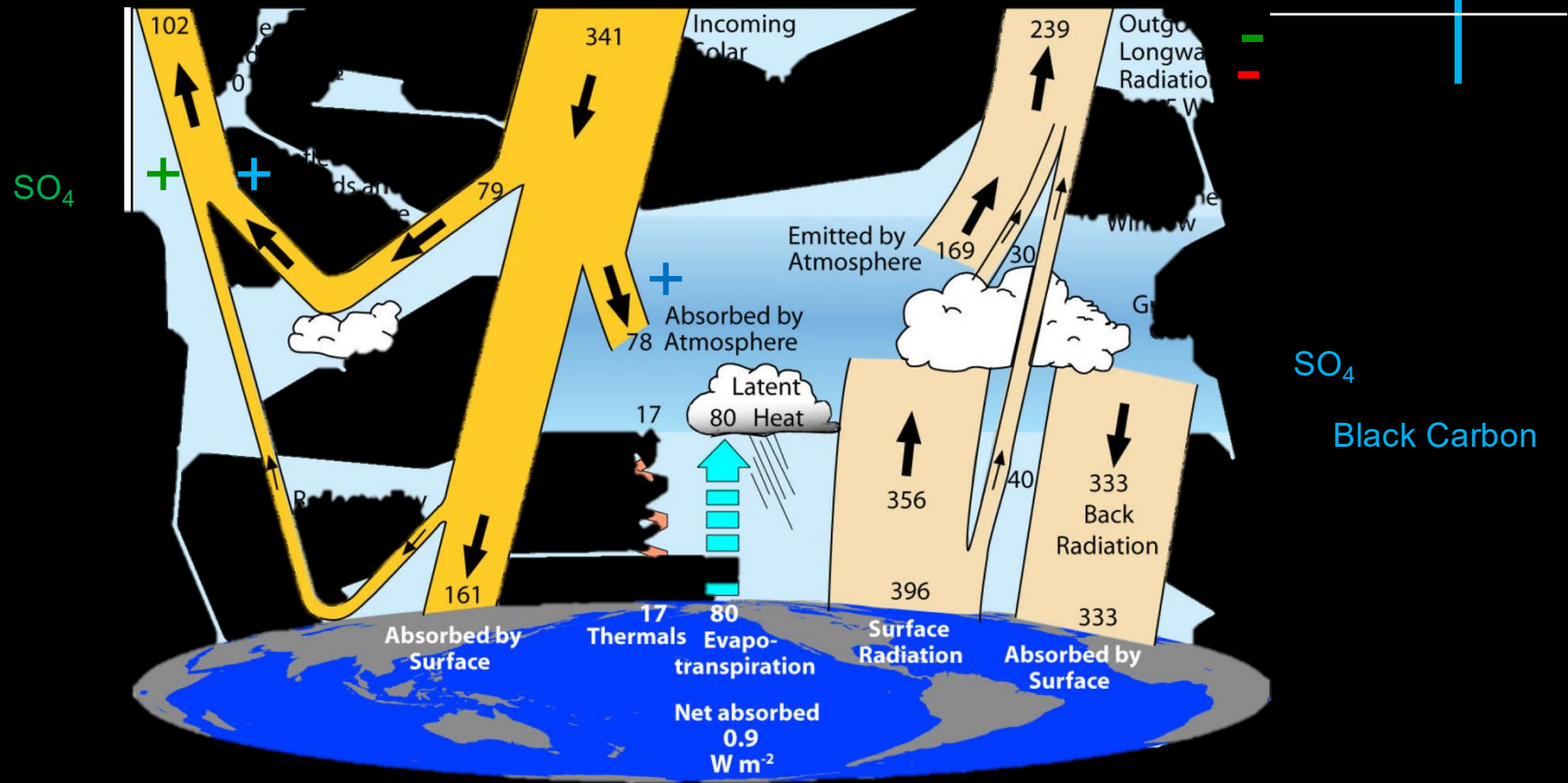


The Global Energy Balance

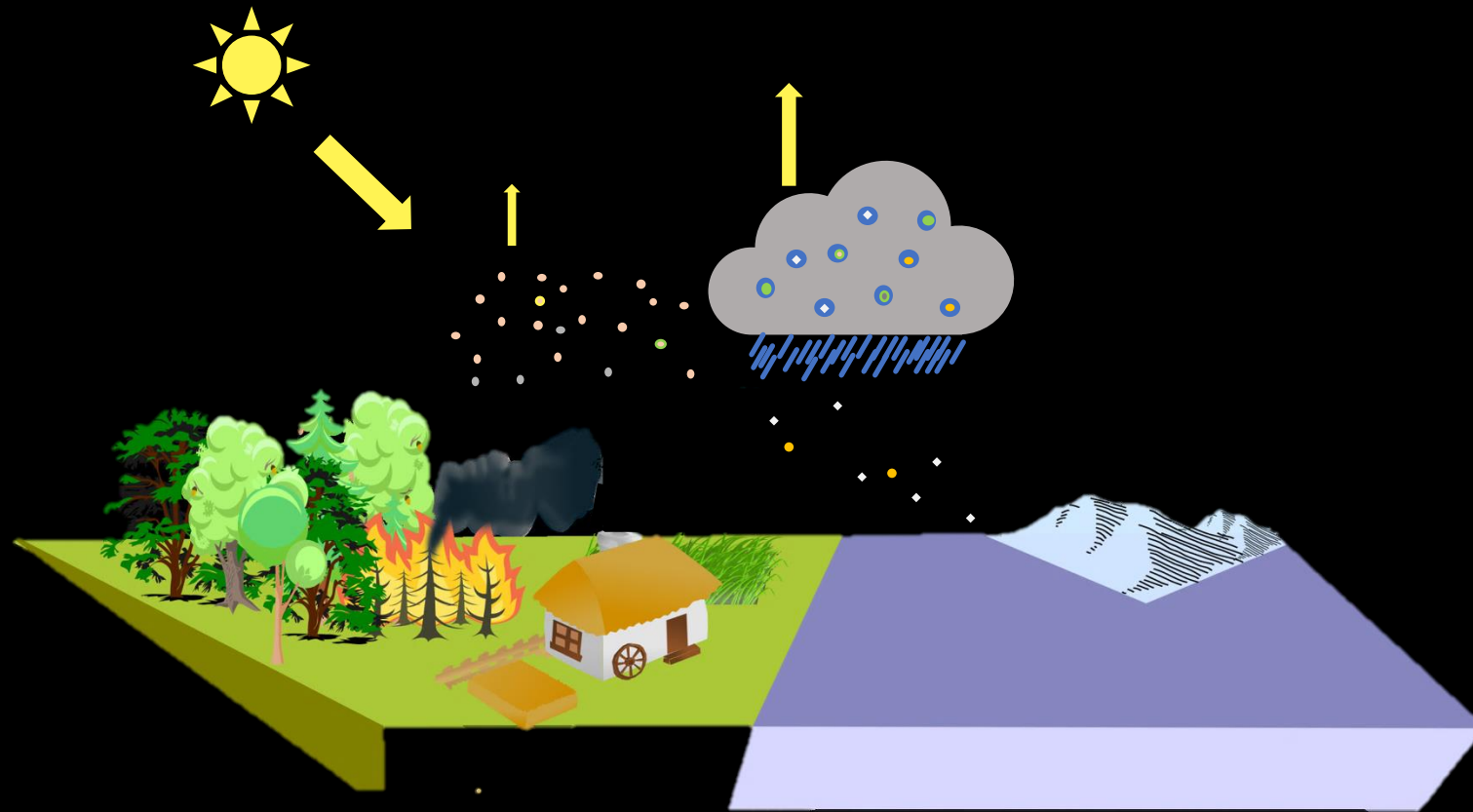
Natural Aerosol Effect

Anthropogenic Aerosol Effect

negative "radiative forcing"
⇒ cooling

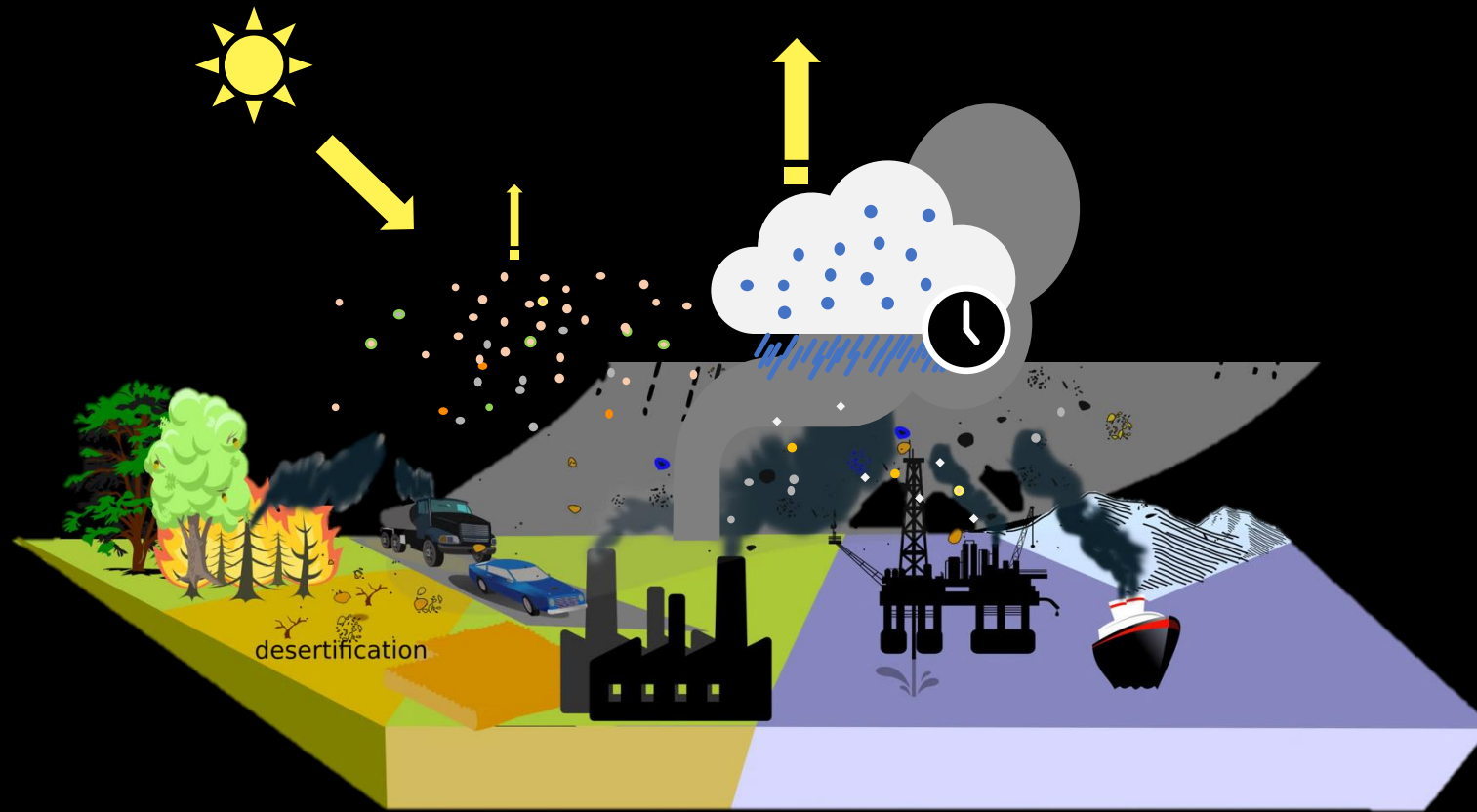


Natural aerosol

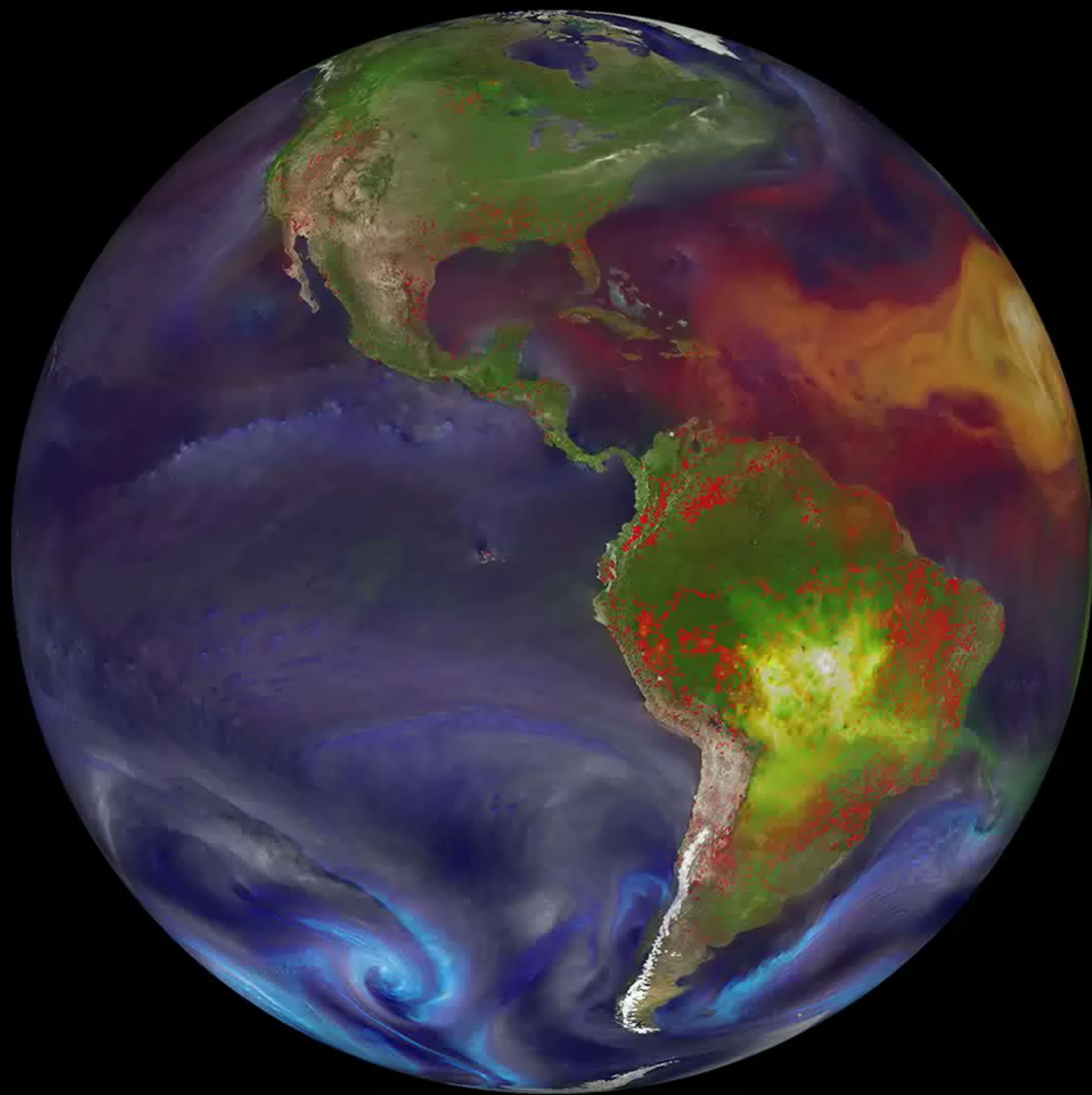


Pre-industrial

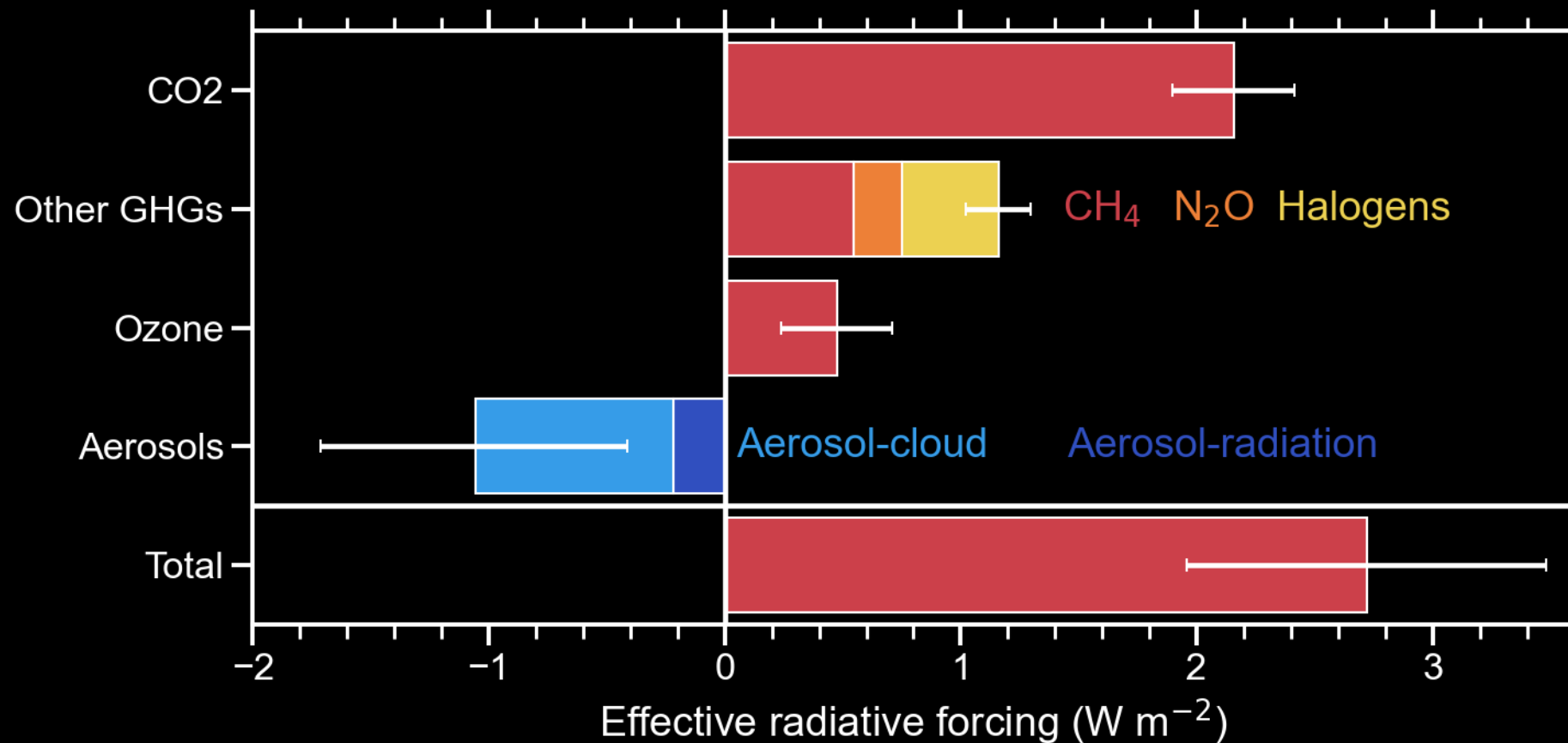
Aerosol Forcing



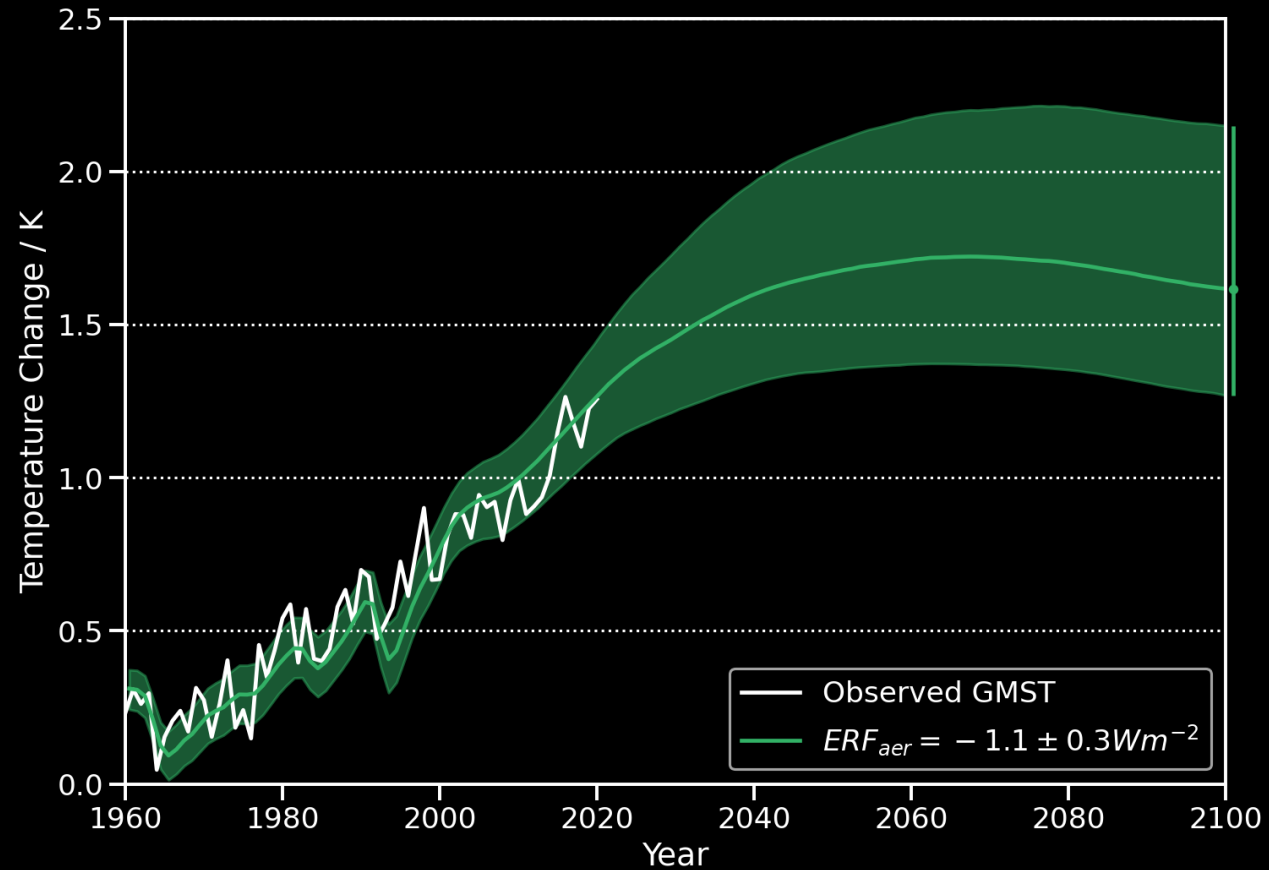
Present day



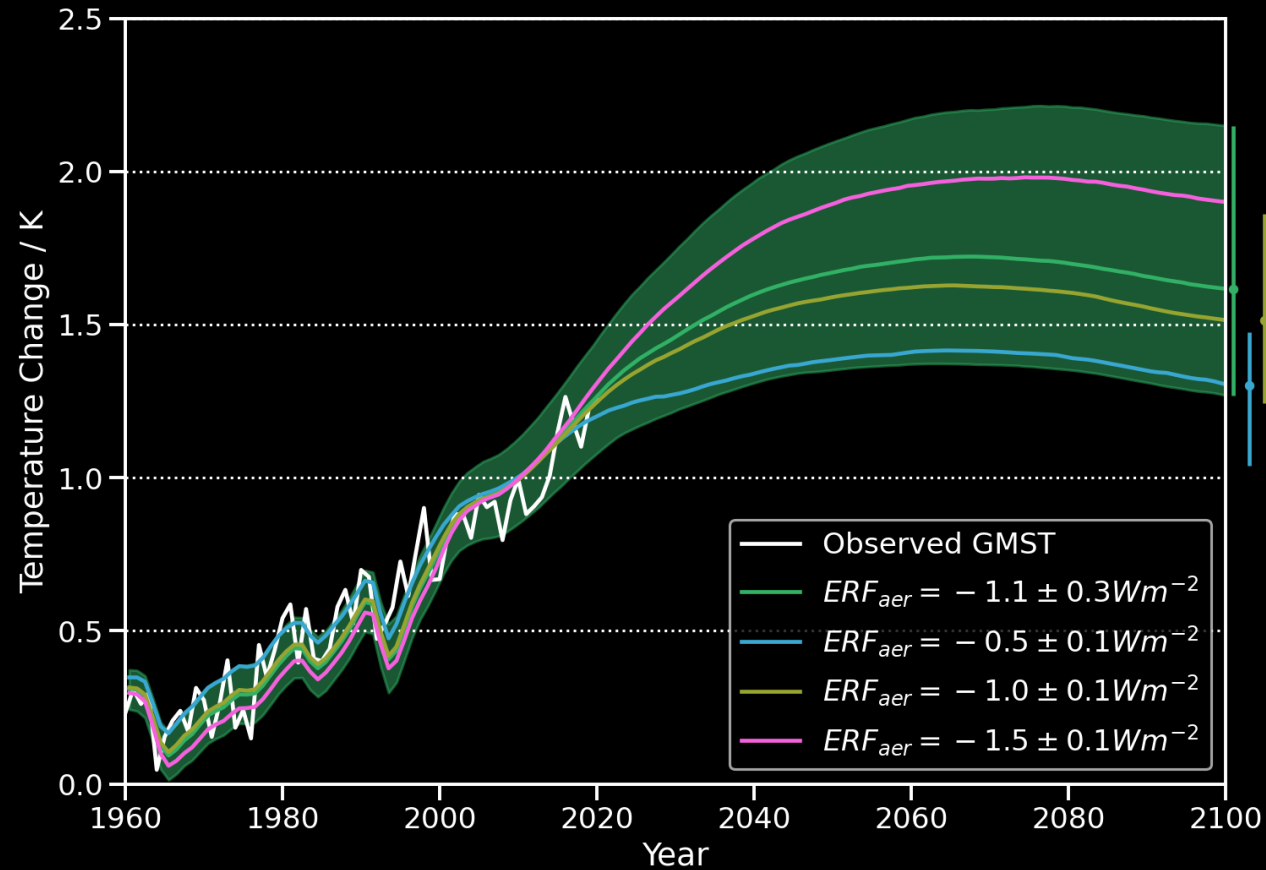
Anthropogenic Forcing Uncertainty



Uncertain Aerosol Forcing - Uncertain Climate Projections



Uncertain Aerosol Forcing - Uncertain Climate Projections



1. Climate model **emulation** for calibration

Climate models

Schematic for Global Atmospheric Model

Horizontal Grid (Latitude-Longitude)

Vertical Grid (Height or Pressure)

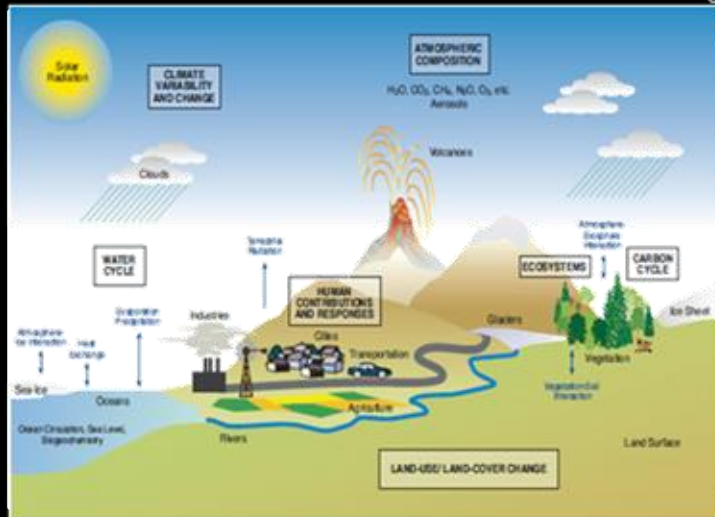
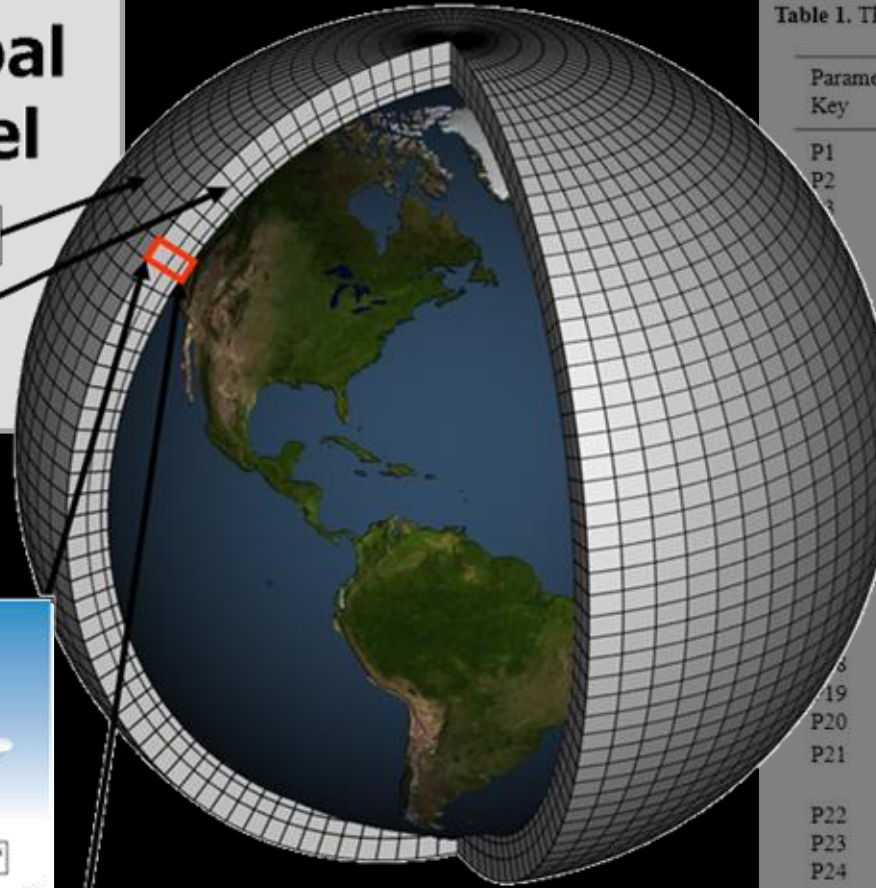


Table 1. The uncertain parameters and emissions factors

Parameter Key	Parameter name	Description of parameter
P1	BL_NUC	Boundary layer nucleation rate
P2	FT_NUC	Free troposphere nucleation rate
P3	AGEING	Ageing "rate" from insoluble to soluble
	ACT_DIAM	Cloud drop activation dry diameter
	SO2O3_CLEAN	pH of cloud drops (controls SO ₂ + O ₃)
	SO2O3_POLL	pH of cloud drops (SO ₂ + O ₃)
	NUC_SCAV_DIAM	Nucleation scavenging diameter
	NUC_SCAV_ICE	Nucleation scavenging fraction in mixed and ice clouds ($T < 0$)
	DRYDEP_AER_AIT	Dry deposition velocity of Aitken mode
	DRYDEP_AER_ACC	Dry deposition velocity of accumulation mode
	ACC_WIDTH	Modal width (accumulation mode)
	AIT_WIDTH	Modal width (Aitken mode)
	NUCAIT_WIDTH	Mode separation diameter (nucleation mode)
	AITACC_WIDTH	Mode separation diameter (Aitken mode)
	FF_EMS	BC/OC mass emission rate (fine mode)
	BB_EMS	BC/OC mass emission rate (broad mode)
	BF_EMS	BC/OC mass emission rate (broad mode)
	FF_DIAM	BC/OC emitted mode diameter (fine mode)
	BB_DIAM	BC/OC emitted mode diameter (broad mode)
	BF_DIAM	BC/OC emitted mode diameter (broad mode)
P18		
P19		
P20	BF_DIAM	BC/OC emitted mode diameter
P21	PRIM.SO4_FRAC	Mass fraction of SO ₂ converted to sulfate in sub-grid power plant plumes
P22	PRIM.SO4_DIAM	Mode diameter of new sub-grid sulfate
P23	SS_ACC	Sea spray mass flux (coarse mode)
P24	ANTH.SO2	SO ₂ emission flux (anthropogenic)
P25	VOLC.SO2	SO ₂ emission flux (volcanic)
P26	DMS_FLUX	DMS emission flux
P27	BIO.SOA	Biogenic monoterpene production
P28	ANTH.SOA	Anthropogenic VOC production

Exploring parametric uncertainty

- A climate model is a function \mathcal{F} of input forcings X and parameters θ and generates outputs Y : $\mathcal{F}(X, \theta) = Y$.
- Given a set of observations of Y , denoted Y^0 , we would like to calculate the inverse: $\mathcal{F}^{-1}(Y^0) = \theta$.
- Or, more precisely, we would like to know the posterior probability distribution of the input parameters:

$$p(\theta|Y^0) = \frac{p(Y^0|\theta)p(\theta)}{p(Y^0)}$$

Likelihood-free inference

- We cannot compute the full likelihood but can approximate it using Approximate Bayesian computation (ABC; or rejection sampling):
 1. Draw θ from $p(\theta)$
 2. Calculate $\mathcal{F}(\theta)$ to determine Y
 3. Accept θ if $\rho(Y^0, Y) \leq \epsilon$
- As $\epsilon \rightarrow \infty$, we get observations from the prior, $p(\theta)$
- As $\epsilon \rightarrow 0$, we generate observations from $p(\theta|Y^0)$
- In practice we need many, many samples and so a surrogate model, or emulator, is used: $\mathcal{E}(\theta) \sim \mathcal{F}(\theta)$

Implausibility

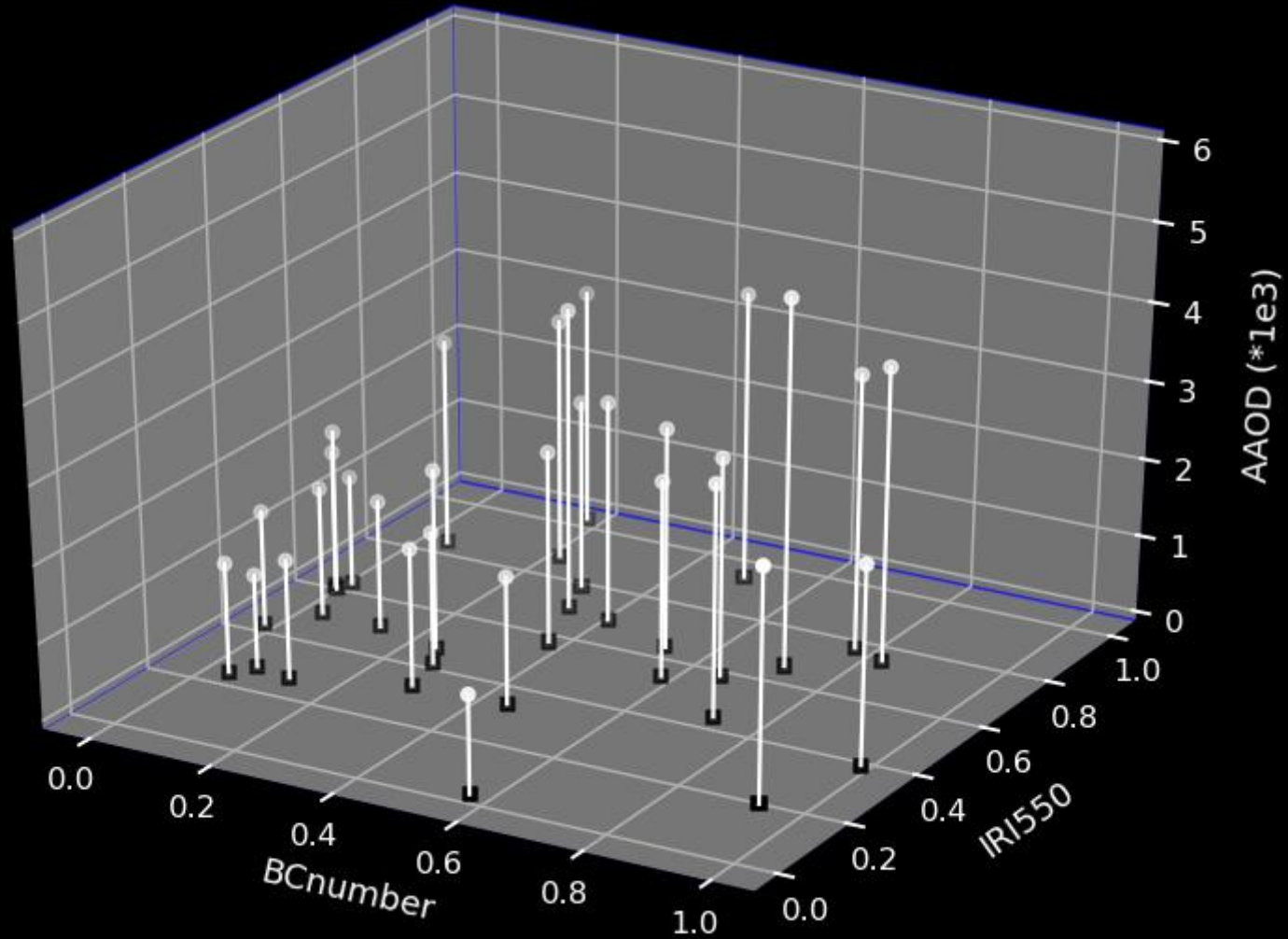
- In practice, we need to define the distance, $\rho(Y^0, Y)$
- We use the concept of an implausibility metric:

$$I(\theta) = \frac{|Y^0 - E[\eta(\theta)]|}{\sqrt{[Var(\phi(\theta)) + Var(\epsilon) + Var(\delta)]}}$$

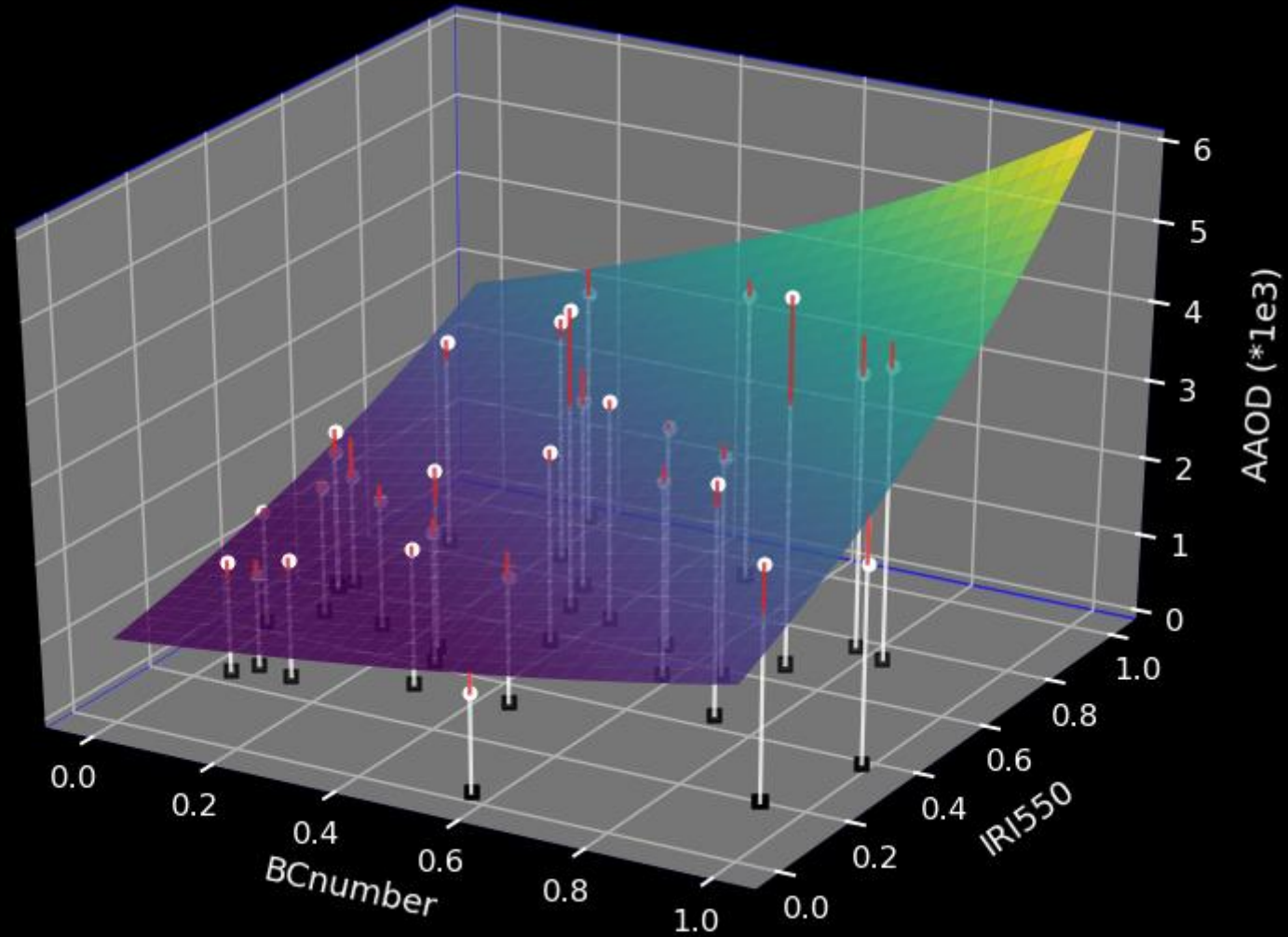
Observation
Model output
[Prediction from emulator]
Emulator prediction uncertainty
Observational uncertainty
Structural uncertainty

- Assuming this distribution is unimodal, we can then use the 3σ to rule out parameter combinations at 95% confidence

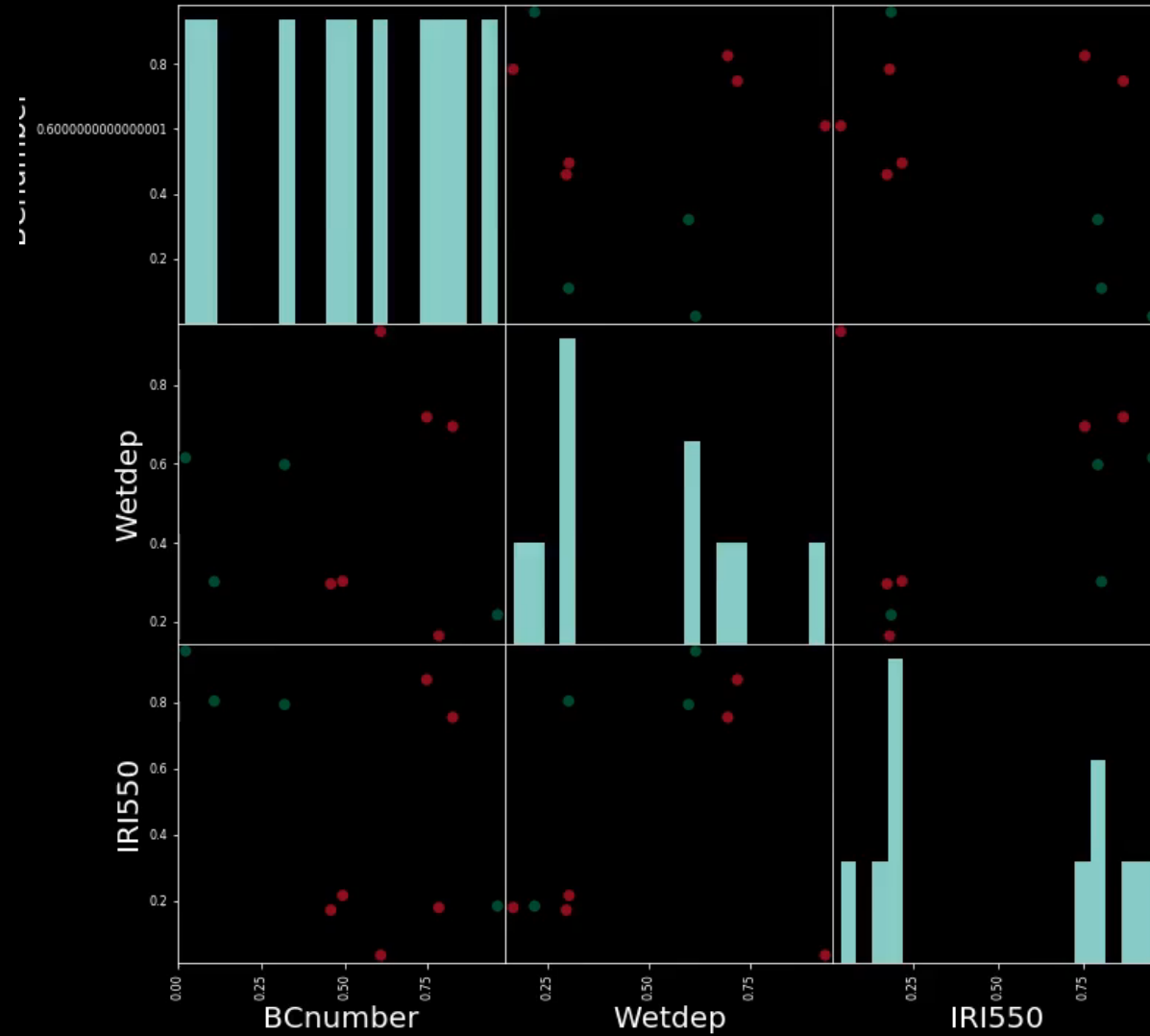
Emulation



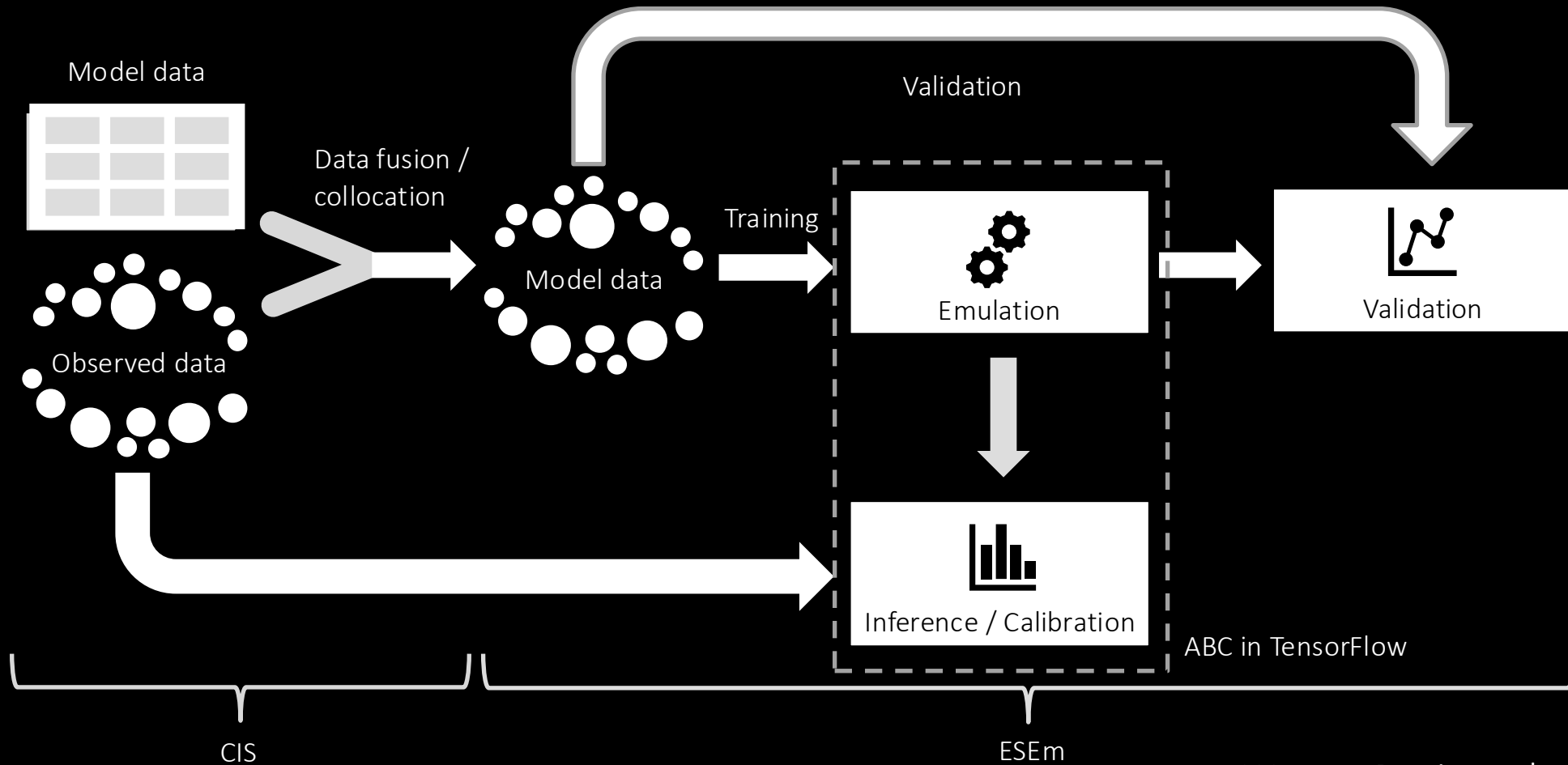
Emulation



Sampling



Earth System Emulator (ESEm)

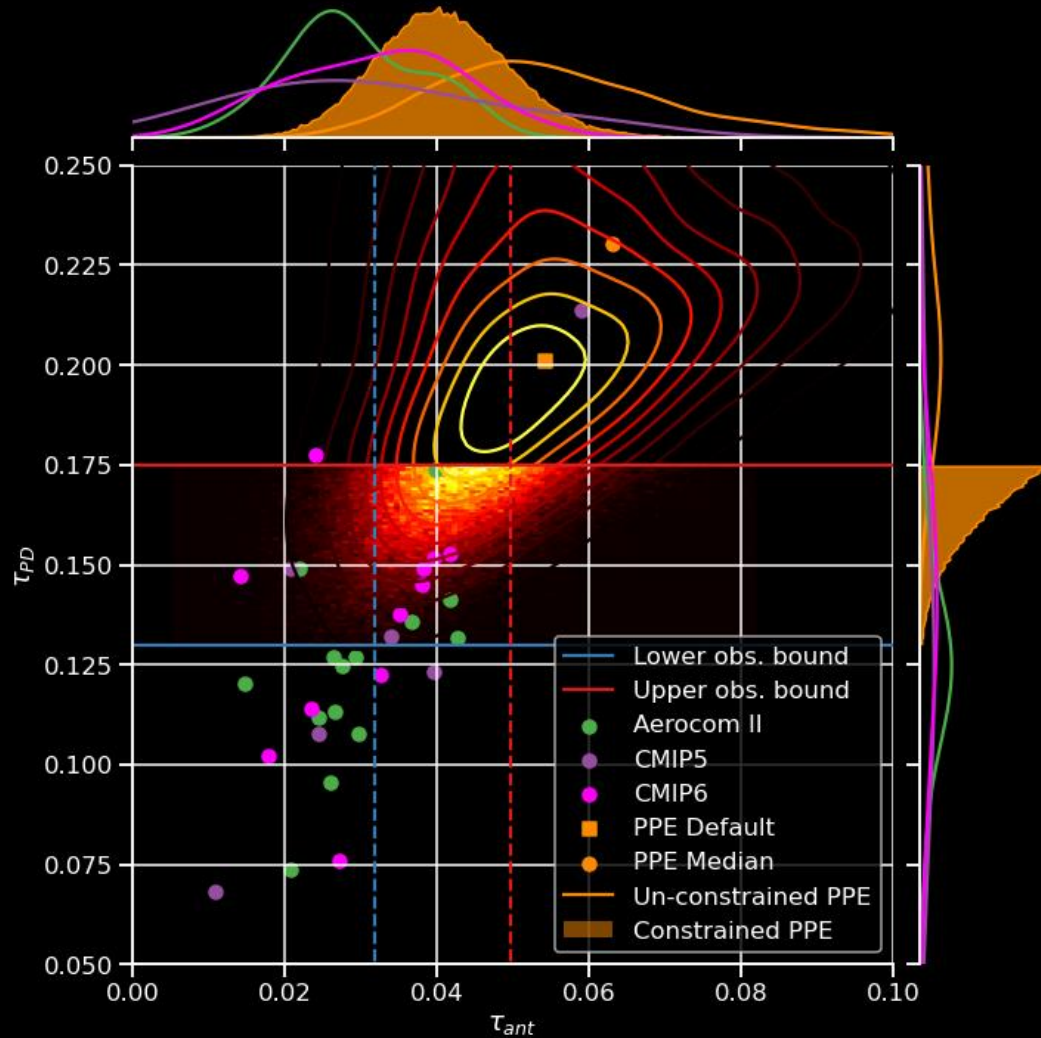


Parametric uncertainty

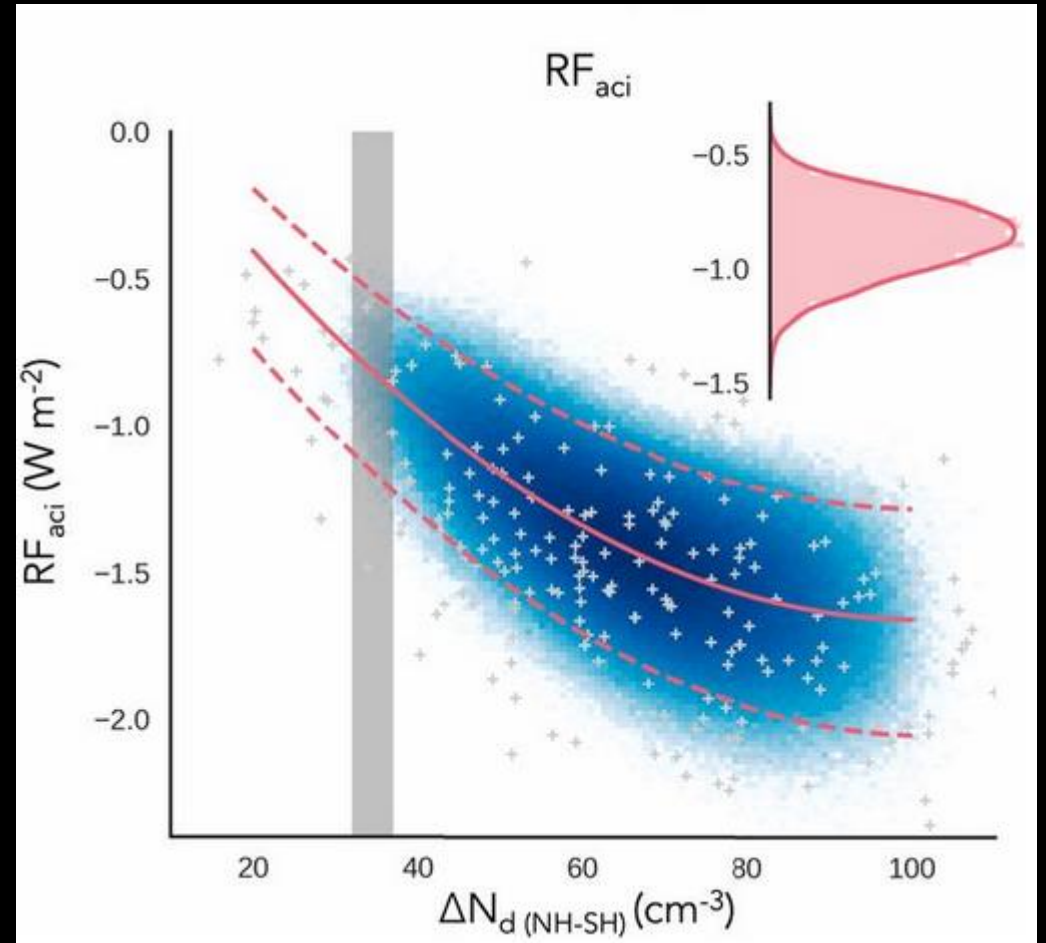
Table 1. The uncertain parameters and emissions factors

Parameter Key	Parameter name	Description of parameter	Uncertainty range	Effect
P1	BL_NUC	Boundary layer nucleation rate coeff (A)	$3.2e^{-7}$ – $2e^{-4} s^{-1}$	Absolute
P2	FT_NUC	Free troposphere nucleation rate	0.01–10	Scaled
P3	AGEING	Ageing “rate” from insoluble to soluble	0.3–5 monolayer	Absolute
P4	ACT_DIAM	Cloud drop activation dry diameter	50–100 nm	Absolute
P5	SO2O3_CLEAN	pH of cloud drops (controls SO ₂ + O ₃)	pH 4–6.5	Absolute
P6	SO2O3_POLL	pH of cloud drops (SO ₂ + O ₃)	pH 3.5–5	Absolute
P7	NUC_SCAV_DIAM	Nucleation scavenging diameter offset dry diameter	0–50 nm	Absolute
P8	NUC_SCAV_ICE	Nucleation scavenging fraction (accumulation mode) in mixed and ice clouds ($T < -15$ °C)	0–1	Scaled
P9	DRYDEP_AER_AIT	Dry deposition velocity of Aitken mode aerosol	0.5–2	Scaled
P10	DRYDEP_AER_ACC	Dry deposition velocity of accumulation mode aerosol	0.1–10	Scaled
P11	ACC_WIDTH	Modal width (accumulation soluble/insoluble)	1.2–1.8	Absolute
P12	AIT_WIDTH	Modal width (Aitken soluble/insoluble)	1.2–1.8	Absolute
P13	NUCAIT_WIDTH	Mode separation diameter (nucleation/Aitken)	9–18 nm	Absolute
P14	AITACC_WIDTH	Mode separation diameter (Aitken/accumulation)	$0.9-2 \times \text{ACT_DIAM}$	Scaled
P15	FF_EMS	BC/OC mass emission rate (fossil fuel)	0.5–2	Scaled
P16	BB_EMS	BC/OC mass emission rate (biomass burning)	0.25–4	Scaled
P17	BF_EMS	BC/OC mass emission rate (biofuel)	0.25–4	Scaled
P18	FF_DIAM	BC/OC emitted mode diameter (fossil fuel)	30–80 nm	Absolute
P19	BB_DIAM	BC/OC emitted mode diameter (biomass burning)	50–200 nm	Absolute
P20	BF_DIAM	BC/OC emitted mode diameter (biofuel)	50–200 nm	Absolute
P21	PRIM.SO4.FRAC	Mass fraction of SO ₂ converted to new SO ₄ ²⁻ particles in sub-grid power plant plumes	0–1 %	Absolute
P22	PRIM.SO4.DIAM	Mode diameter of new sub-grid SO ₄ ²⁻ particles	20–100 nm	Absolute
P23	SS_ACC	Sea spray mass flux (coarse/accumulation)	0.2–5	Scaled
P24	ANTH_SO2	SO ₂ emission flux (anthropogenic)	0.6–1.5	Scaled
P25	VOLC_SO2	SO ₂ emission flux (volcanic)	0.5–2	Scaled
P26	DMS_FLUX	DMS emission flux	0.5–2	Scaled
P27	BIO_SOA	Biogenic monoterpene production of SOA	$5-360 \text{ Tg a}^{-1}$	Absolute
P28	ANTH.SOA	Anthropogenic VOC production of SOA	$2-112 \text{ Tg a}^{-1}$	Absolute

Constraining parametric uncertainty



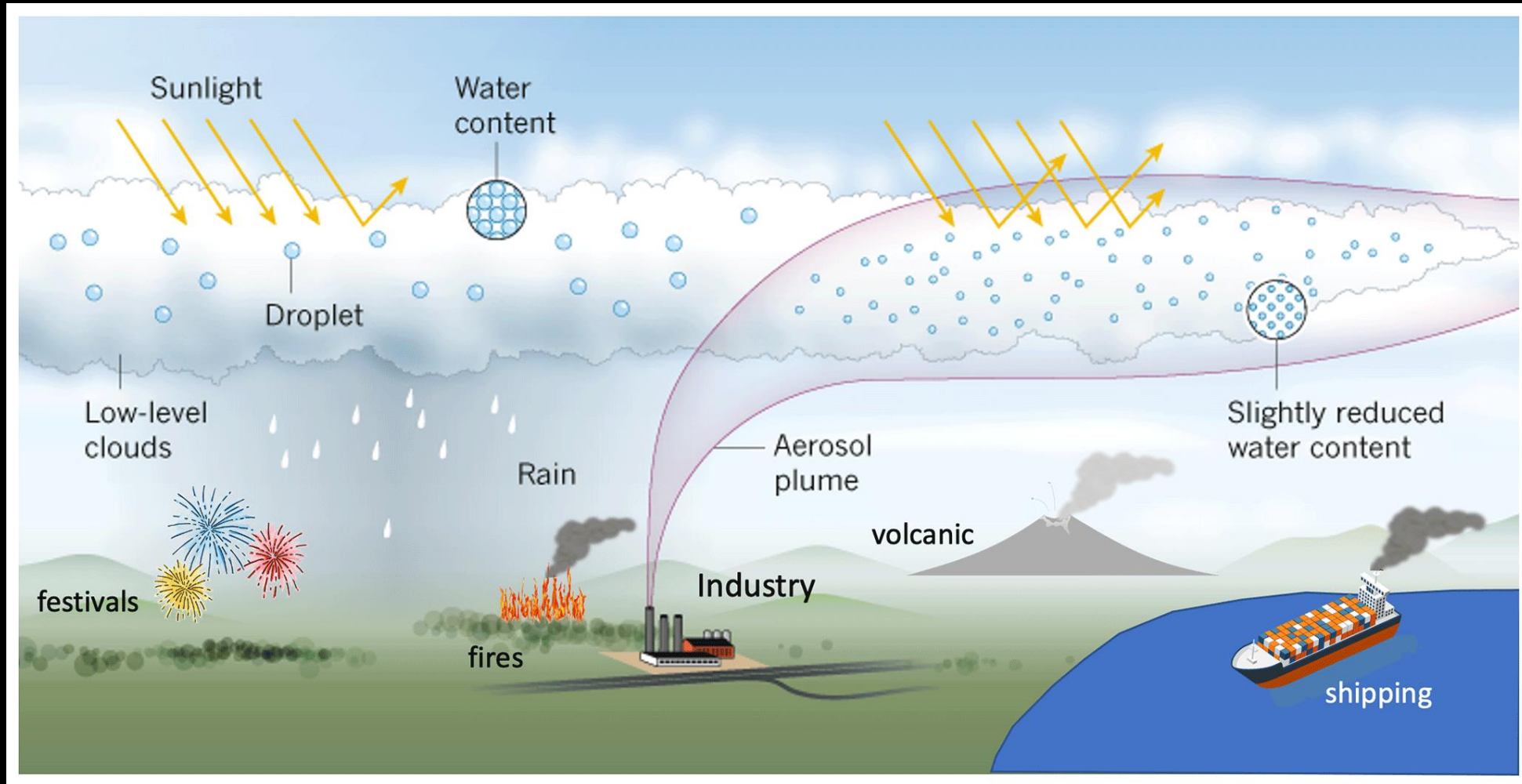
Watson-Parris et al. *GRL* 2020



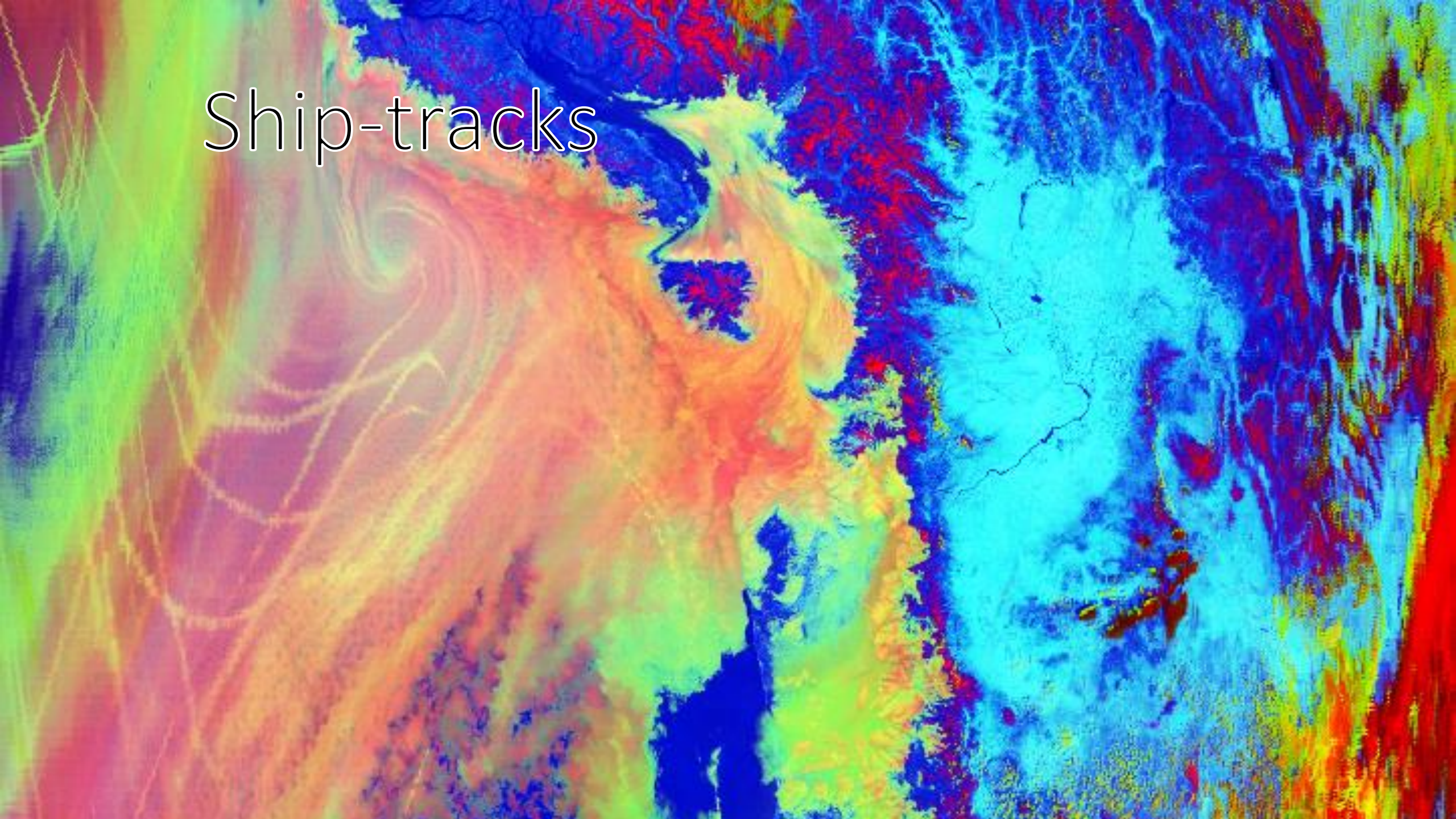
McCoy et al. 2020

2. Measuring aerosol-cloud perturbations

Opportunistic Experiments



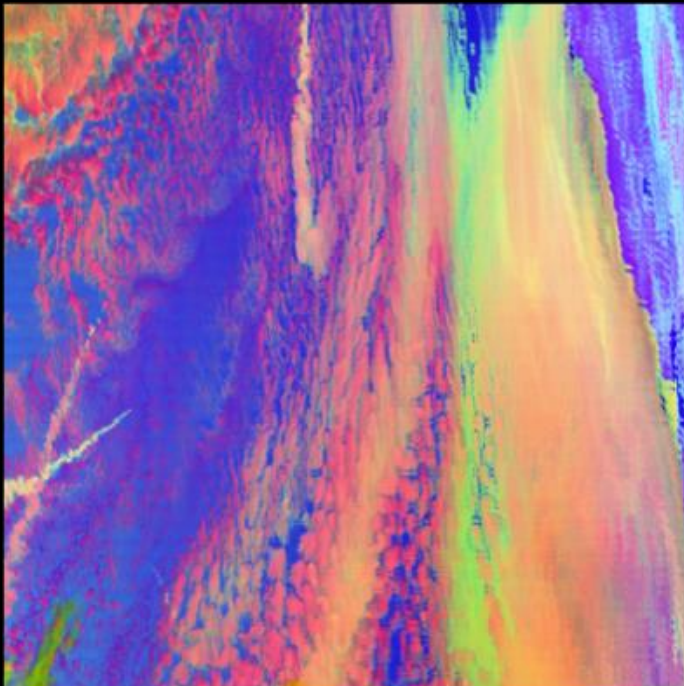
Ship-tracks



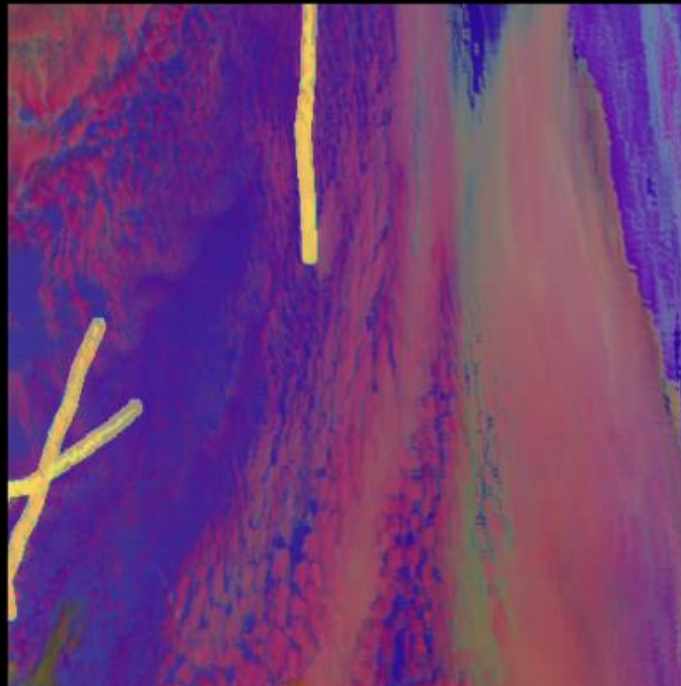
Ship-track detection

We use a 'micro-physics' RGB composite include visible, near-IR and IR channels and target rasterized masks

Composite input



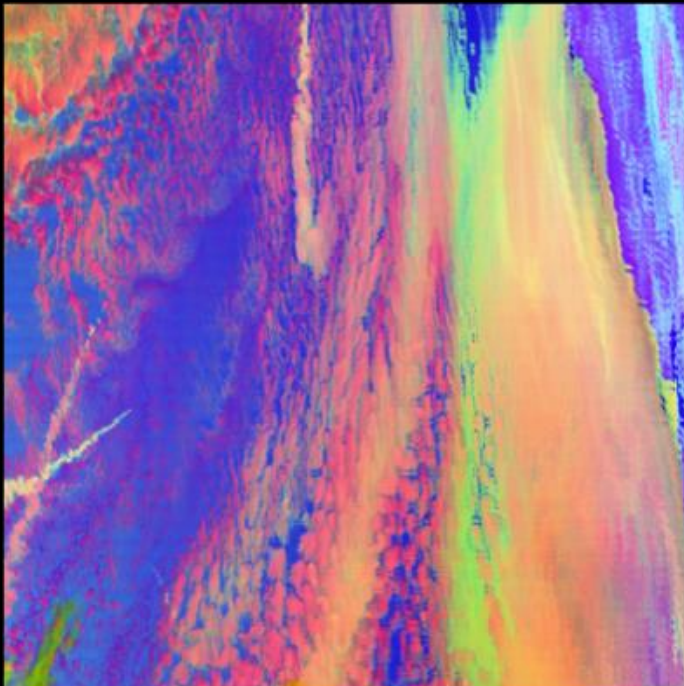
Hand-logged tracks



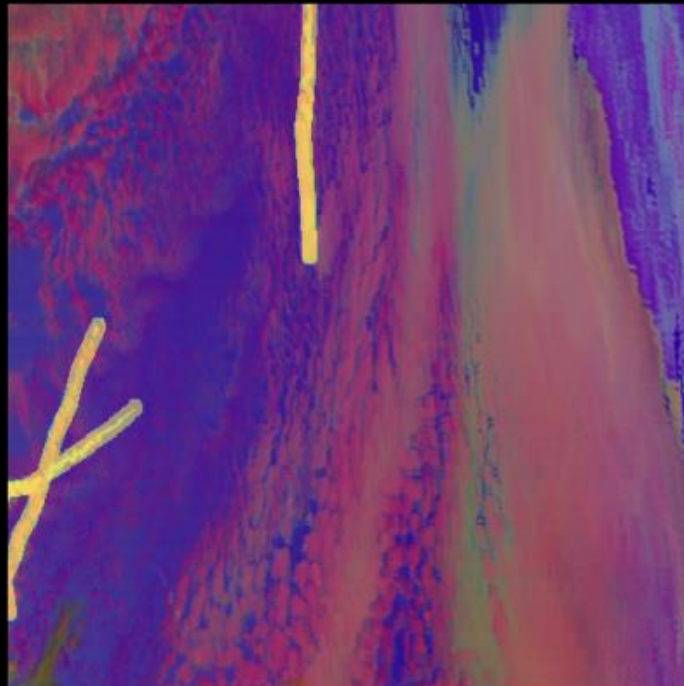
Ship-track detection

We have developed multiple models that perform well against the held-back test data

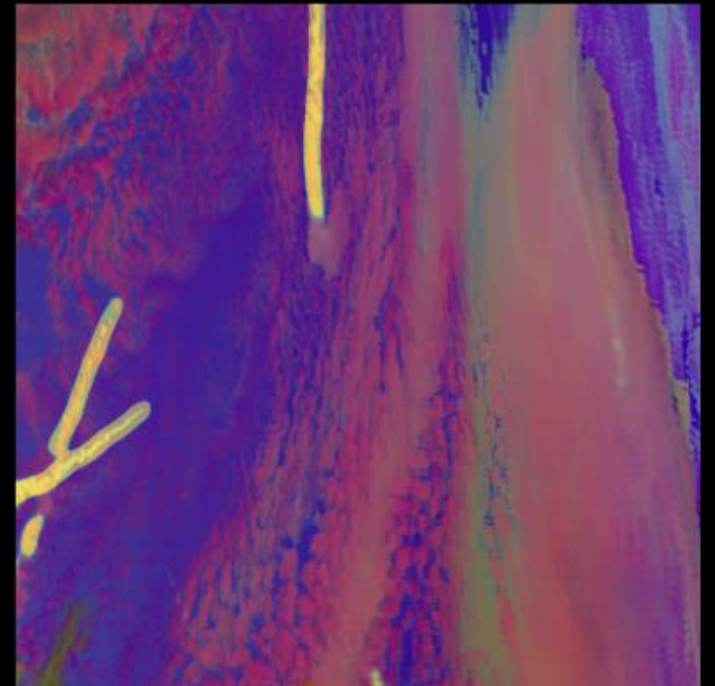
Composite input



Hand-logged tracks



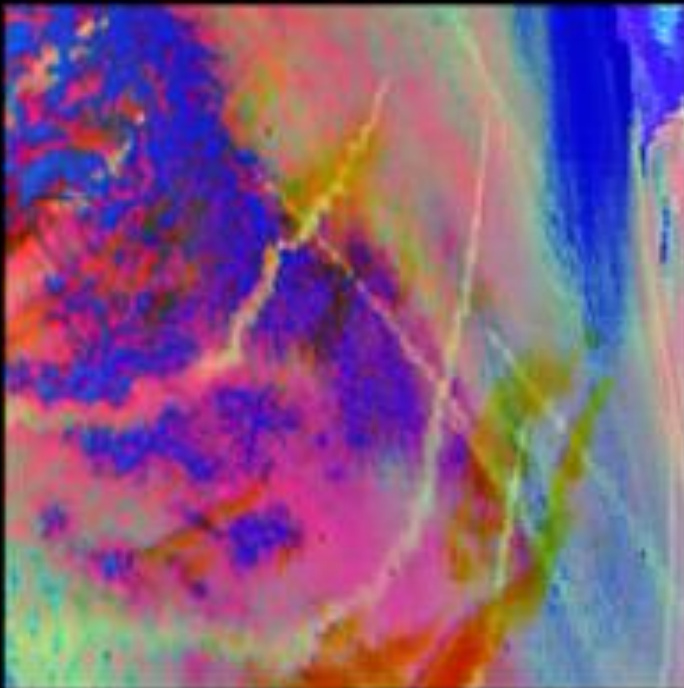
Detected tracks



Ship-track detection

Using Bayesian Optimisation we found the resnet-152 model with the Jacard loss function to be optimal.

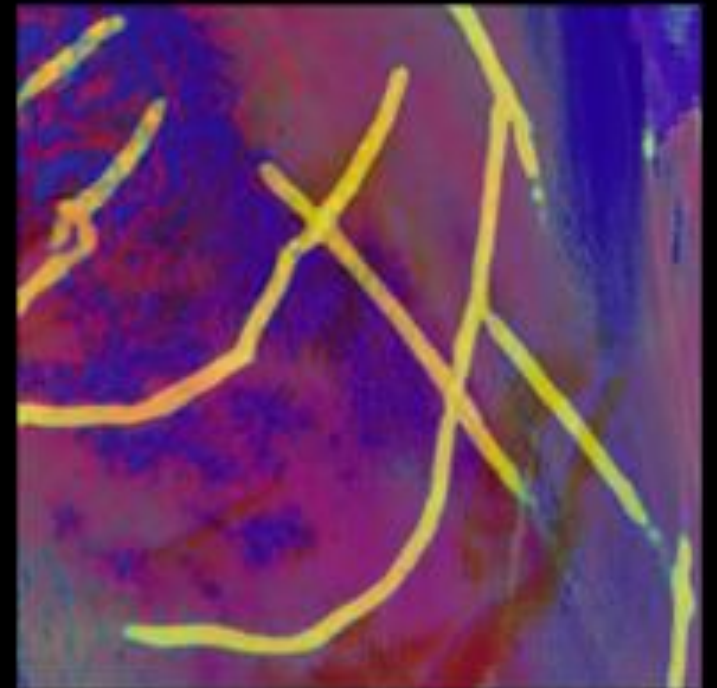
Composite input



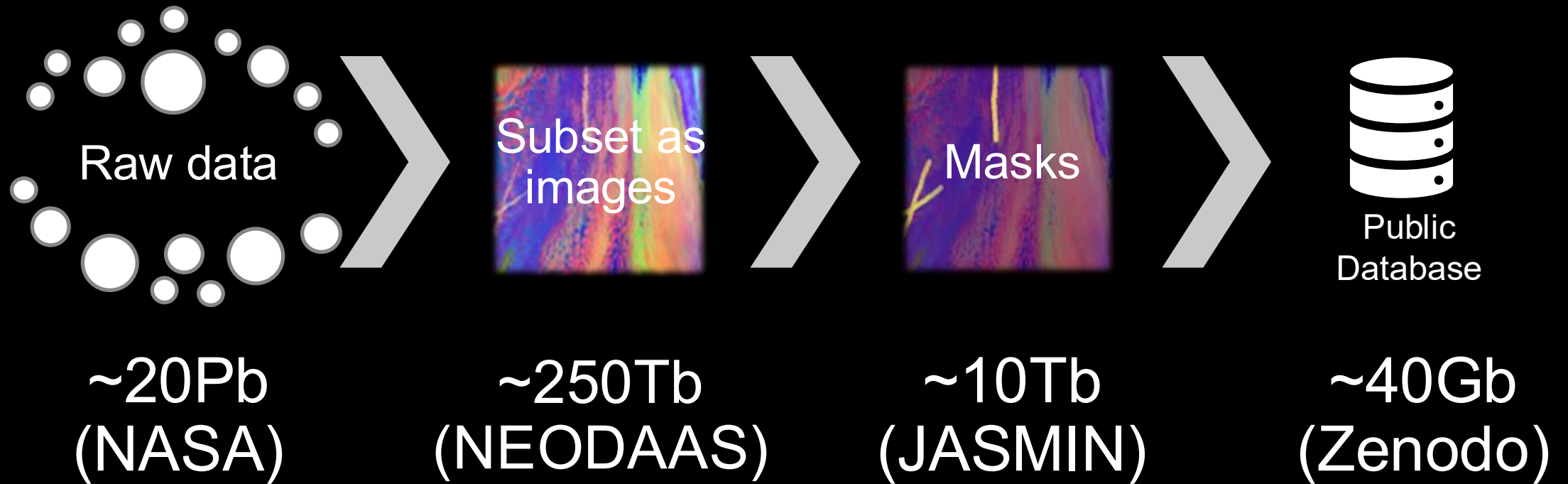
Hand-logged tracks



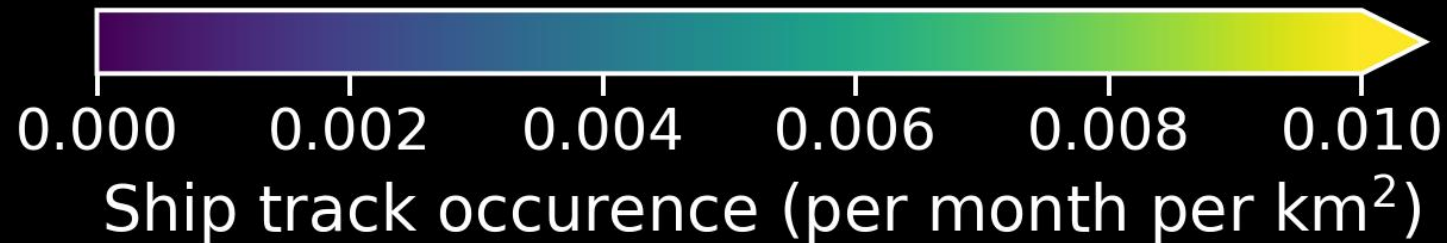
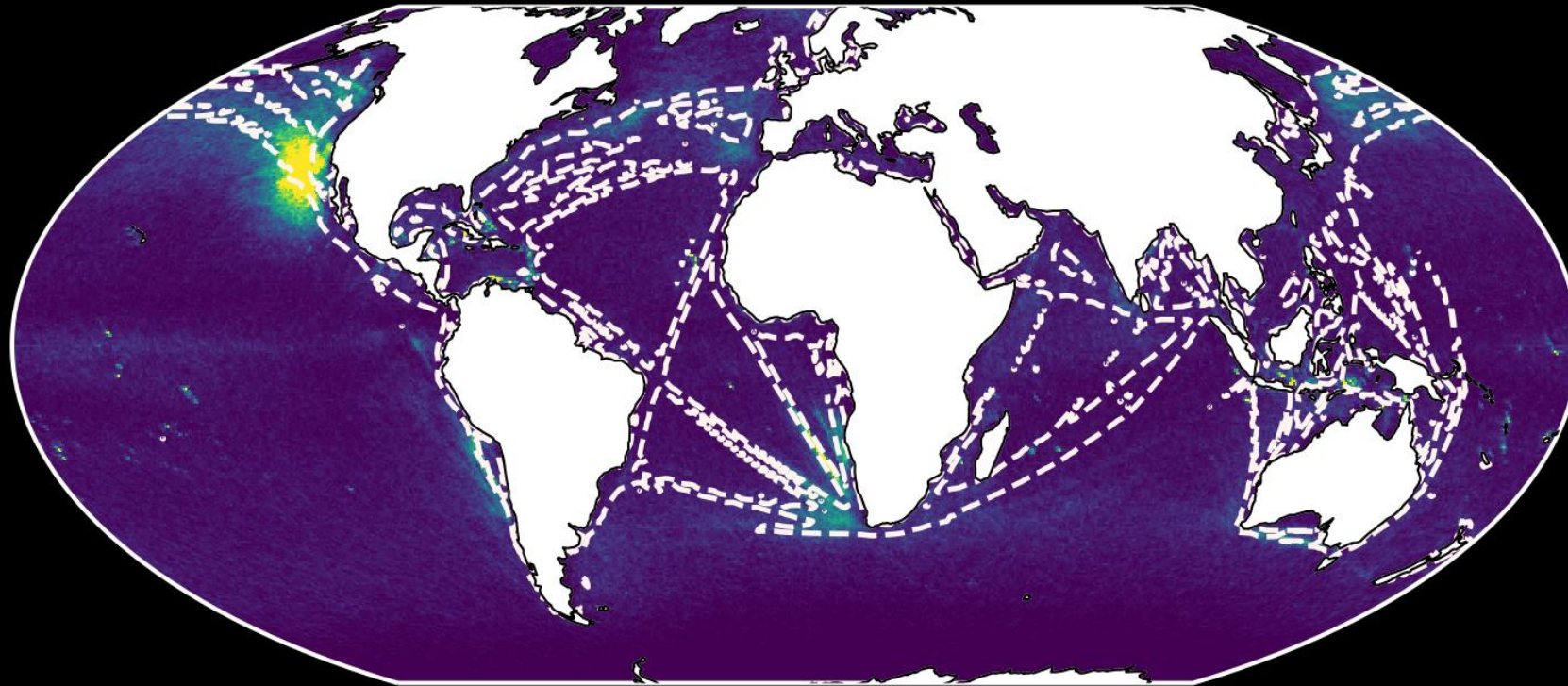
Detected tracks



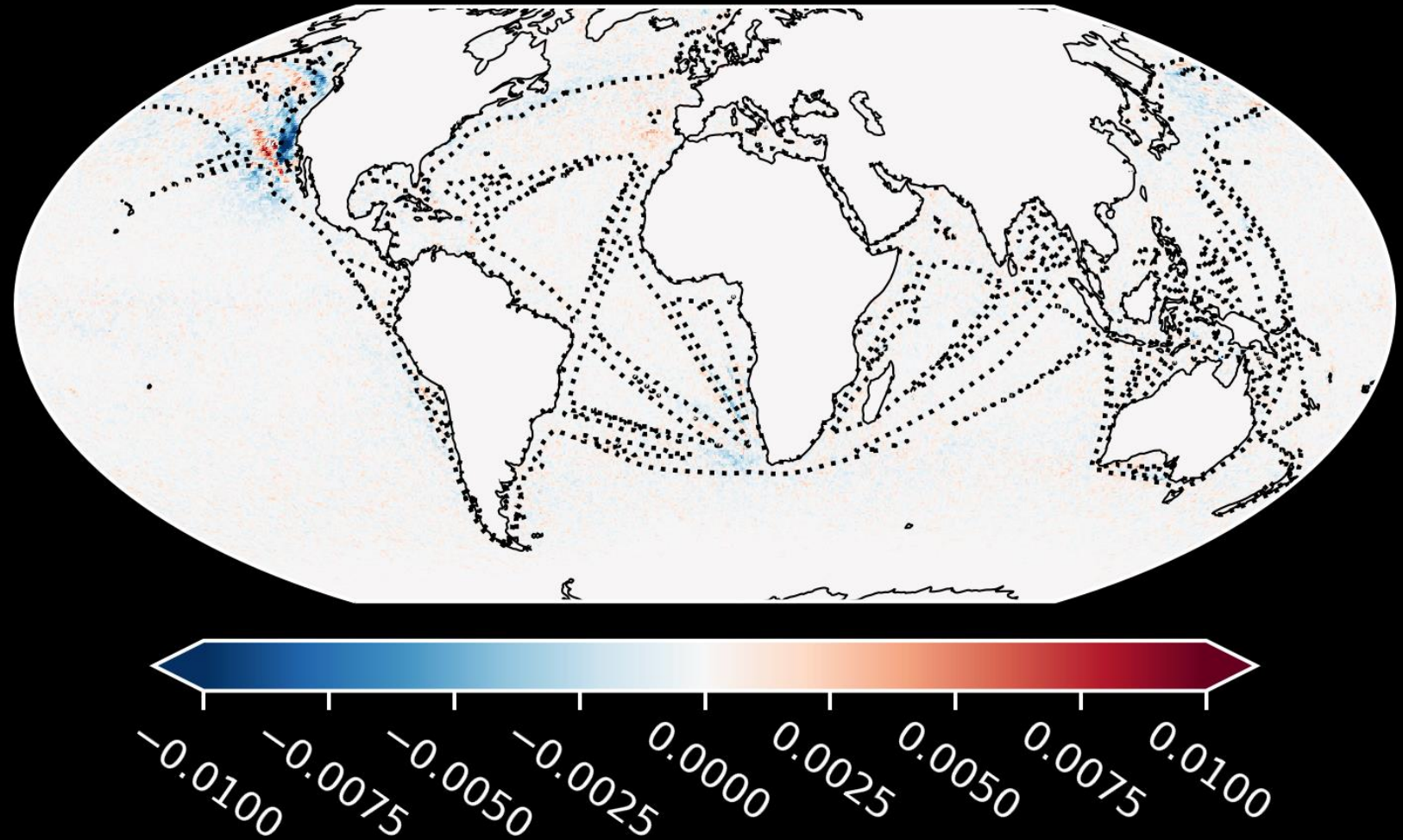
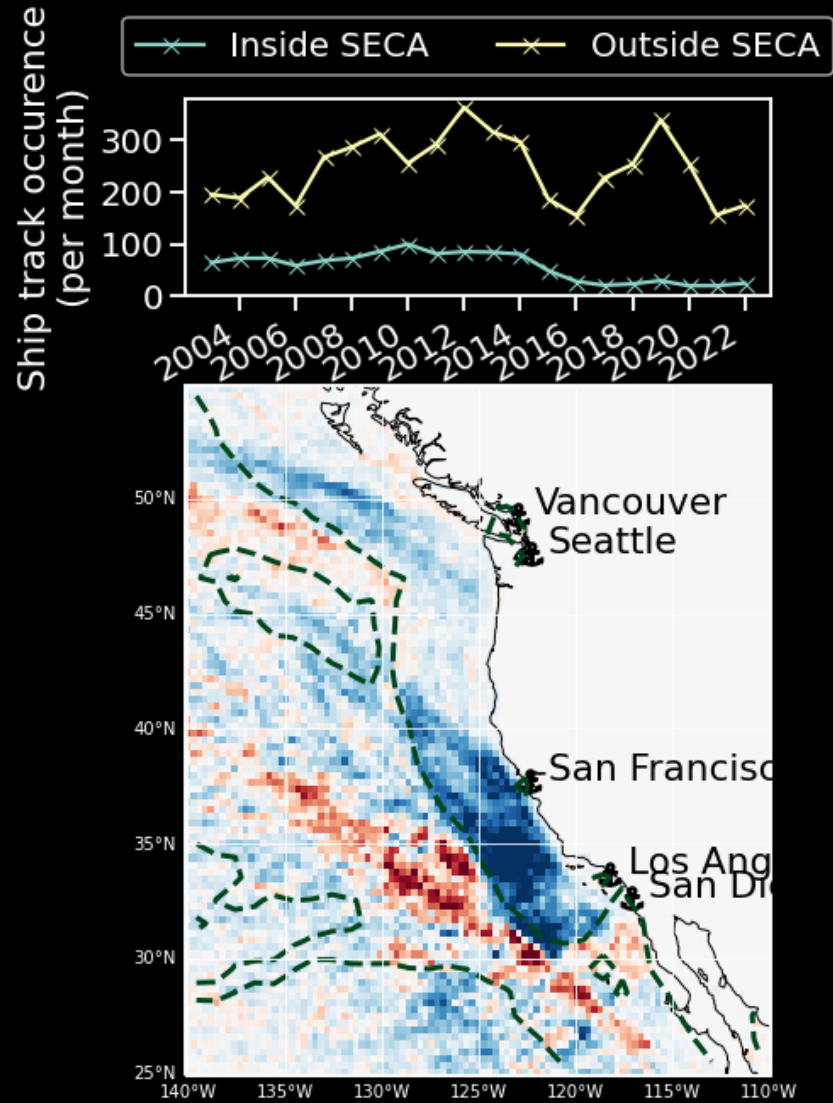
Inference



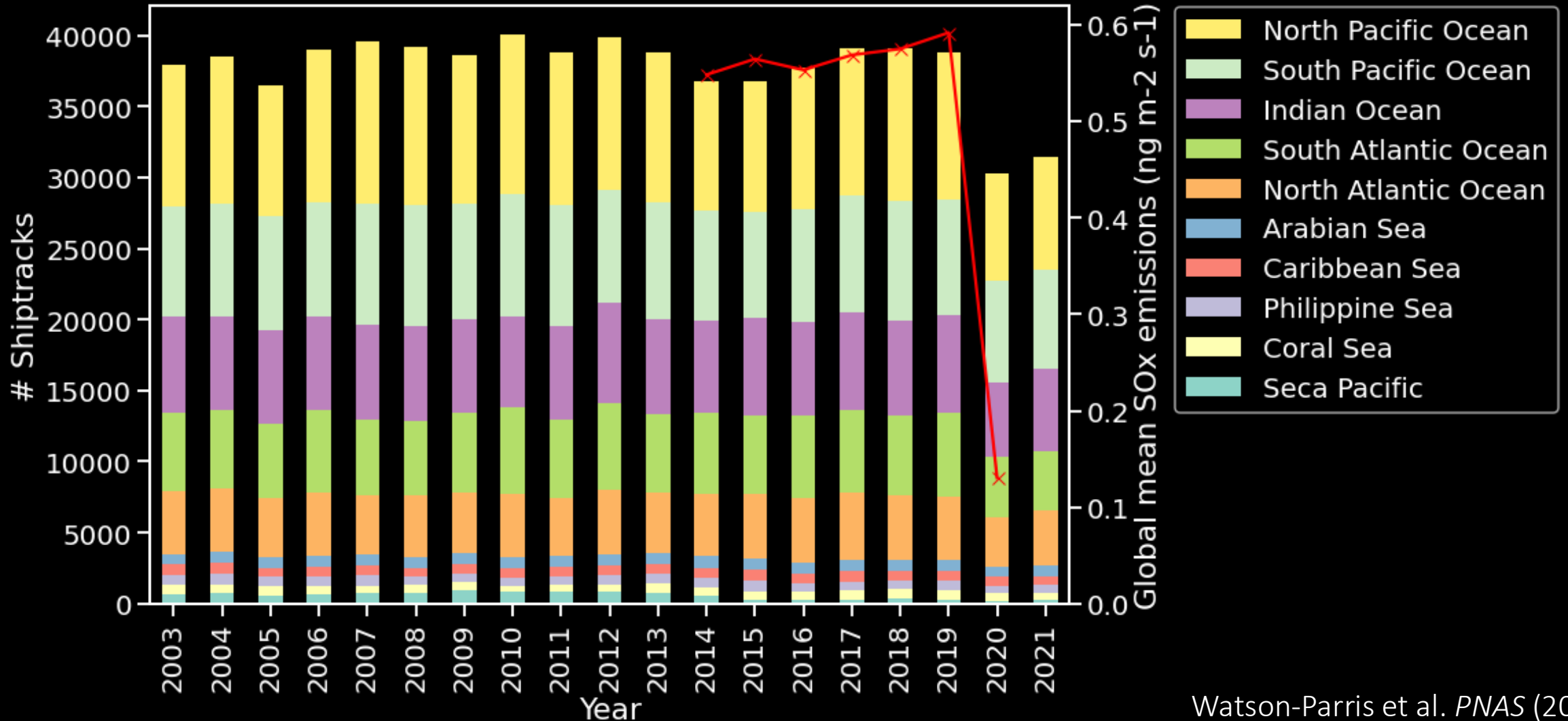
Ship-track density (2003-2021)



Change in ship-track density: SECA



Ship-track counts (2003-2021)





Measuring the **causes** of cloud transitions



Tim Pearce
ML Researcher



Sorawit Saengkyongam
ML Researcher



Will Jones
Clouds Researcher



Lucas Kruitwagen
Climate Researcher



Matt Kusner
ML Lead



Matt Christensen
Domain Lead



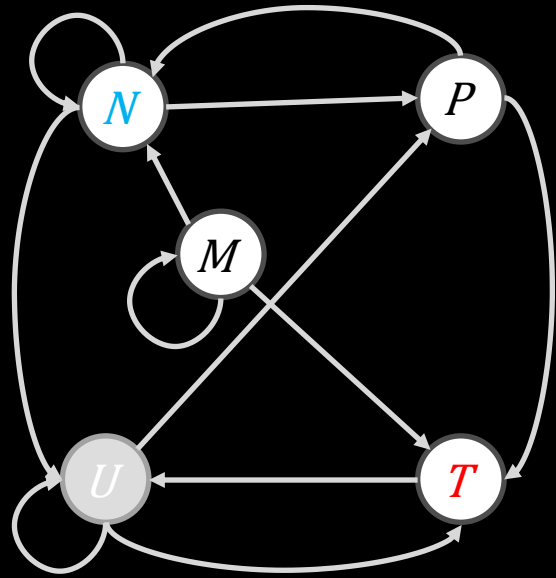
Duncan Watson-Parris
Super Mentor



Measuring the causes of cloud transitions

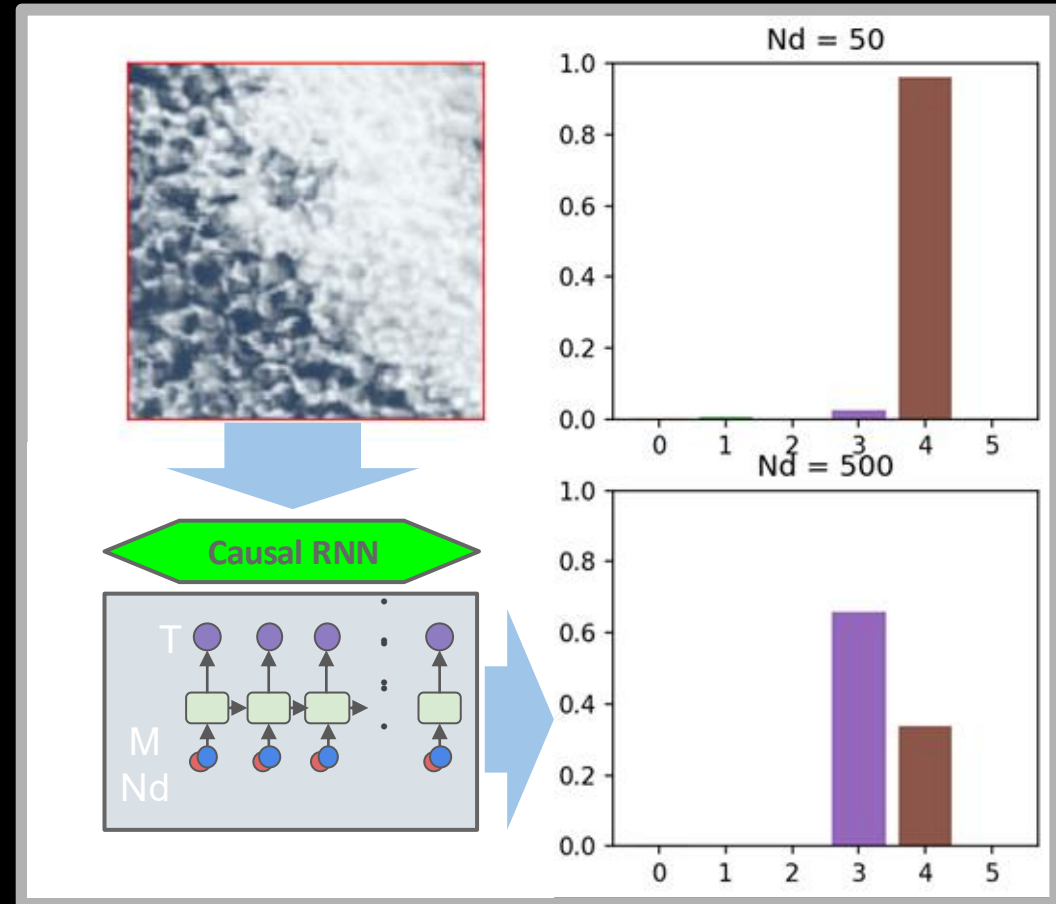


- N_d
- P (recipitation)
- U (nobserved) cloud properties
- T (ype)
- M (eteorology)



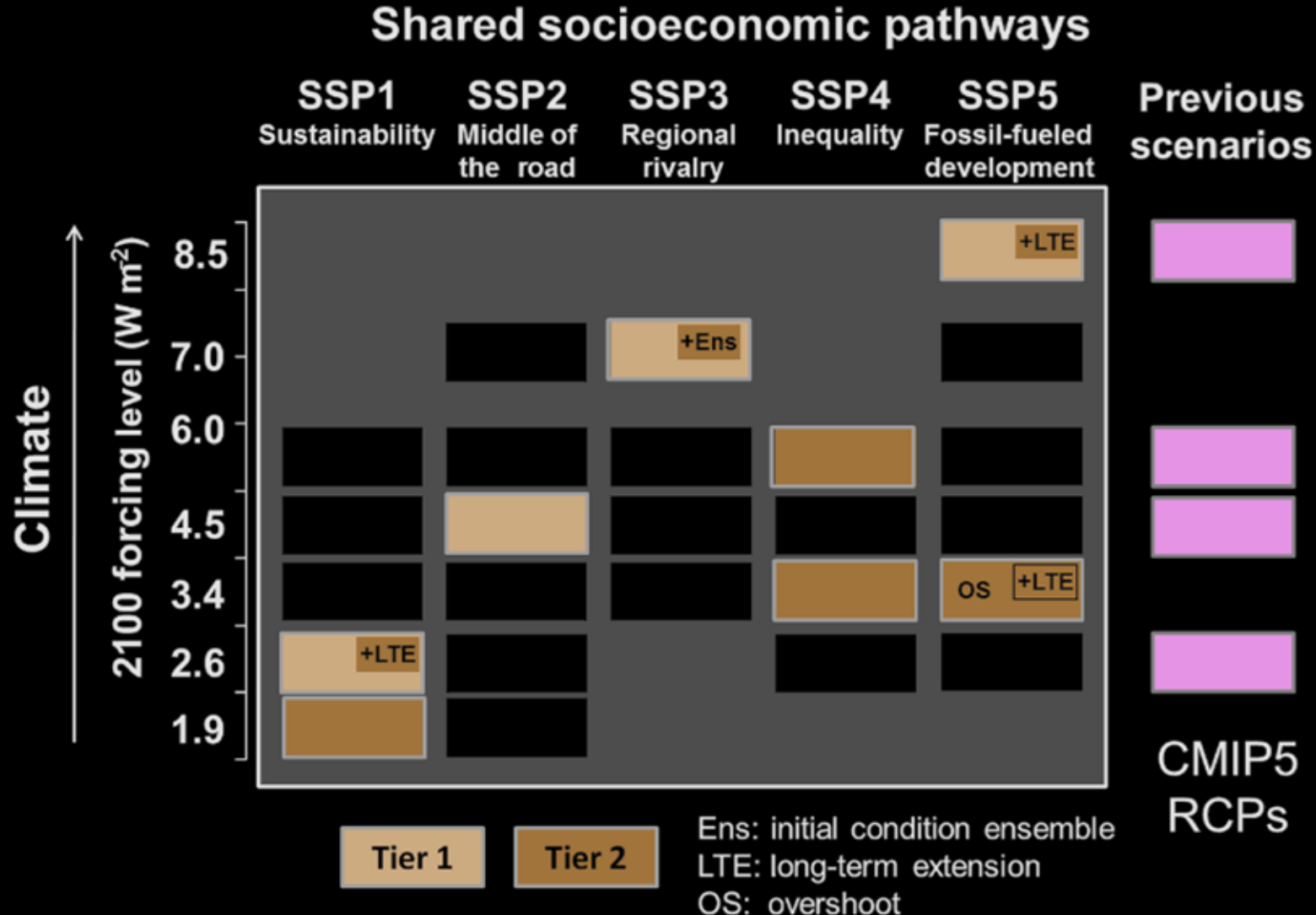
$$P(T_t | do(N_{t'}), M_t) =$$

$$\sum_{M_{t'}, N_{t'-1}, P_{t'-1}} P(T_t | N_{t'}, M_t, M_{t'}, N_{t'-1}, P_{t'-1}) P(M_{t'}, N_{t'-1}, P_{t'-1})$$

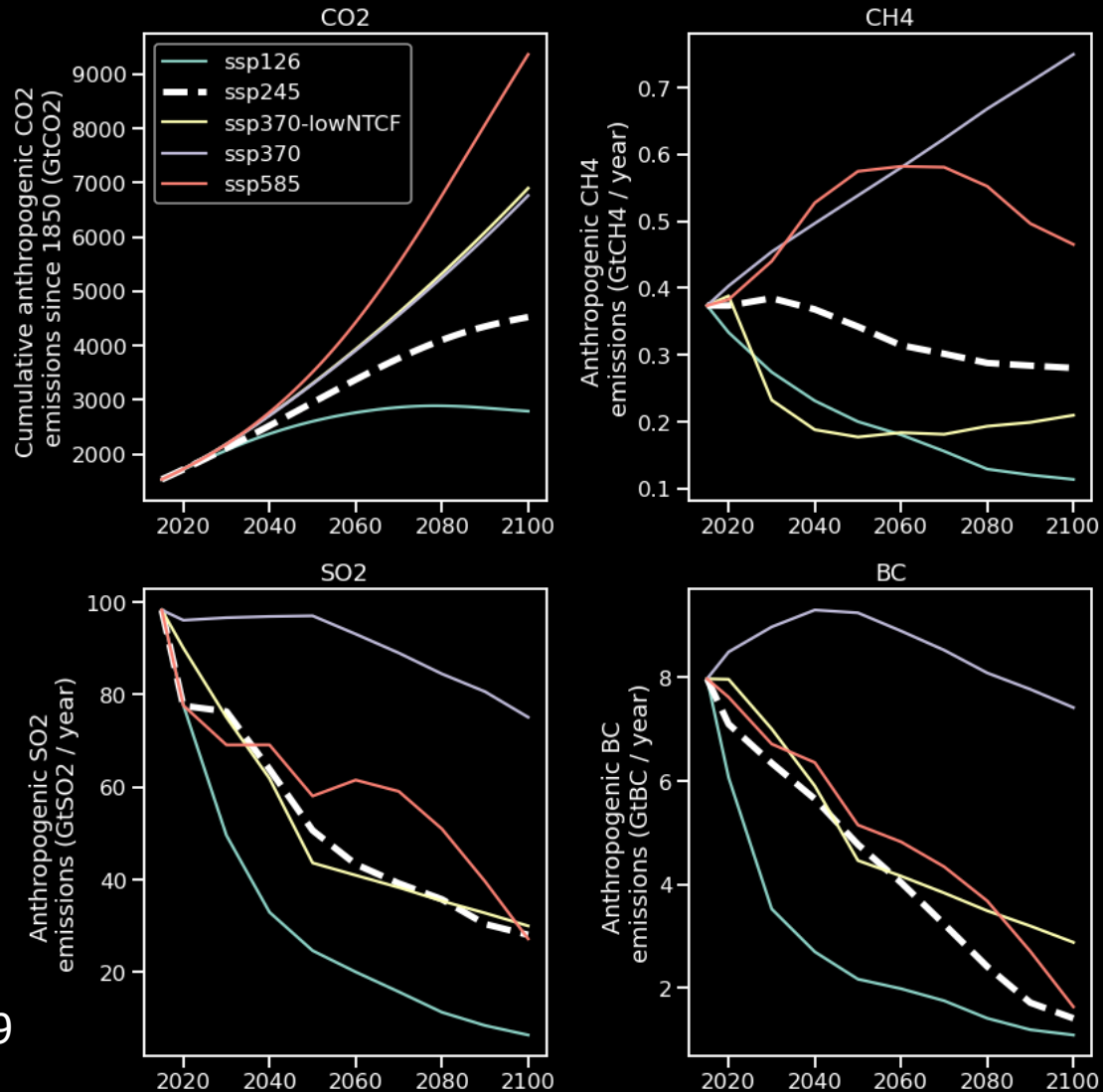


Exploring different climates with emulators

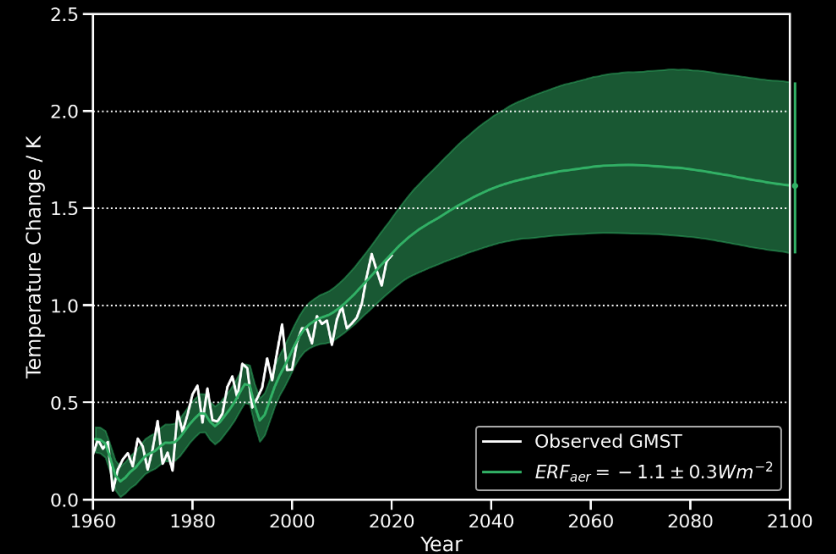
Climate projections: ScenarioMIP



Exploring different scenarios: (Simple) Emulators

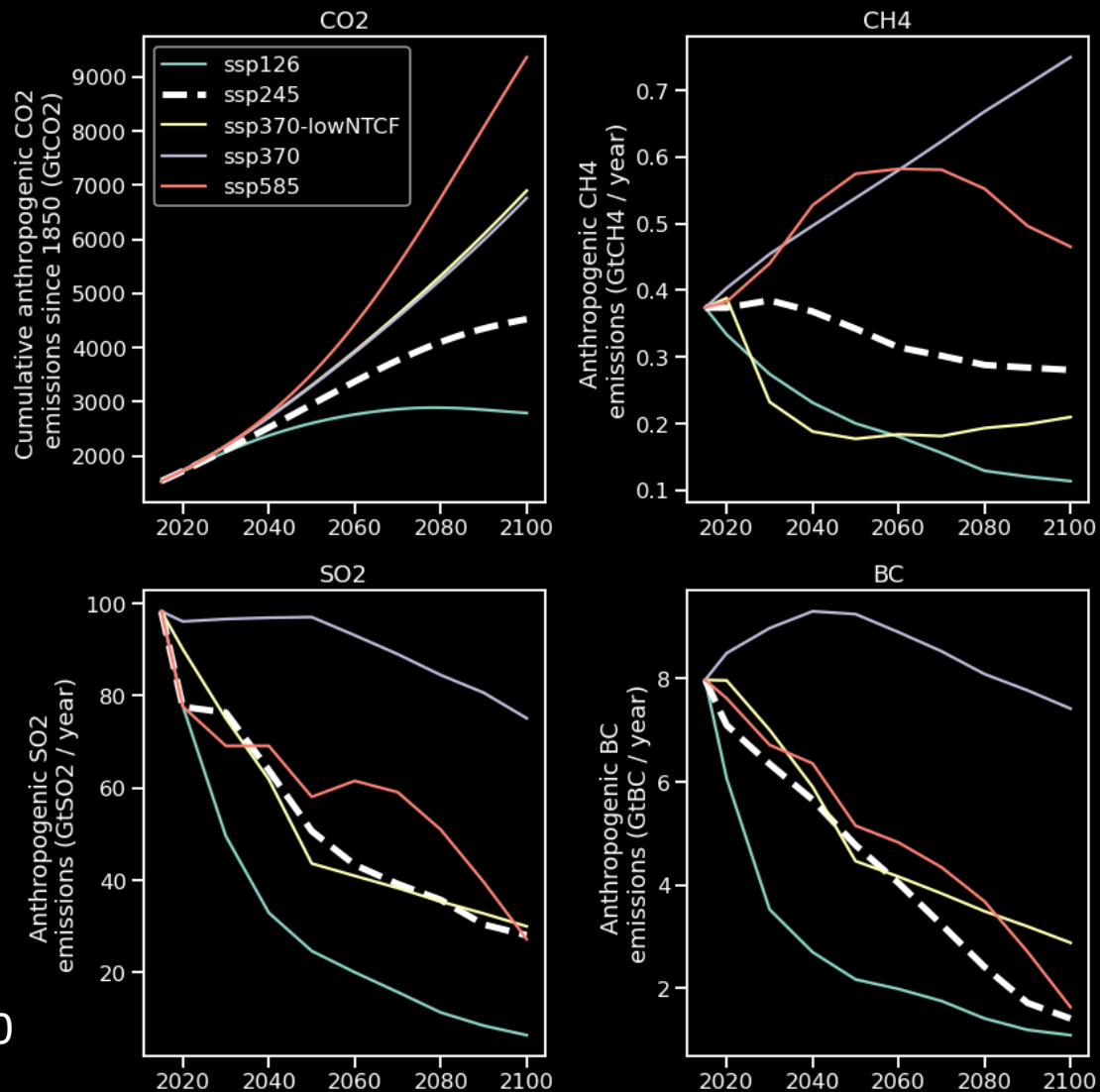


Emulate $|\mathcal{F}(X, \theta)|$

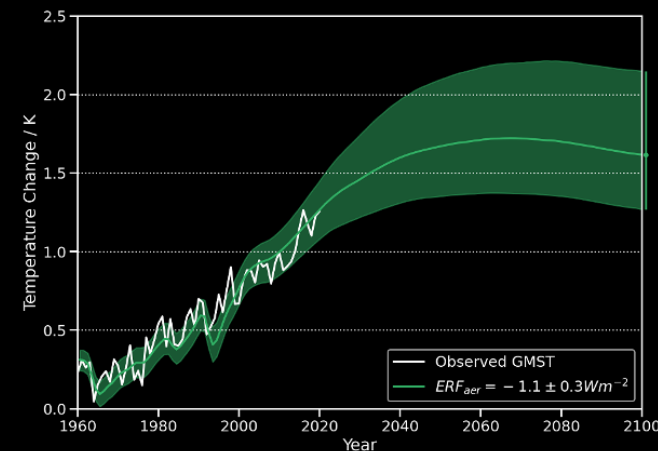


E.g., FAIR, MAGGIC, WASP etc.

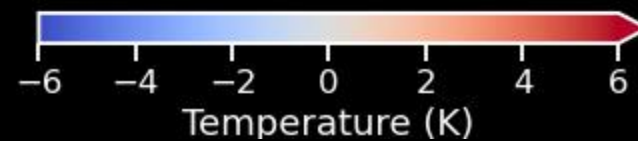
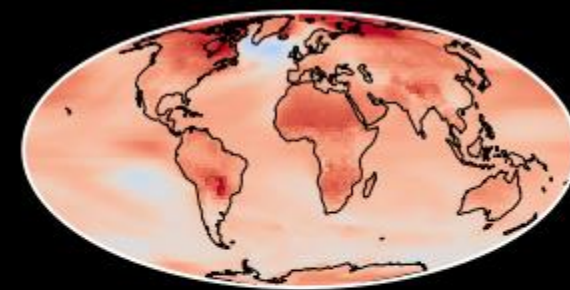
Exploring different scenarios: Pattern Scaling



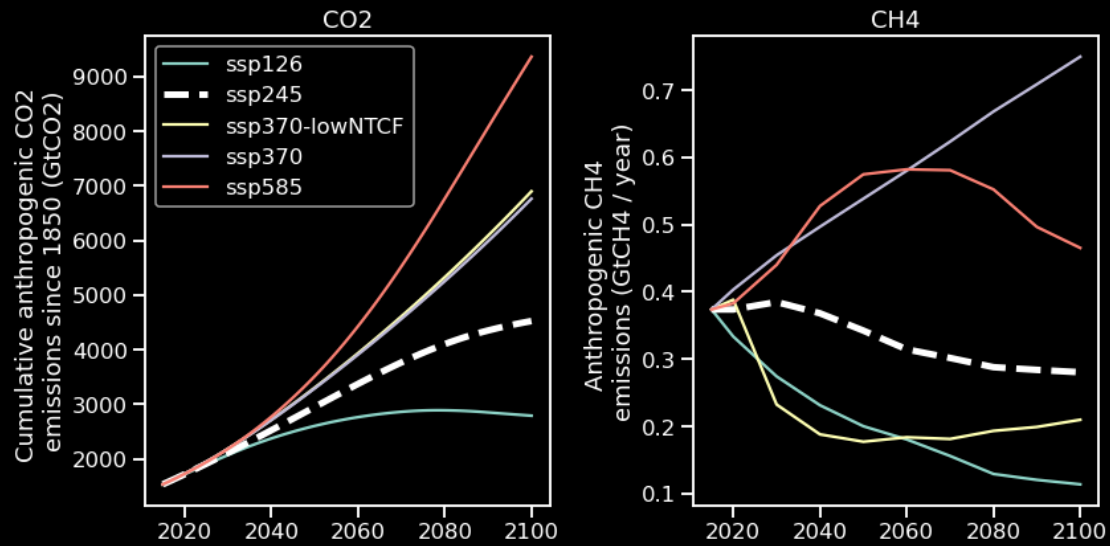
Emulate $|\mathcal{F}(X, \theta)|$



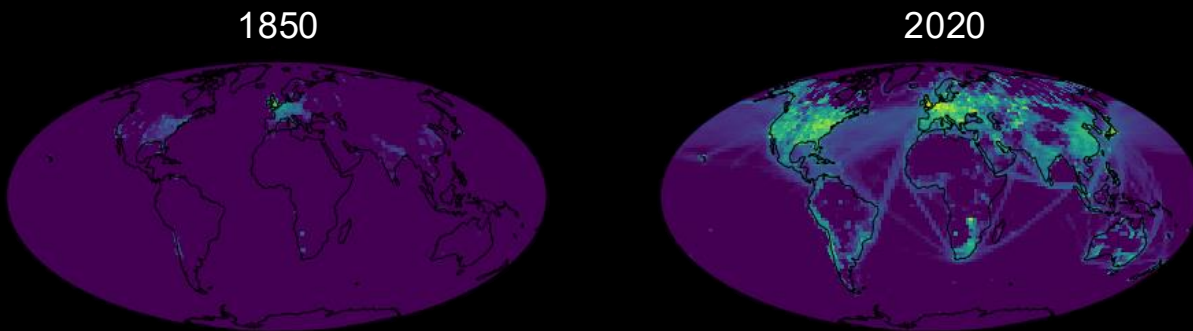
E.g., MESMER



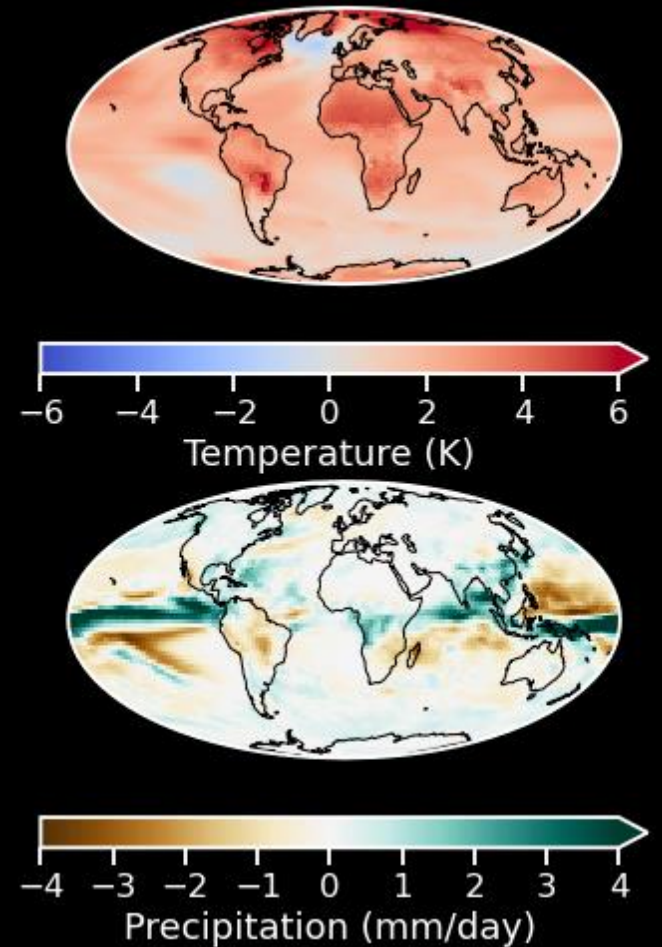
Exploring different scenarios: ClimateBench



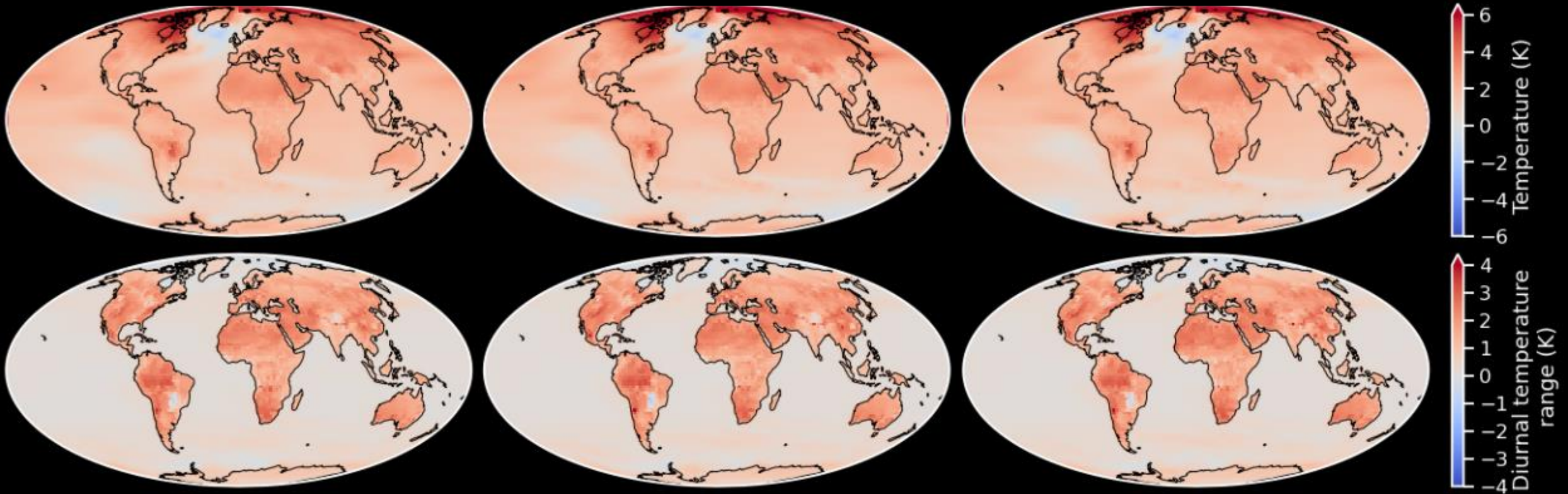
Spatially resolved emissions of SO2 and BC



Emulate $\mathcal{F}(X, \theta)$

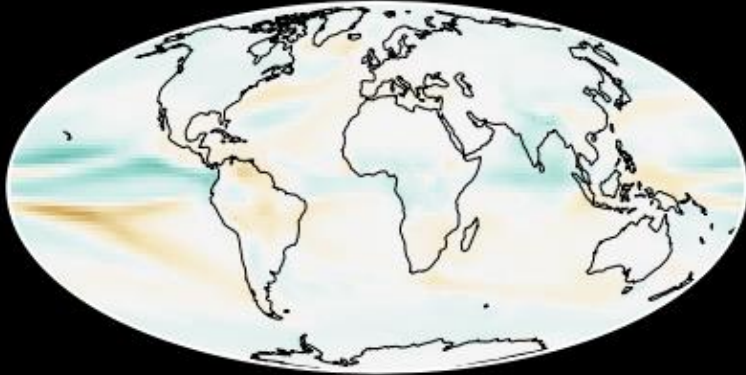


Baseline Models

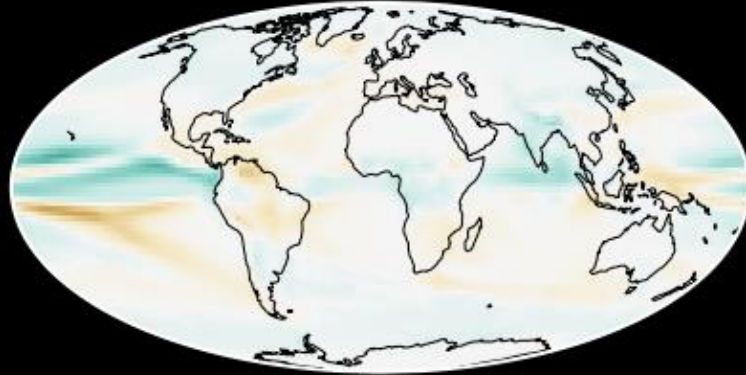


Baseline Models

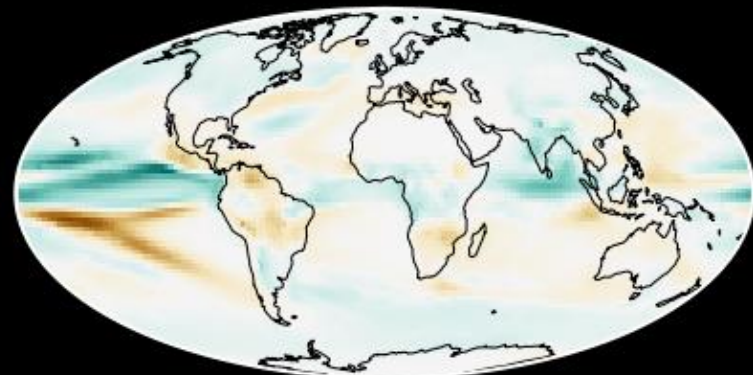
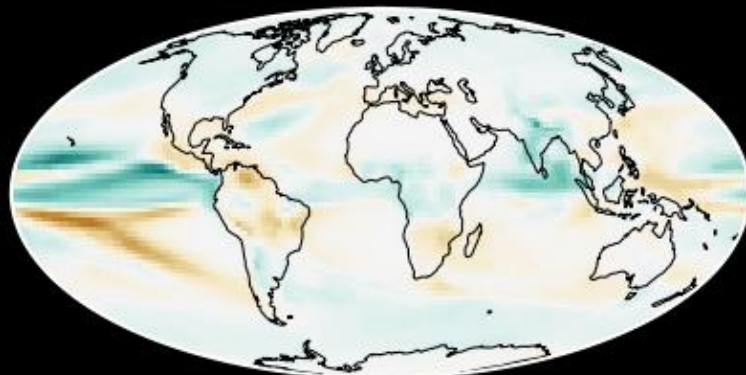
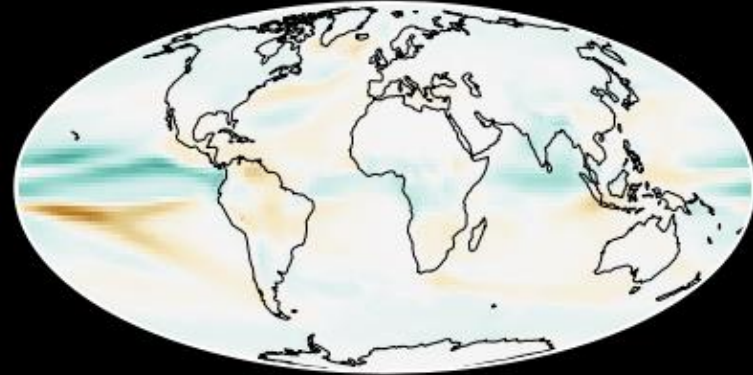
Neural Network



Gaussian Process



NorESM2



Summary

- Machine learning can be harnessed to accelerate climate science
- Such techniques are used to create Earth system model **emulators** for parameter estimation and constraining uncertainty
- We have also used it for **detecting** ship-tracks and detecting and quantify the changes aerosol are **causing** on different clouds
- ClimateBench has enabled new emulators for the fast and accurate exploration of different future climates
- Ultimately these approaches will allow better informed policy.

ClassBuzz

MM3Z

Spare slides

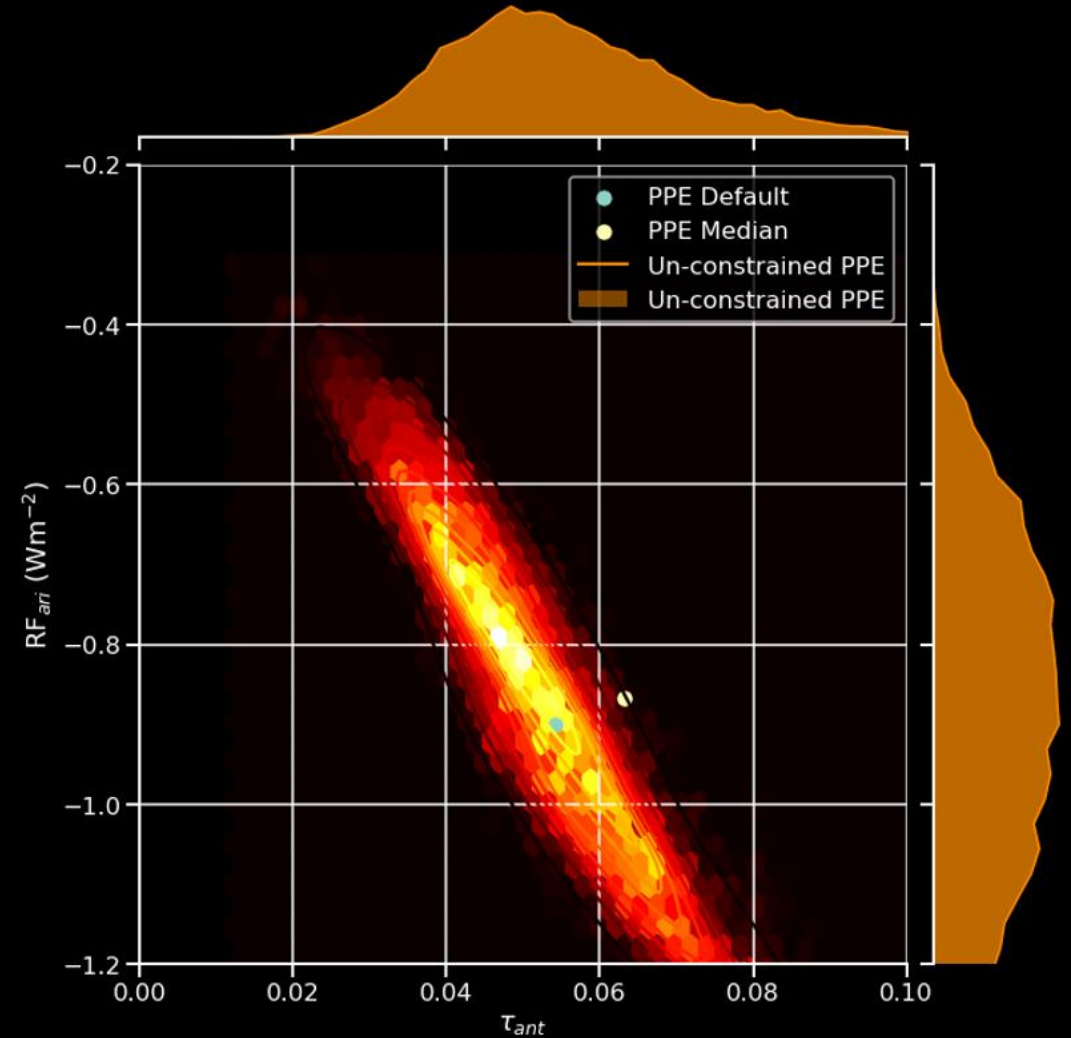
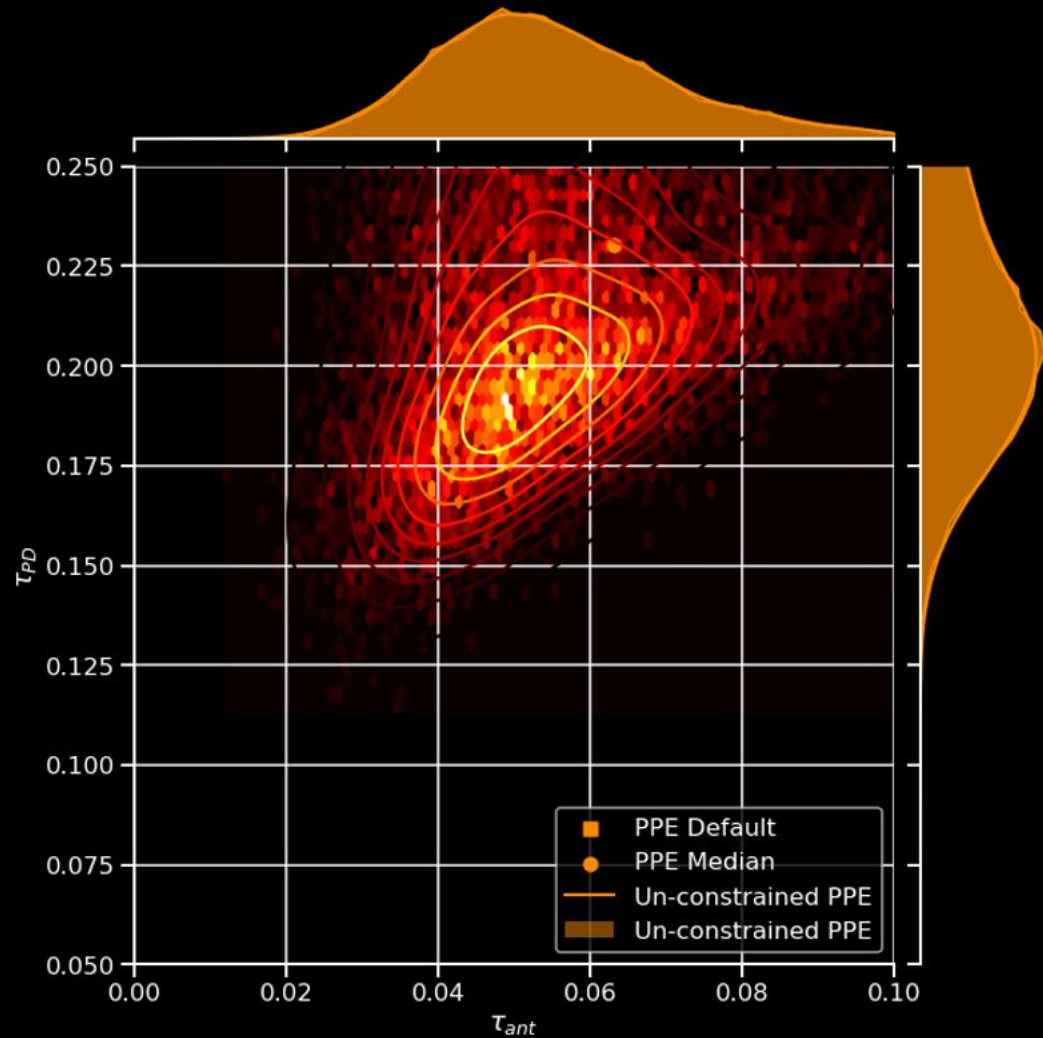
Box model of the climate

The simplest model we can write of the climate system:

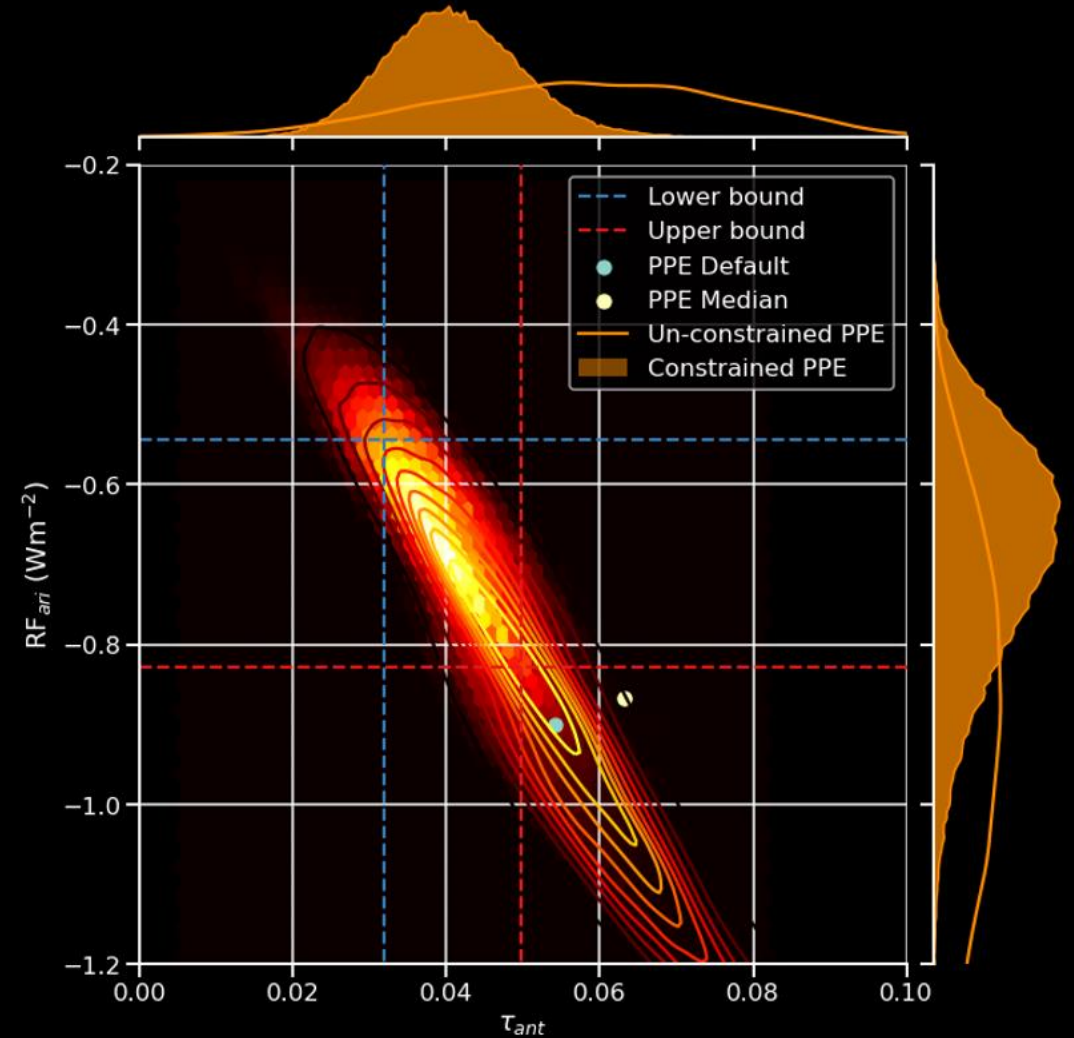
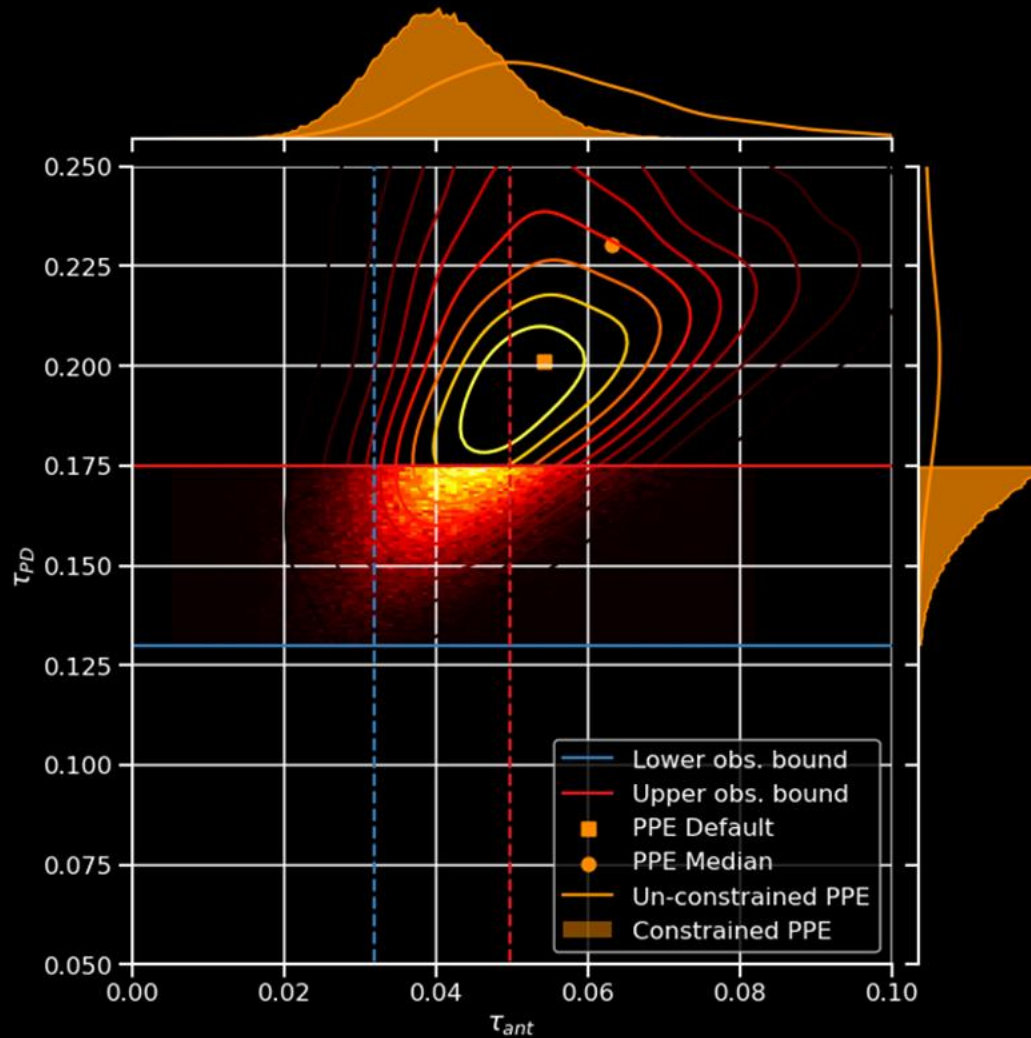
$$C \frac{dT}{dt} = F_{ext} - \lambda T$$

- T is the global average surface temperature change.
- C is the “effective heat capacity”.
- F_{ext} is imbalance between incoming and outgoing energy.
- λ is a constant “sensitivity parameter”.

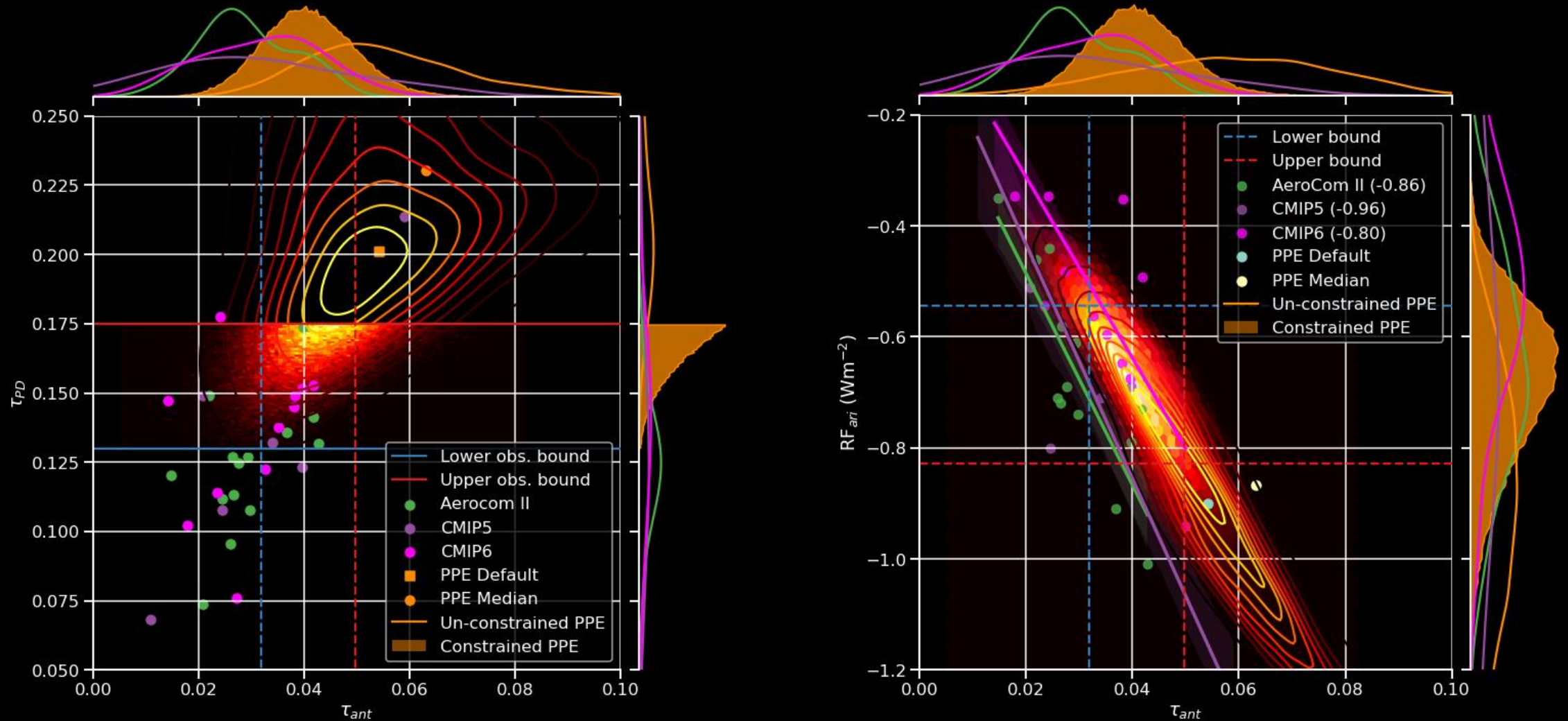
Constraining parametric uncertainty



Constraining parametric uncertainty

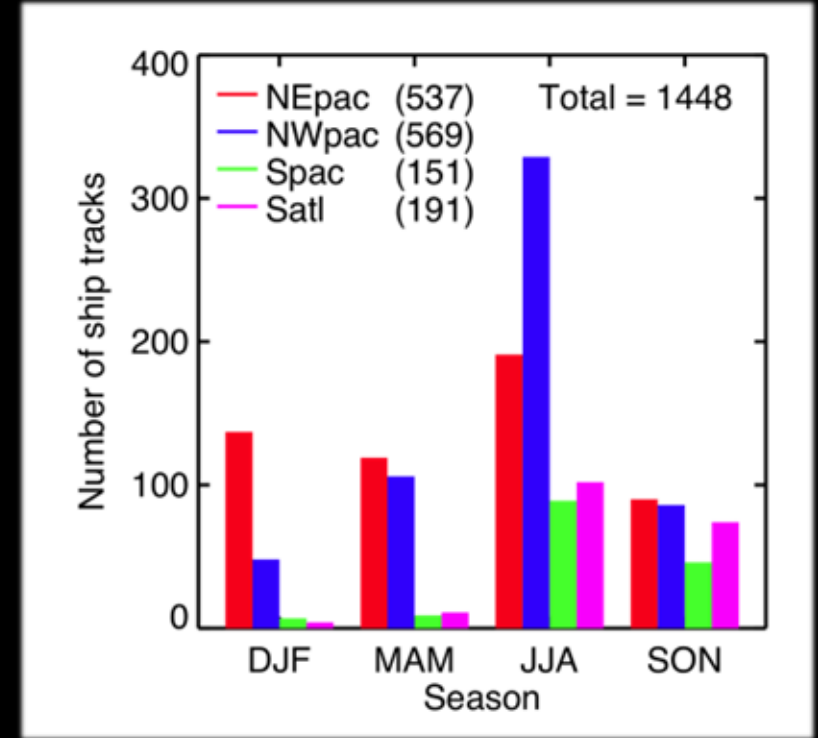
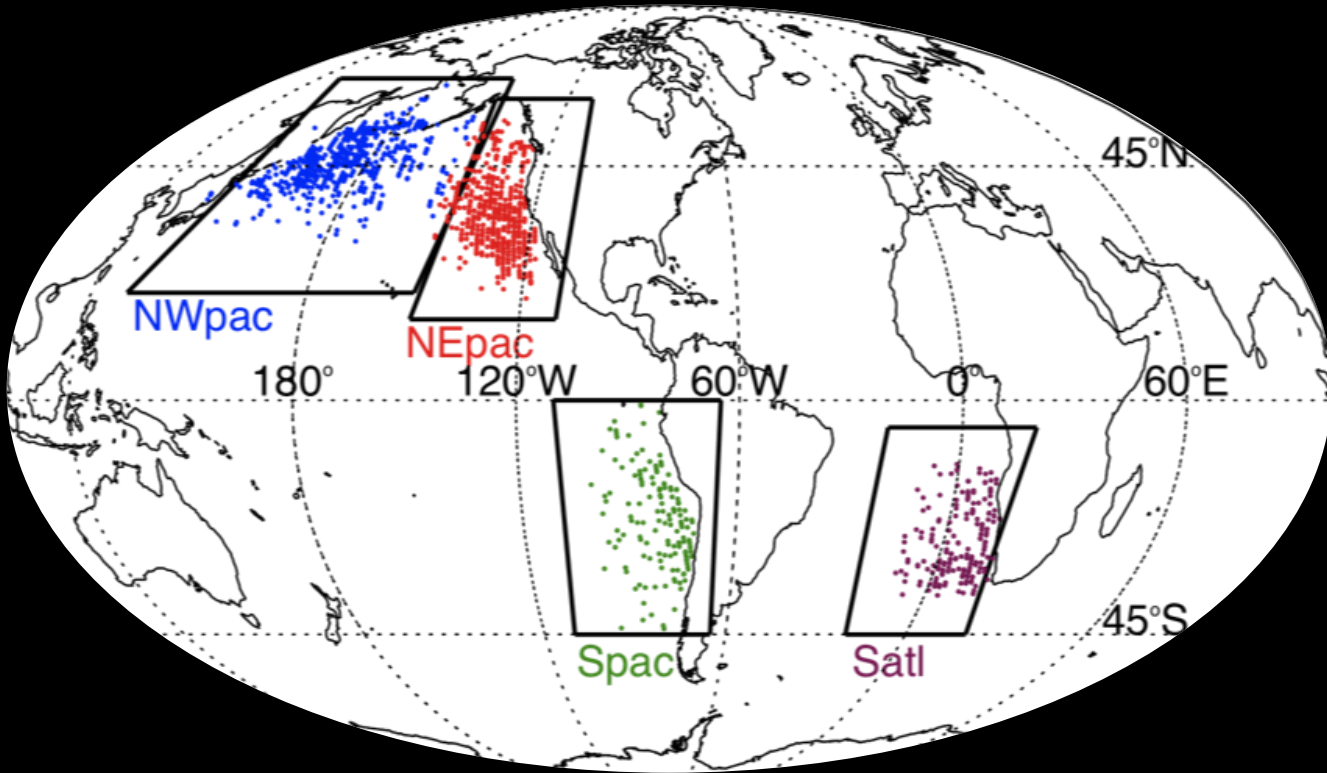


Constraining parametric uncertainty



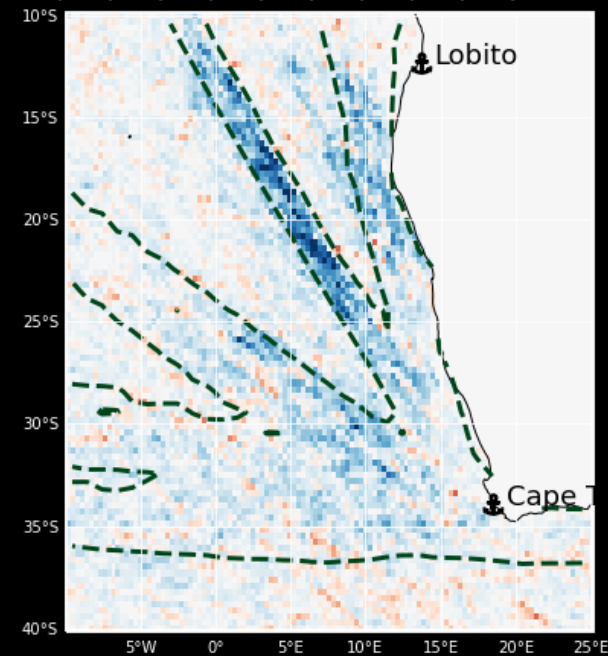
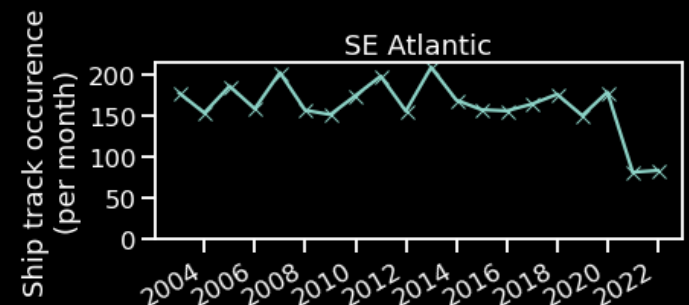
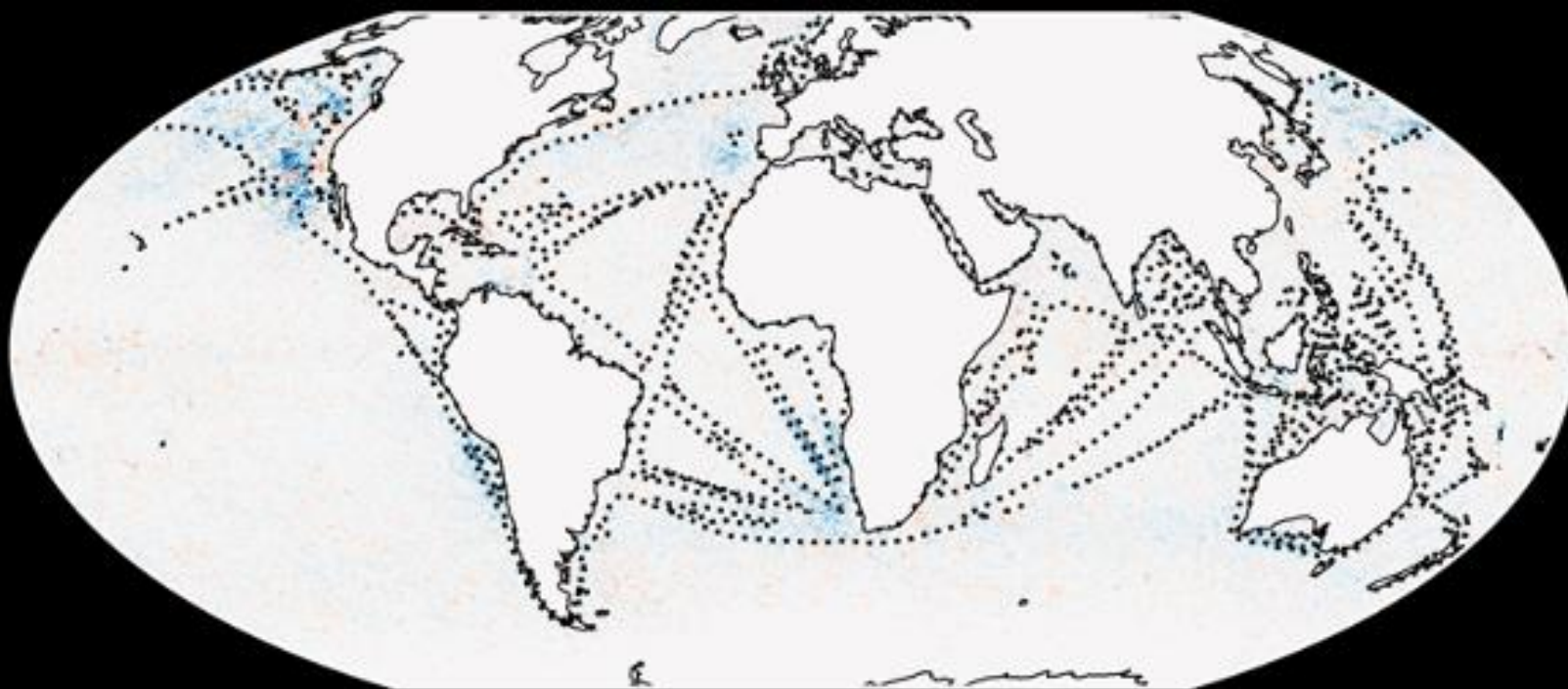
Shiptrack spares

Training data

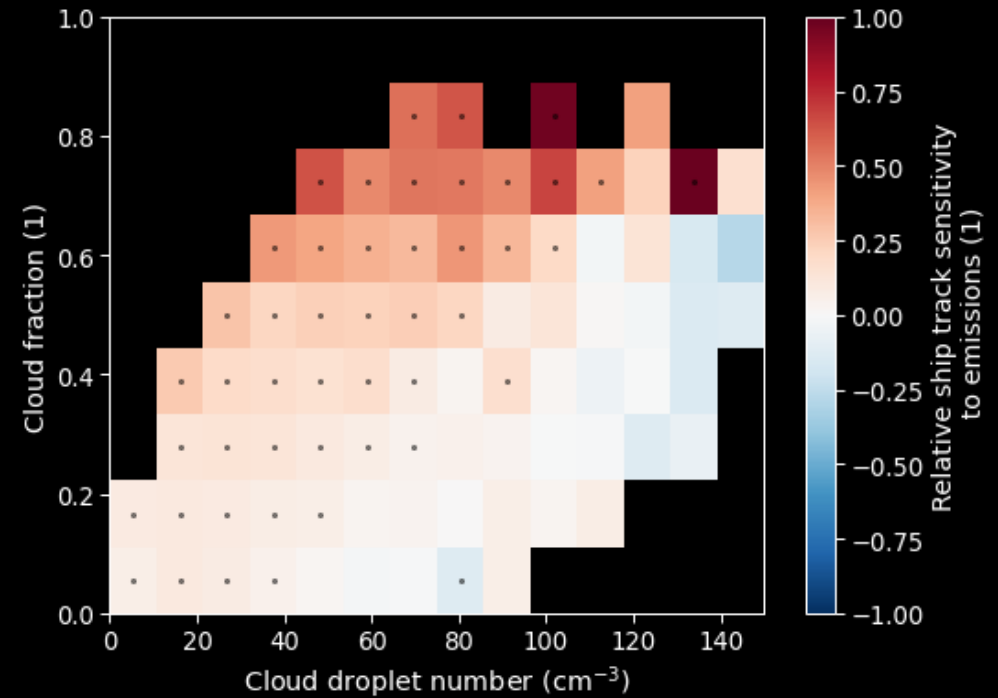
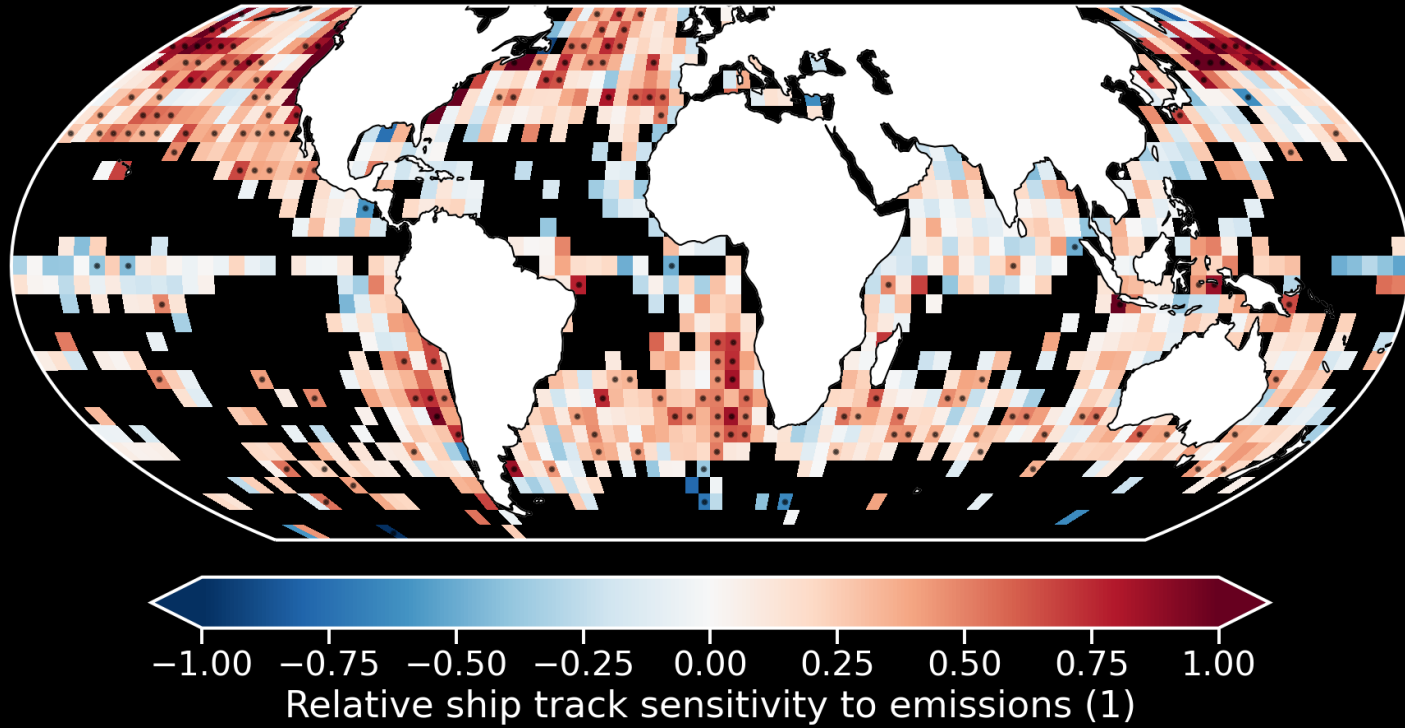


4,000 ship tracks from Segrin et al. (2007), off the coast of California (MODIS)
1,000 volcano tracks from Toll et al. (2017), South Sandwich and Kuril Islands
Total: 5,500 hand-logged tracks

Change in ship-track density: IMO

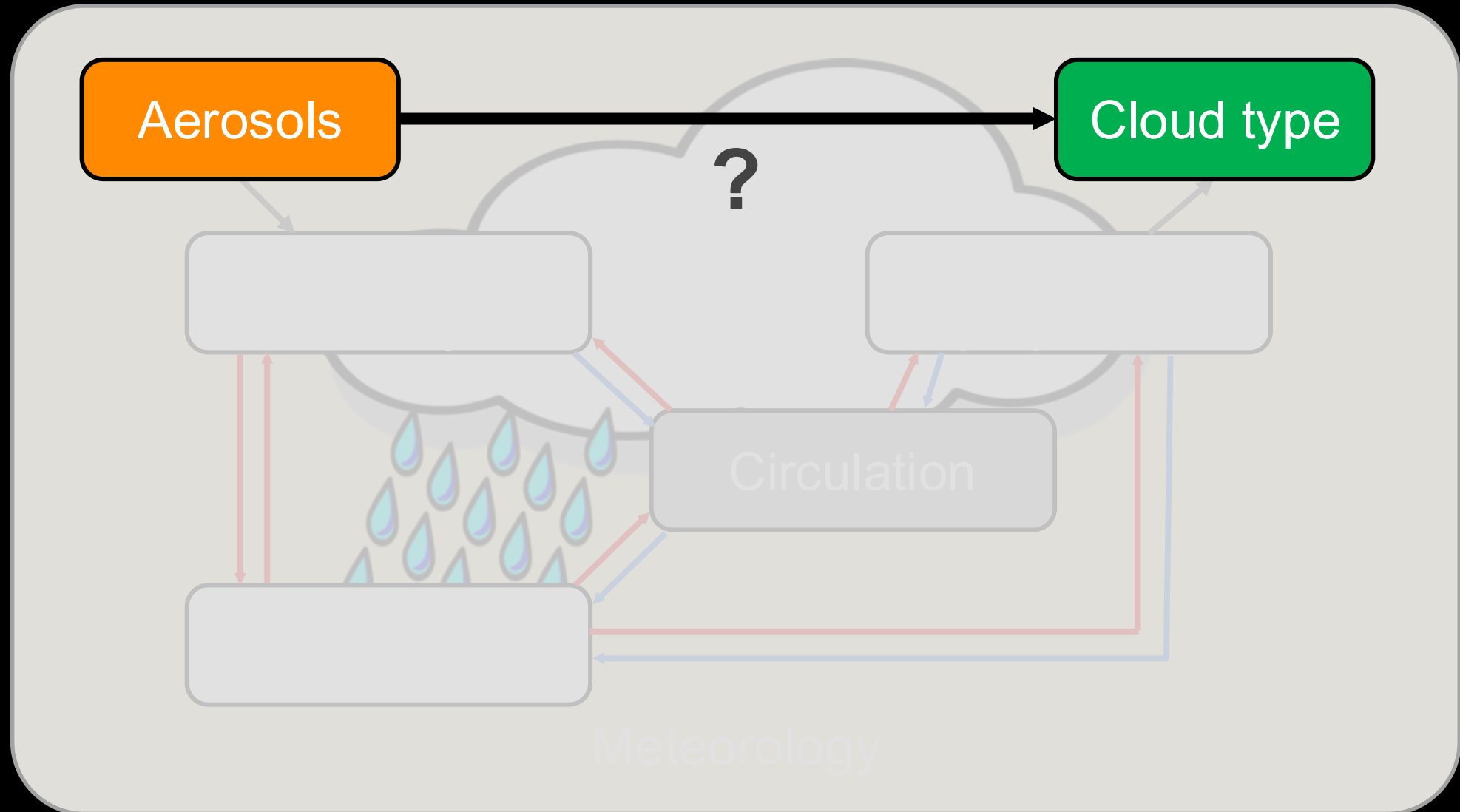


Ship-track sensitivity to emissions

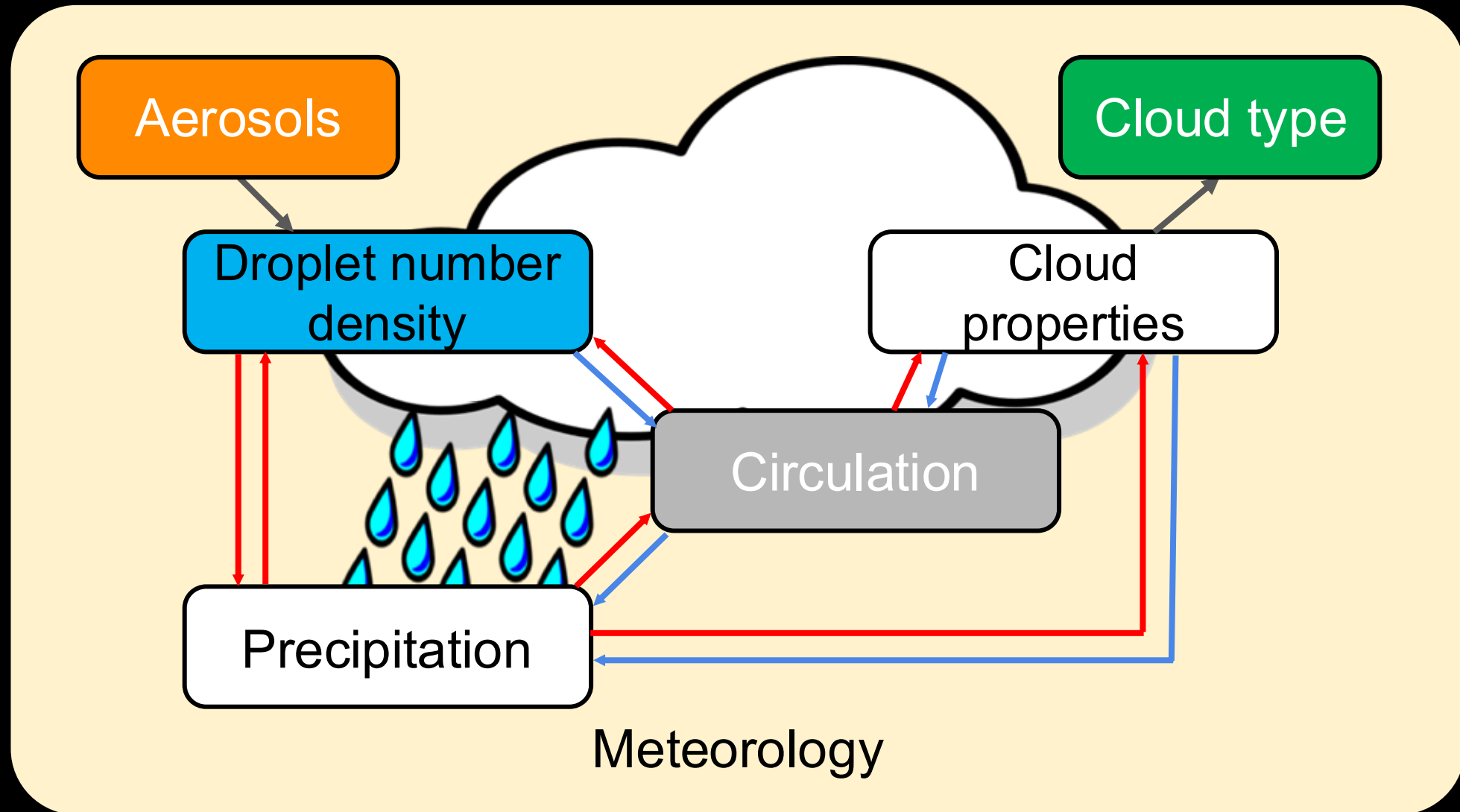


Causal spares

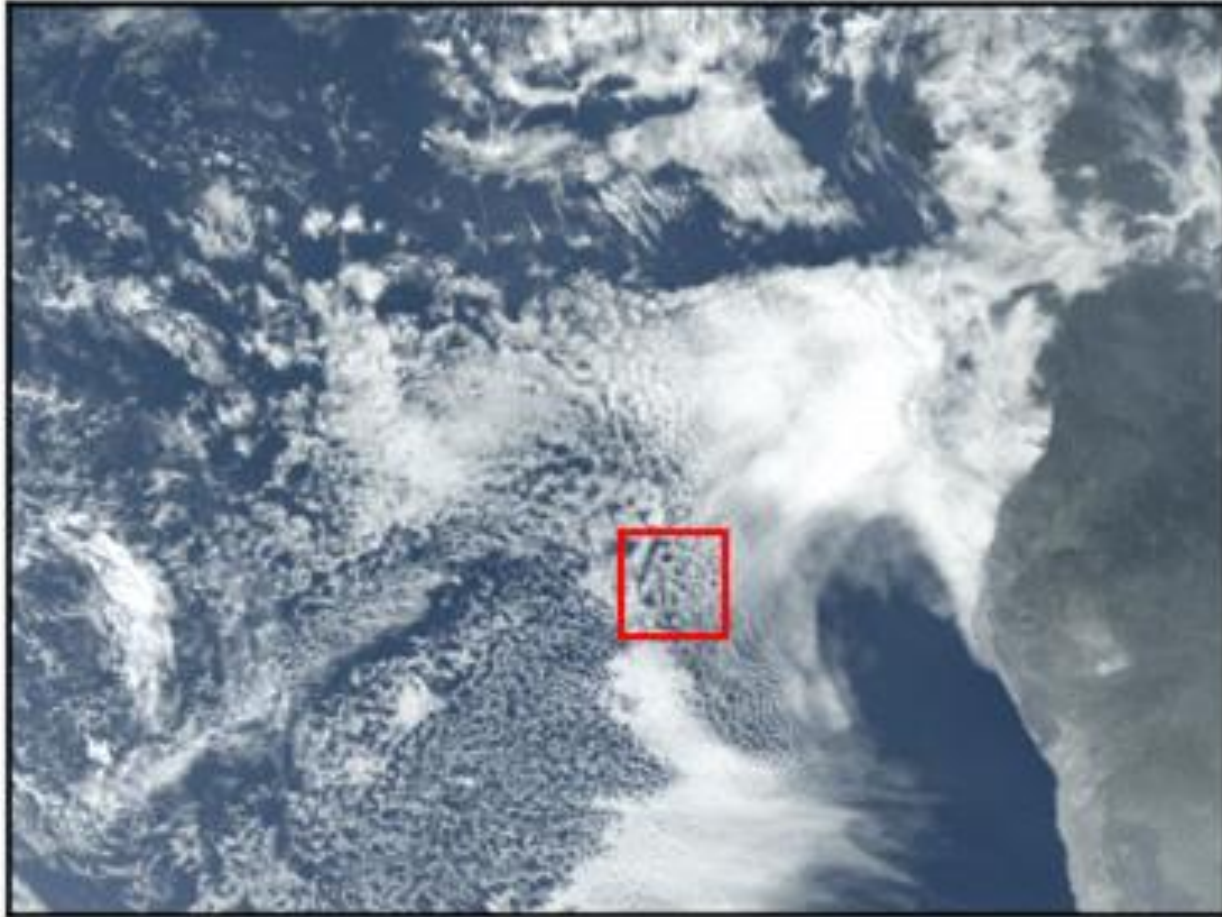
Causal Effect of Aerosol on Cloud Type



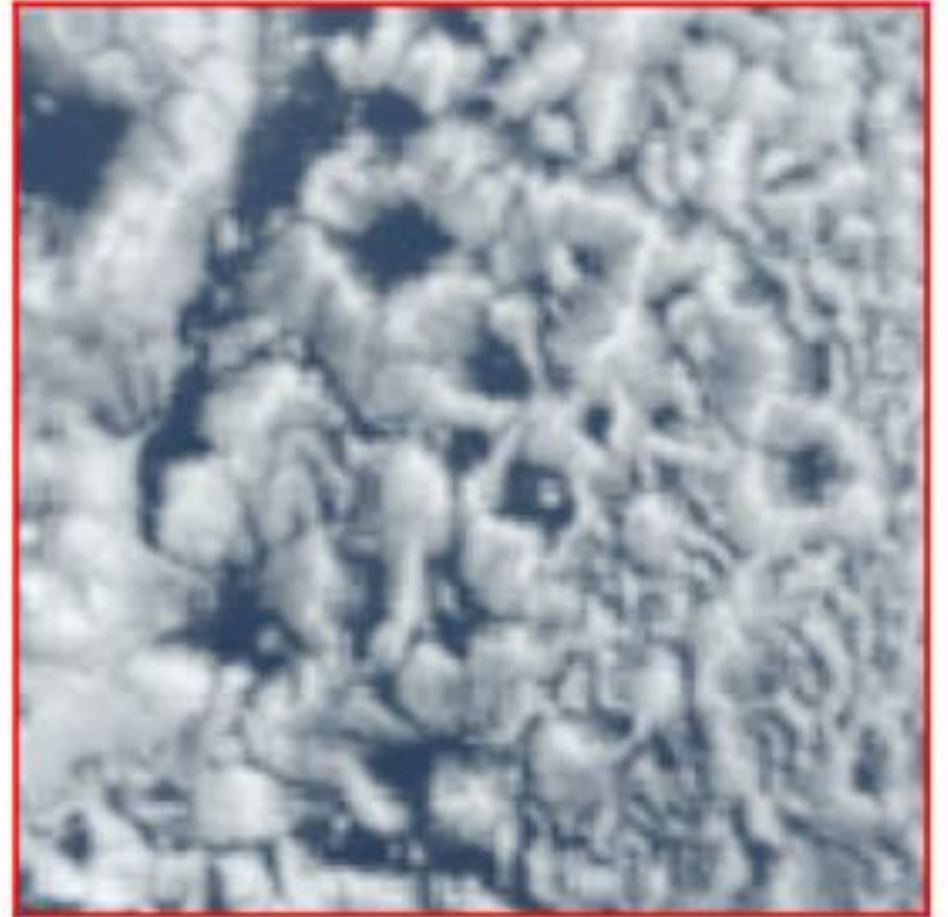
Causal Effect of Aerosol on Cloud Type



Lagrangian Reference Data

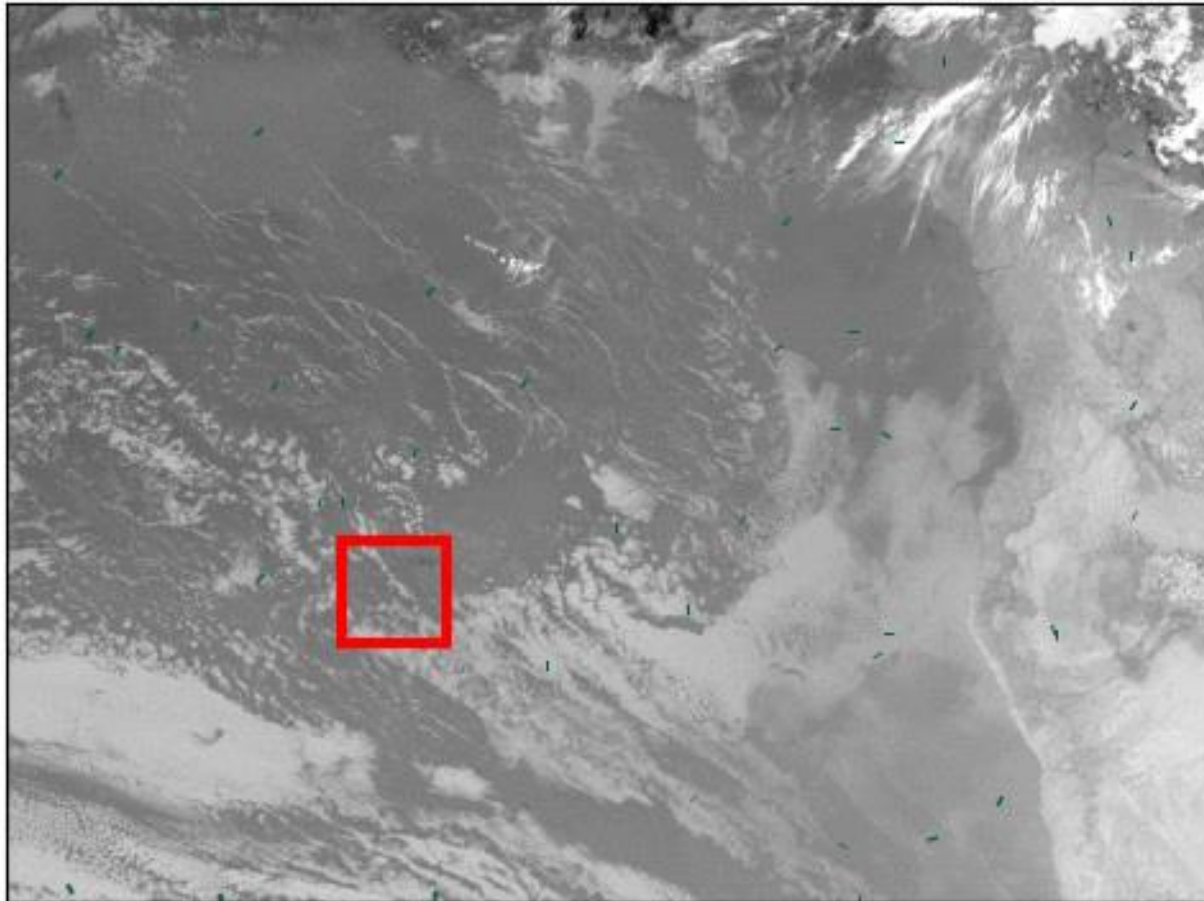


4500km



400km

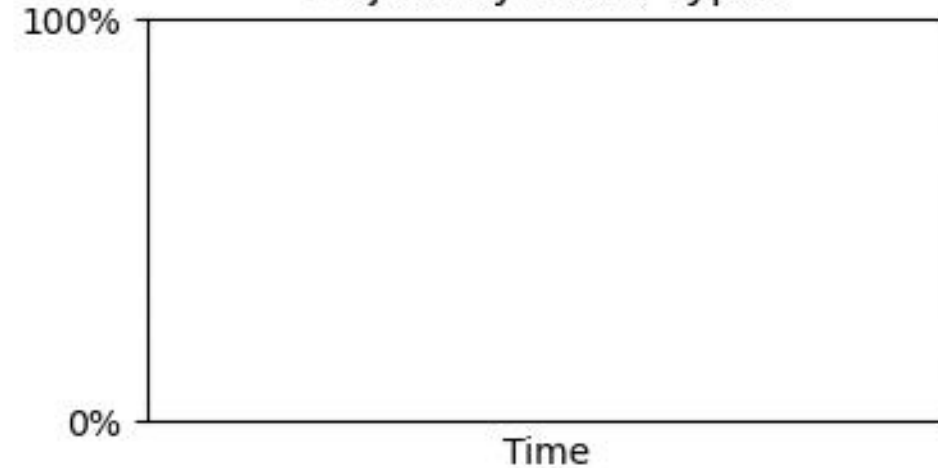
Cloud Types Along Trajectories



Patch Cloud Types

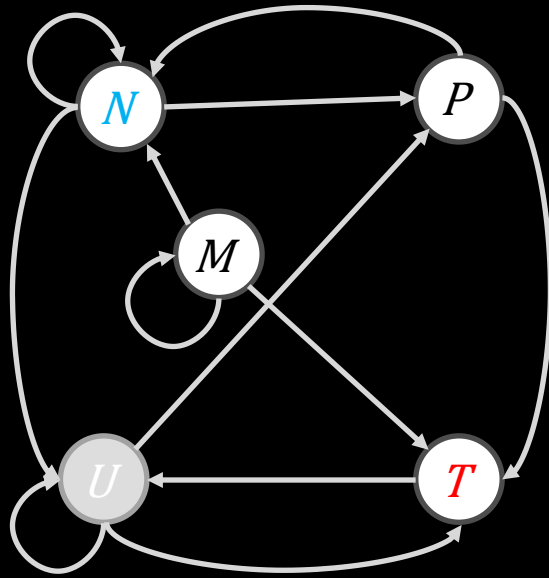


Trajectory Cloud Types

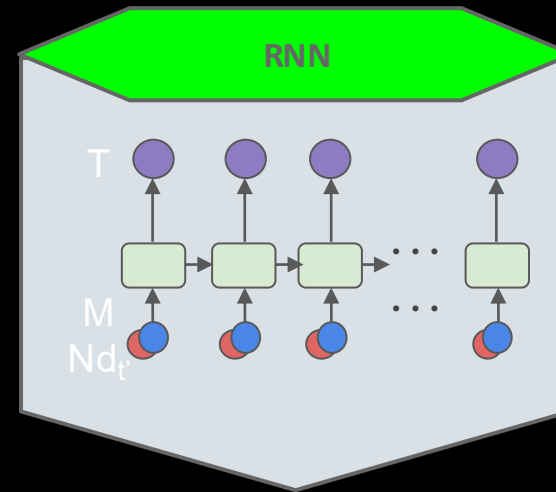


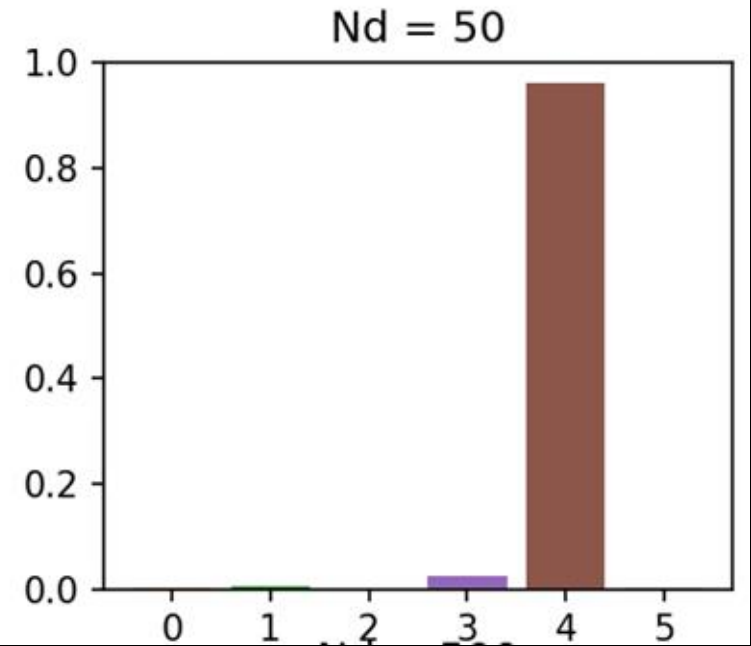
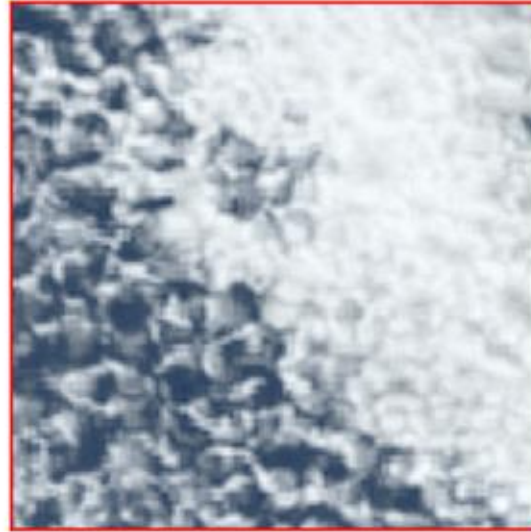
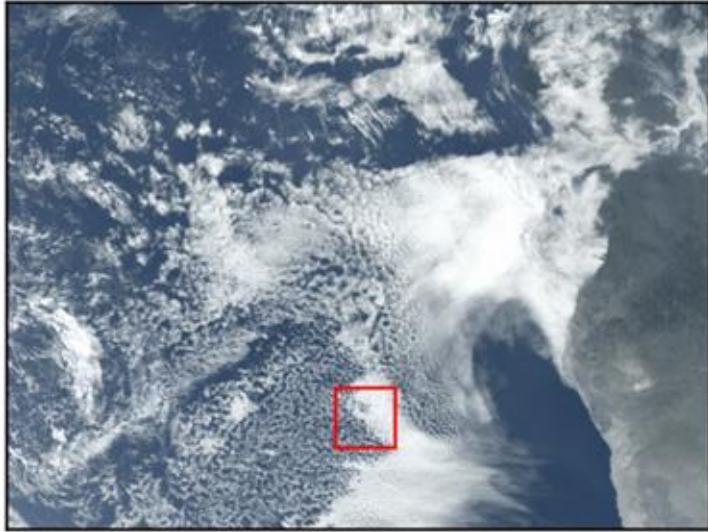
Causal Effect of Droplet Number on Cloud Type

- N_d
- P (recipitation)
- U (nobserved) cloud properties
- T (ype)
- M (eteorology)






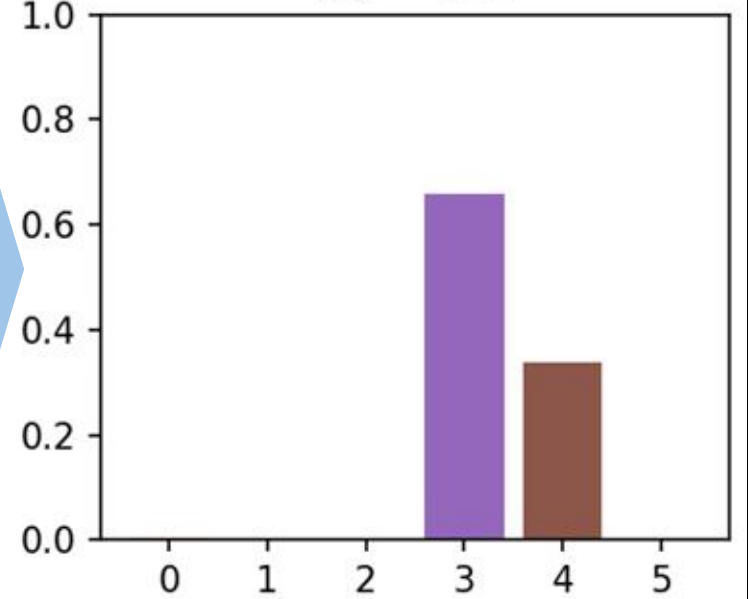
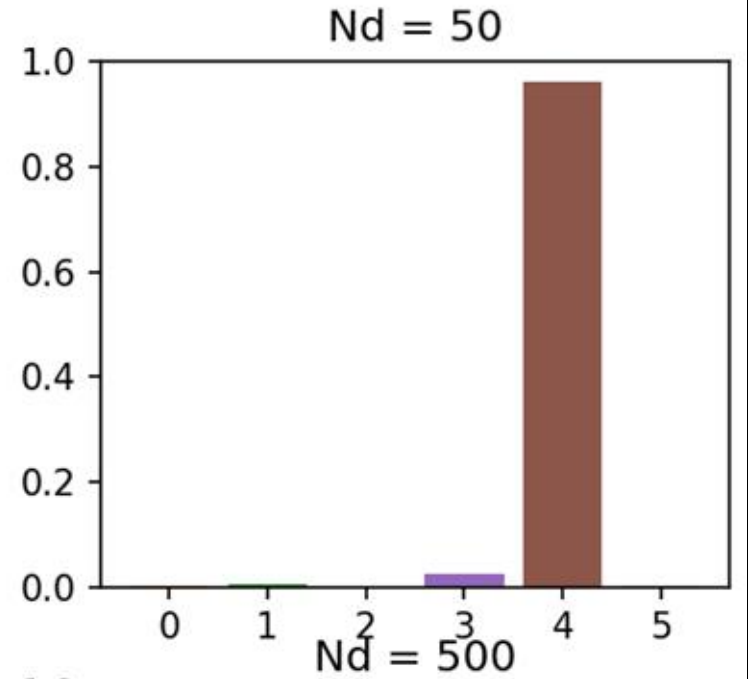
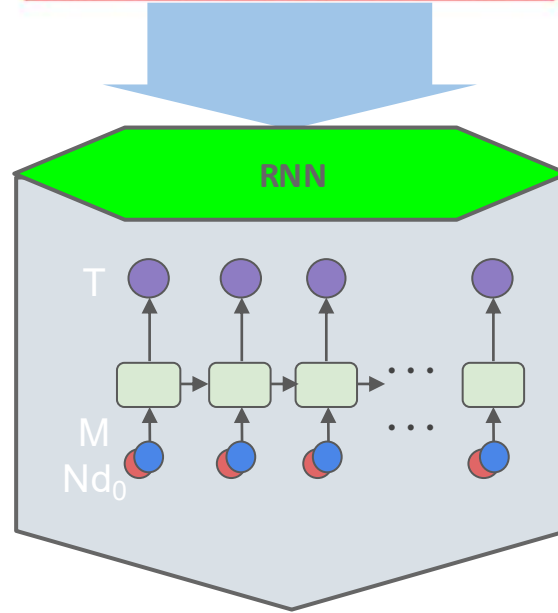
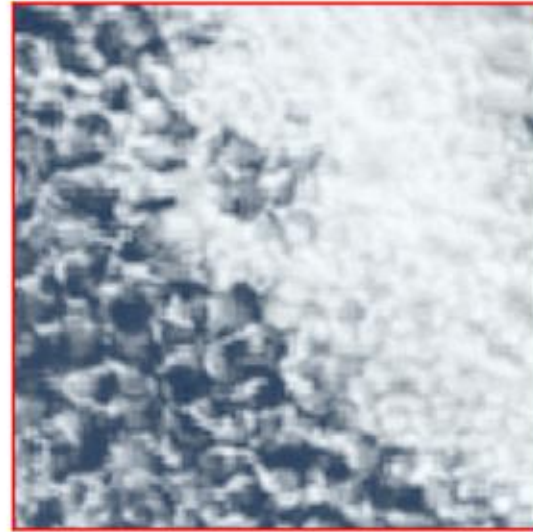
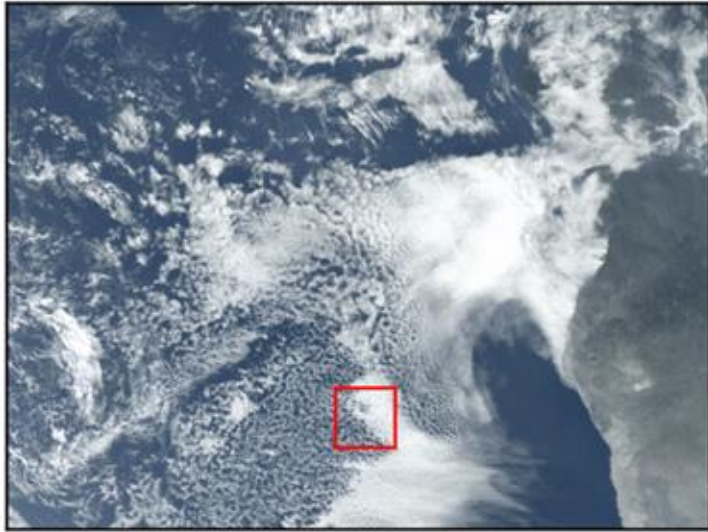
$$P(T_t | do(N_{t'}), M_t) = \sum_{M_{t'}, N_{t'-1}, P_{t'-1}} P(T_t | N_{t'}, M_t, M_{t'}, N_{t'-1}, P_{t'-1}) P(M_{t'}, N_{t'-1}, P_{t'-1})$$








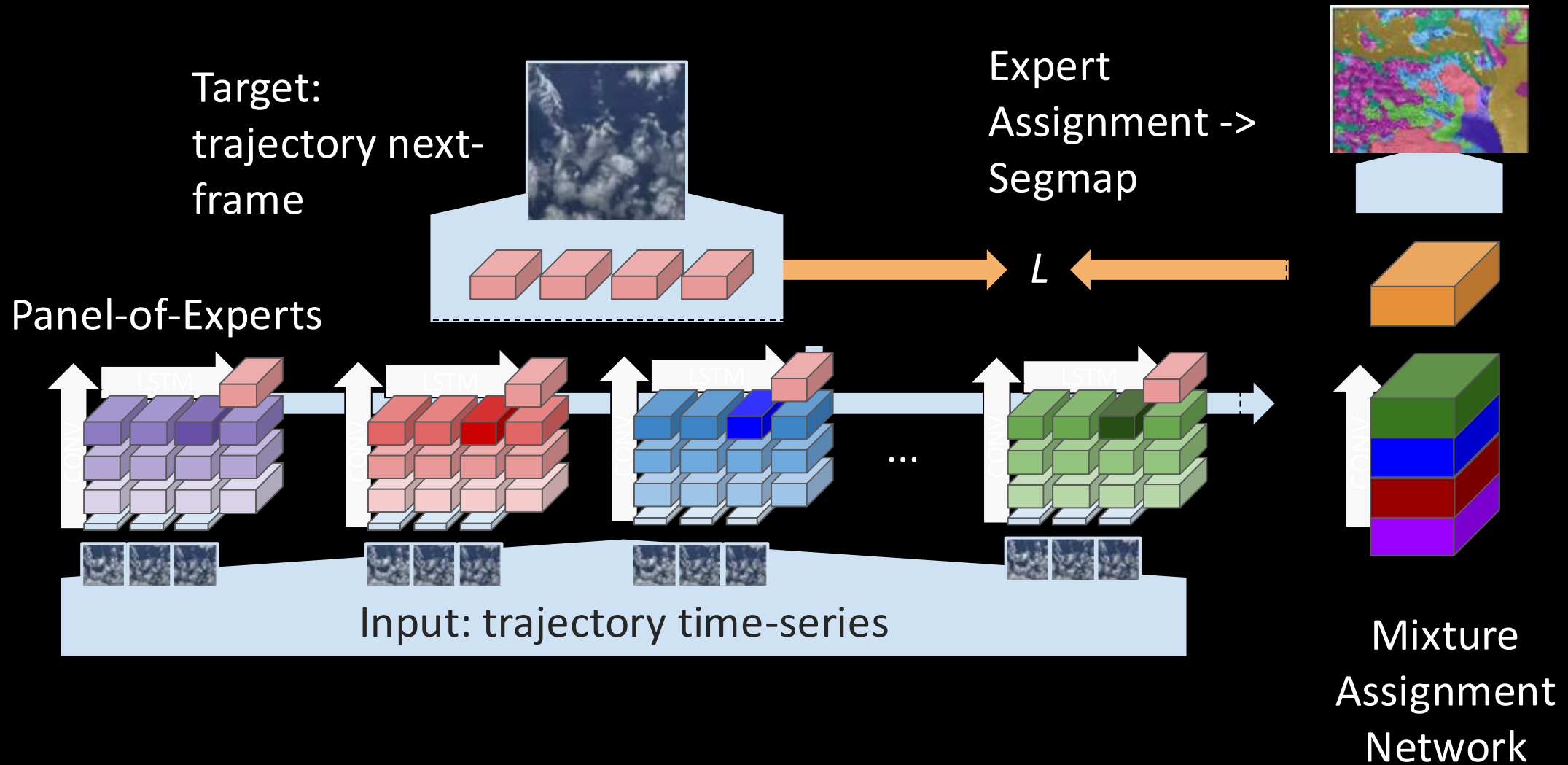
What if we increased the aerosols?

-  Broken Cumulus
-  Open cells
-  Closed cells



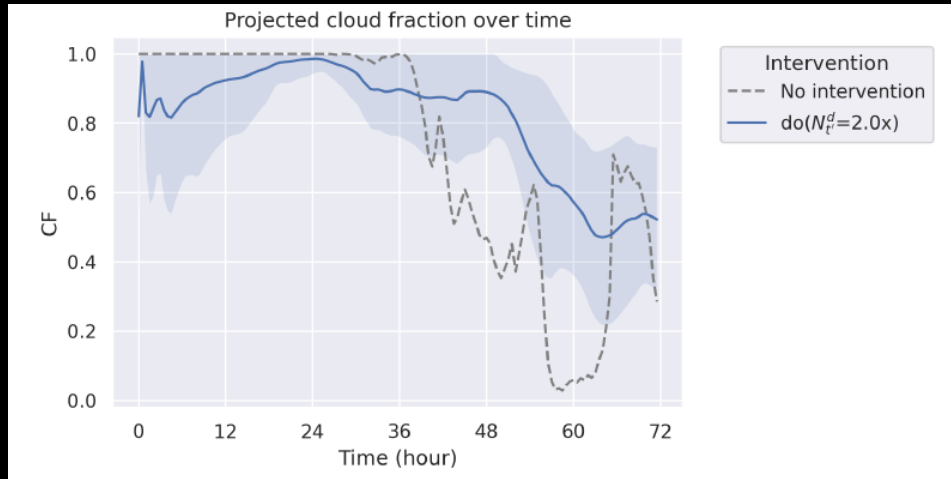
-  Broken Cumulus
-  Open cells
-  Closed cells

Self-supervised Learning of Cloud Types Mixture-of-Experts

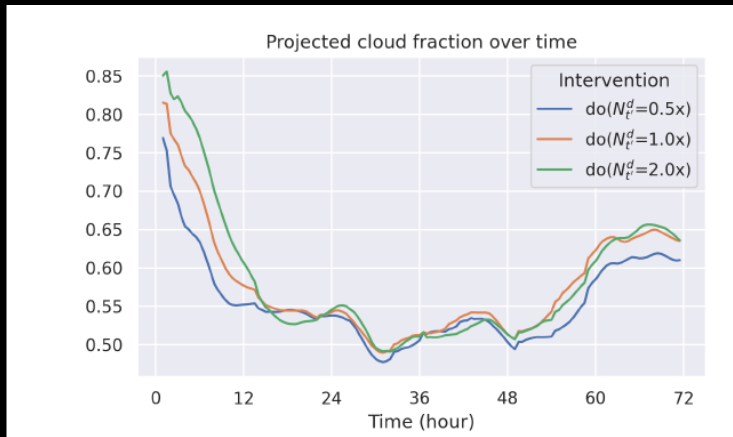
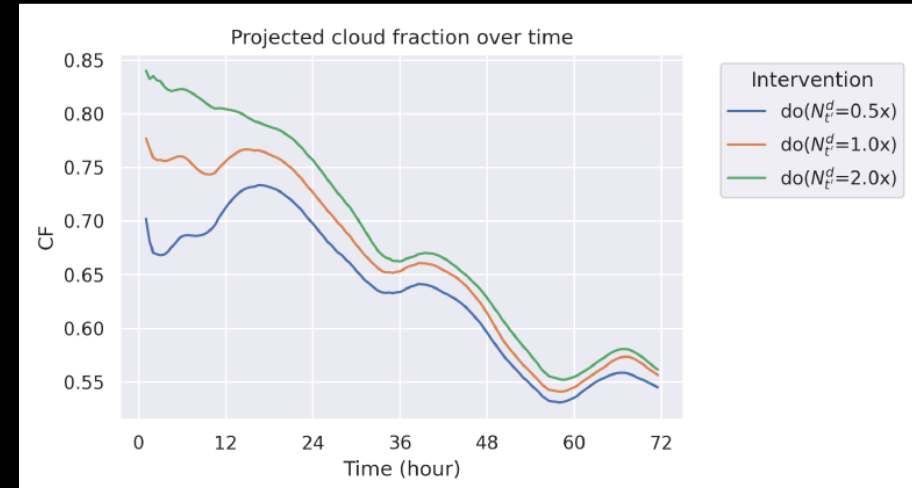


Causal Effect of Aerosol on Cloud Fraction

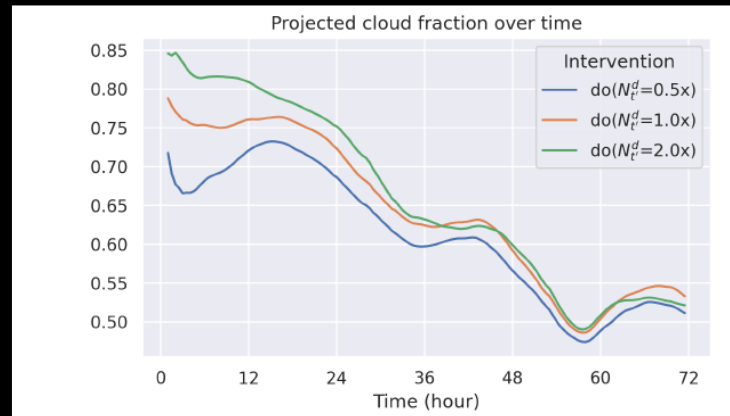
a) Example trajectory



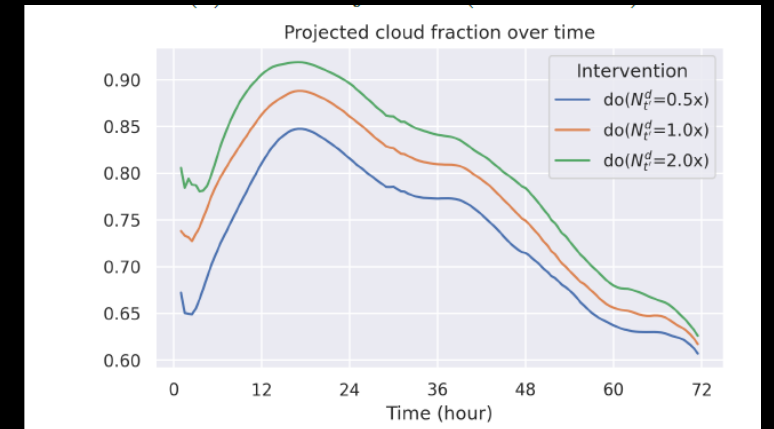
b) Mean trajectory



c) Unstable trajectories (16.5 +/- 1.5K)



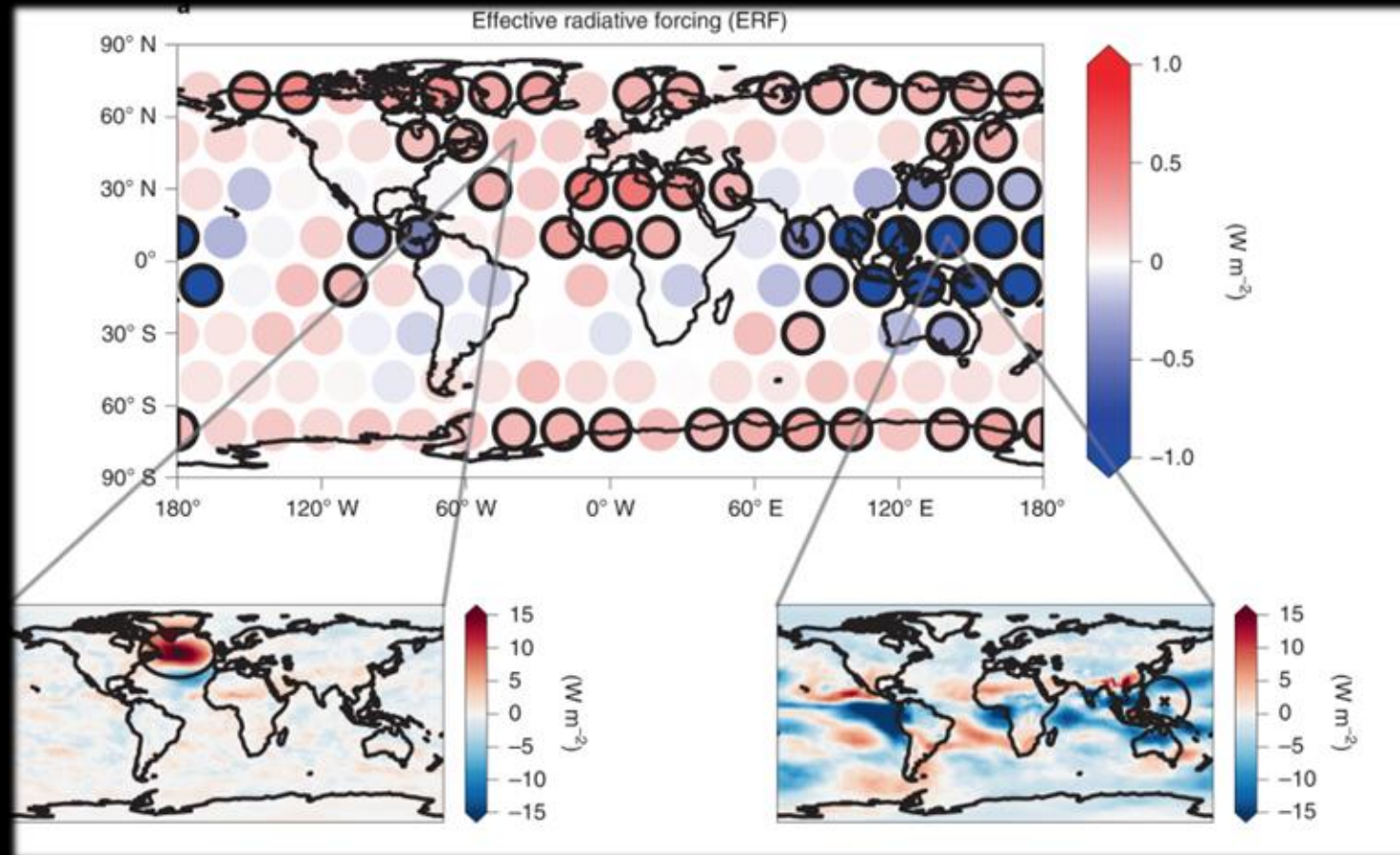
d) Stable trajectories (22.5 +/- 1.5K)



e) Very Stable trajectories (28.5 +/- 1.5K)

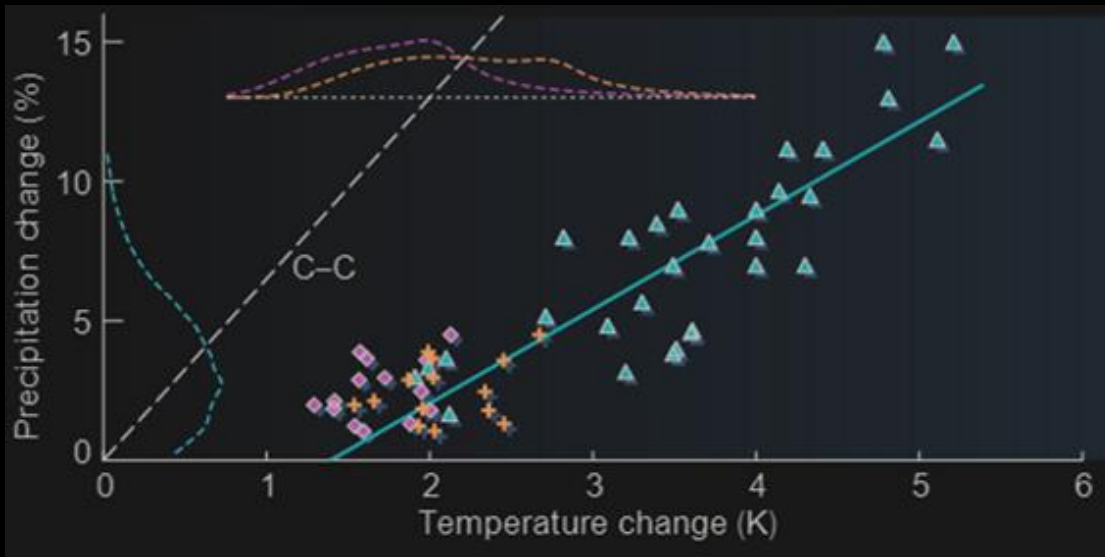
ClimateBench spares

Dependence of forcing on spatial distribution

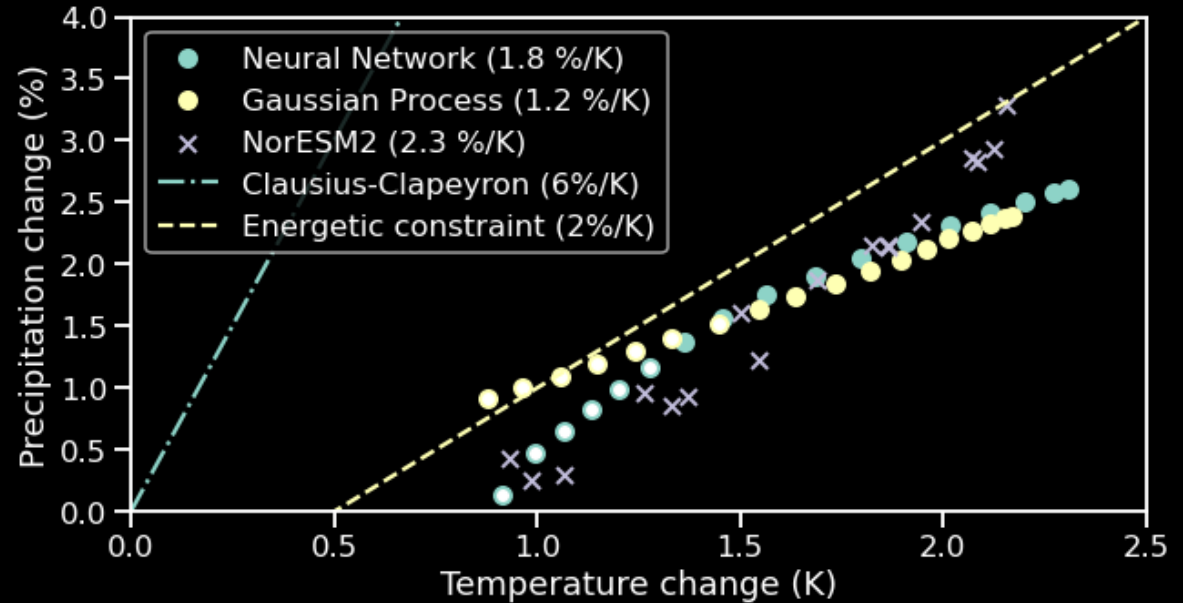


Global energy conservation

$$L\Delta P \cong \Delta R$$



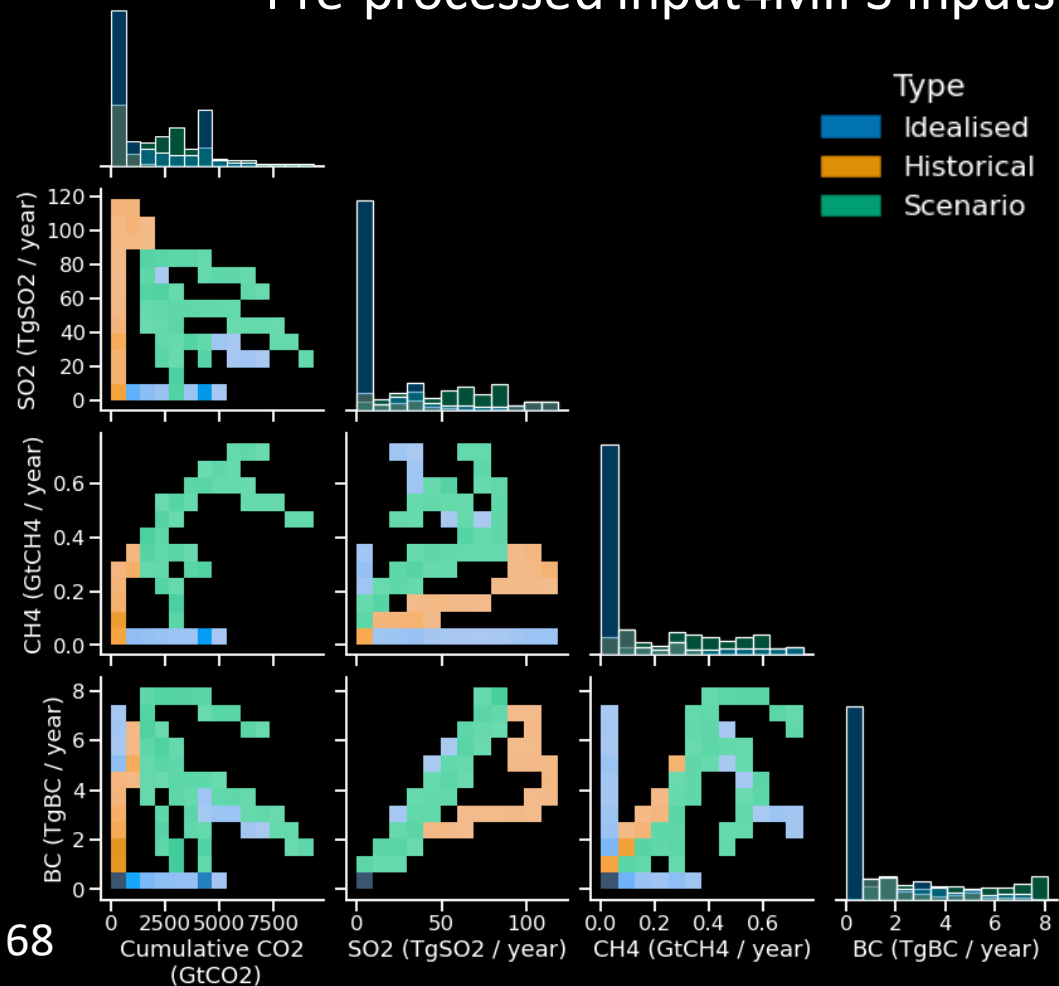
Allen & Ingram 2002



Watson-Parris et al. *JAMES* (2022)

ClimateBench training dataset

Pre-processed input4MIPS inputs and NorESM2 outputs for multiple experiments



- Selection of future socio-economic pathways designed to span range of likely future scenarios
- Two idealised simulations modelling the effect of abrupt and gradual increases in CO2
- Core historical experiment plus two detection and attribution simulations of the historical period with either aerosol or GHG held constant
- Together they do a good job of spanning the input space – although aerosol species are correlated

My Data Science Journey

Theoretical Physics
BSc (2007)



Software
Consultant
(2016)



Faculty (...)



Theoretical
Physics
PhD (2011)



PostDoc
(2021)

